

Lecture 16: Trees in Arrays & Priority Queues

Fall 2016

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This Week

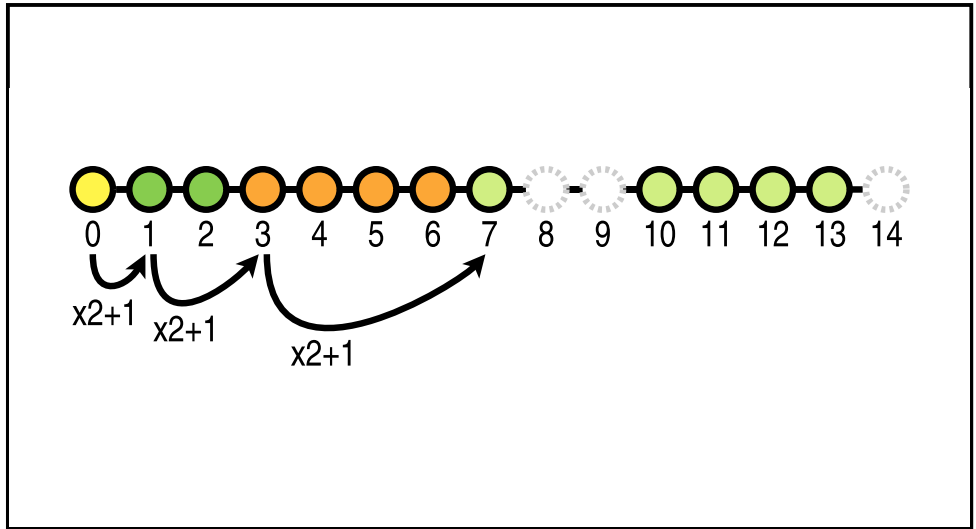
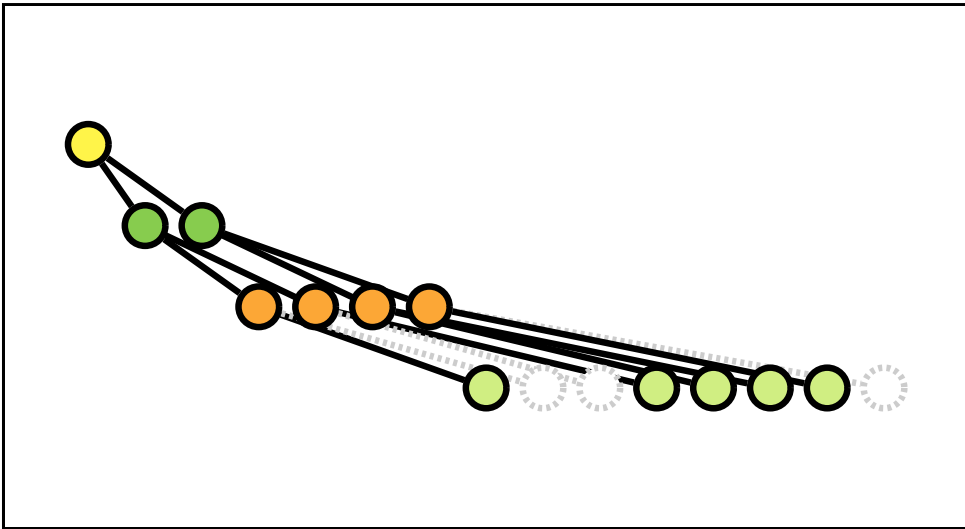
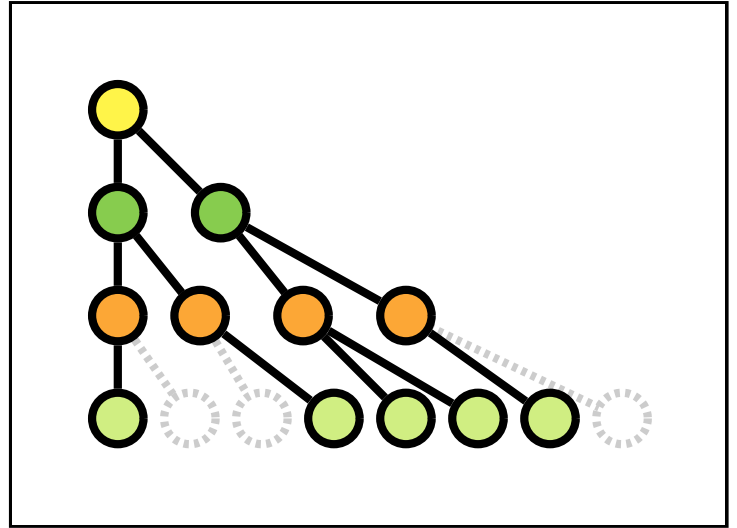
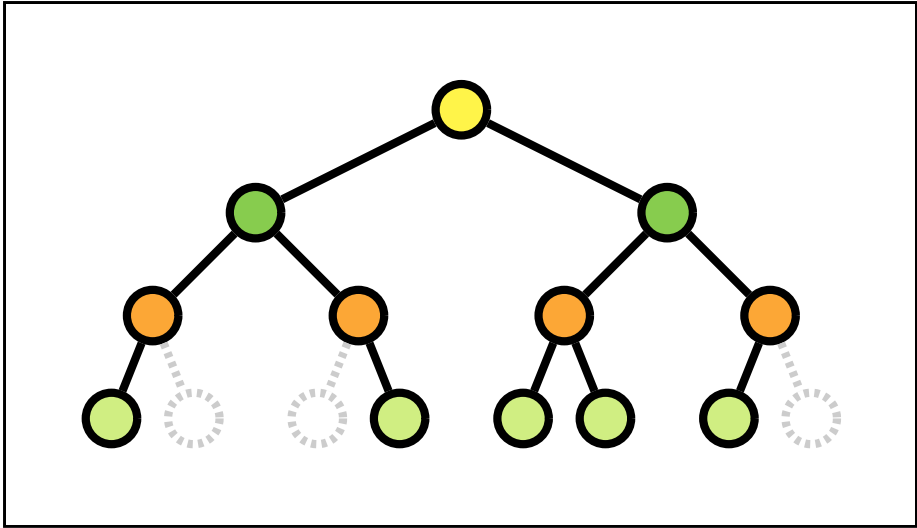
- No quiz today.
- Assignment: Calculator
 - Postfix calculator
 - Start with simplified version that requires “enter” before each operation

The Midterm

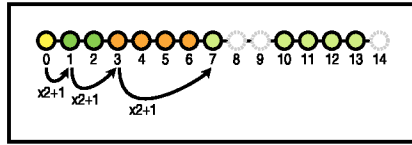
- Will be graded by next week (perhaps Wednesday)
- There’s a second midterm

How can they Fit?

- How do you fit a 2D data structure into a 1D array?
 - How did `RowOrderedPosn` do it?
 - Is there an index formula that will work for a tree?



Indices



- `data[0..n-1]` can hold data for tree of height $\log n$
 - left child of i goes at $2i+1$, right child at $2i+2$
 - parent is at $(i-1)/2$

Efficiency

- We need 2^{h-1} slots even if we only store $O(h)$ nodes
 - Bad for sticks and skinny trees
 - Good for full and well-balanced trees (topiary)
- A *complete* tree is full at every layer except the last, where empty spots are all on the right

PriorityQueue

```
public interface PriorityQueue<E extends Comparable<E>>
{
    /**
     * @pre !isEmpty()
     * @return The minimum value in the queue.
     */
    public E remove();
    public E getFirst();
    public void add(E value);
    public boolean isEmpty();
    public int size();
    public void clear();
}
```

First Pass

- Use a regular queue to hold the data
- Search for the min every time we call `remove`
 - `remove` is $O(n)$

Second Pass

- Use a regular queue to hold the data
- Every time we insert, put it in the right place
 - insert is now $O(n)$

Hmmmmm

- What subject have we talked about without a practical use-case?
- Why are we discussing two unrelated topics today?

For Next Time

Heaps