

OS and Processes

CS 105

Fall 2023

Intro to Operating Systems

- the **operating system** is a piece of software that manages a computer's resources for its users and their applications
 - Examples: OSX, Windows, Ubuntu, iOS, Android, Chrome OS



- resource allocation
- isolation
- communication
- access control



- multiprocessing
- virtual memory
- reliable networking
- virtual machines

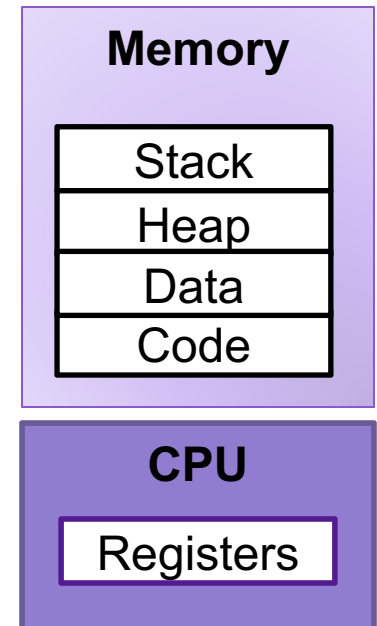


- user interface
- file I/O
- device management
- process control

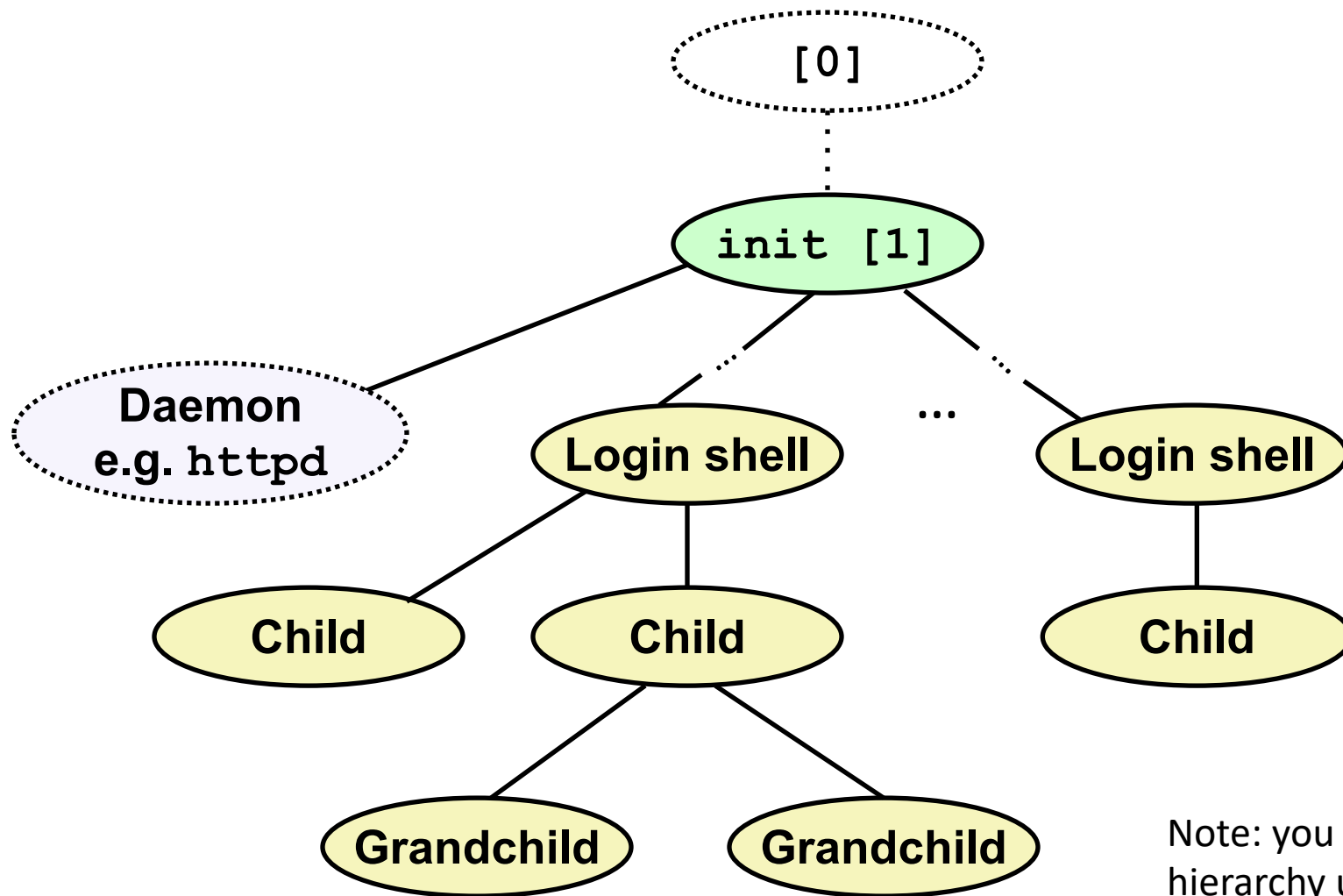
- OS is divided into two pieces: user-mode and kernel-mode
 - core OS functionality is implemented by the OS **kernel**

Processes

- A **program** is a file containing code + data that describes a computation
- A **process** is an instance of a running program.
 - One of the most profound ideas in computer science
 - Not the same as “program” or “processor”



Linux Process Hierarchy



Note: you can view the hierarchy using the Linux `ps tree` command

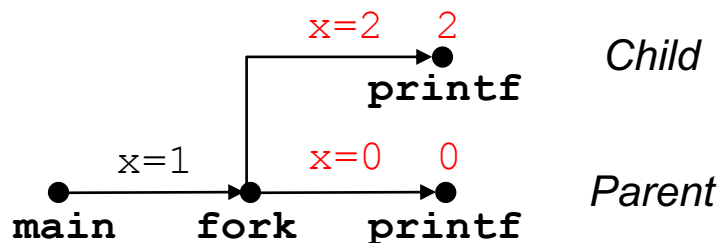
Creating Processes

- *Parent process* creates a new running *child process* by calling **fork**
- **int fork(void)**
 - Returns 0 to the child process, child's PID to parent process
 - Child is *almost* identical to parent:
 - Child get an identical (but separate) copy of the parent's virtual address space.
 - Child gets identical copies of the parent's open file descriptors
 - Child has a different PID than the parent
- **fork** is interesting (and often confusing) because it is called **once** but returns **twice**

fork Example

```
int main(){  
  
    pid_t pid;  
    int x = 1;  
  
    pid = fork();  
    if (pid == 0) { /* Child */  
        printf("child : x=%d\n", ++x);  
        return 0;  
    }  
  
    /* Parent */  
    printf("parent: x=%d\n", --x);  
    return 0;  
}
```

- Call once, return twice
- Duplicate but separate address space
 - `x` has a value of 1 when `fork` returns in parent and child
 - Subsequent changes to `x` are independent
- Shared open files
 - `stdout` is the same in both parent and child

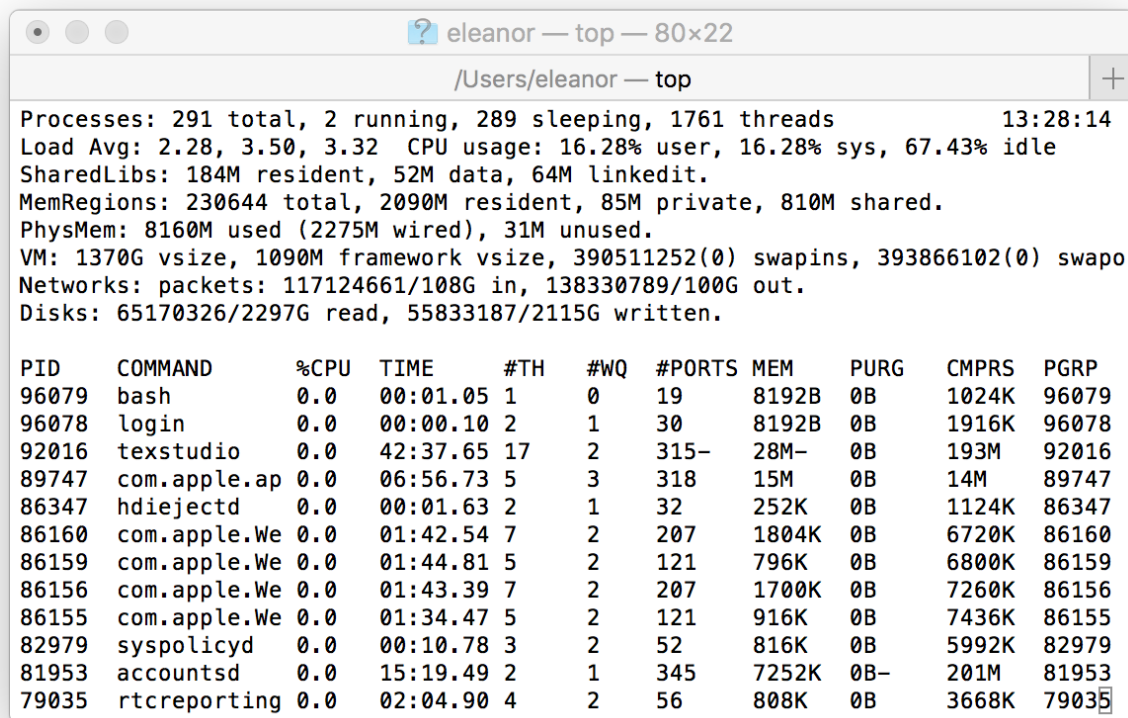


execve: Loading and Running Programs

- `int execve(char *filename, char *argv[], char *envp[])`
- Loads and runs in the current process:
 - Executable file `filename`
 - Can be object file or script file beginning with `#!interpreter` (e.g., `#!/bin/bash`)
 - ...with argument list `argv`
 - By convention `argv[0]==filename`
 - ...and environment variable list `envp`
 - “name=value” strings (e.g., `USER=droh`)
 - `getenv`, `putenv`, `printenv`
- Overwrites code, data, and stack
 - Retains PID, open files and signal context
- Called **once** and **never** returns
 - ...except if there is an error

Multiprocessing

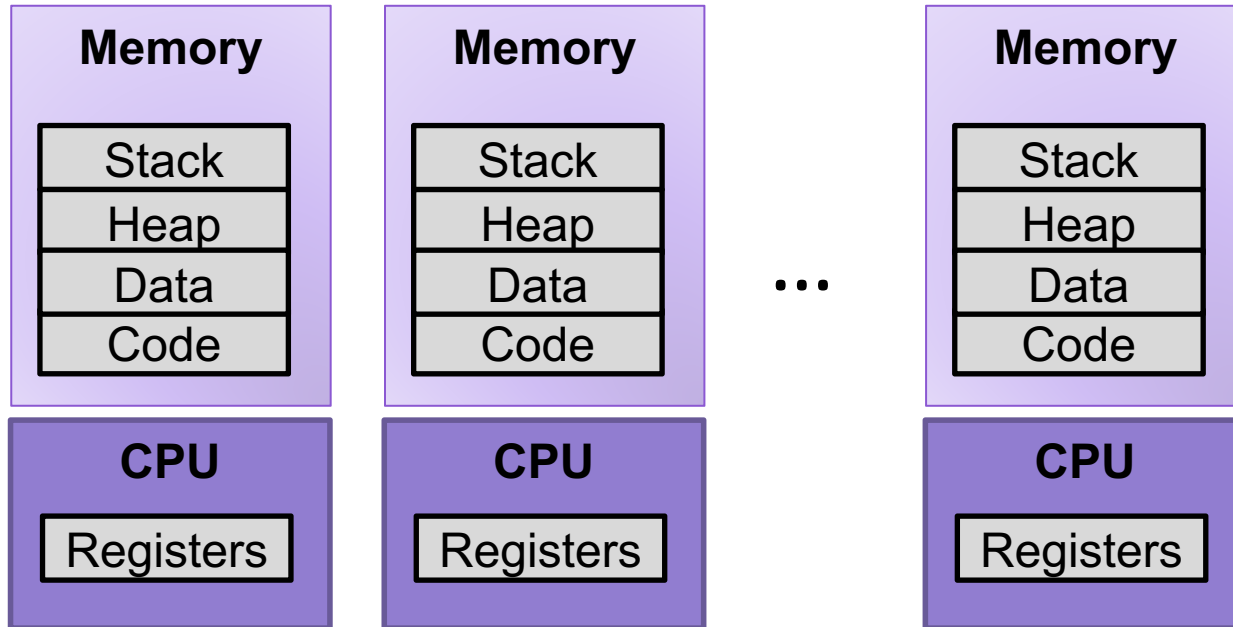
- Computer runs many processes simultaneously
- Running program “top” on Mac
 - Identified by Process ID (PID)



```
Processes: 291 total, 2 running, 289 sleeping, 1761 threads          13:28:14
Load Avg: 2.28, 3.50, 3.32  CPU usage: 16.28% user, 16.28% sys, 67.43% idle
SharedLibs: 184M resident, 52M data, 64M linkedit.
MemRegions: 230644 total, 2090M resident, 85M private, 810M shared.
PhysMem: 8160M used (2275M wired), 31M unused.
VM: 1370G vsize, 1090M framework vsize, 390511252(0) swapins, 393866102(0) swapo
Networks: packets: 117124661/108G in, 138330789/100G out.
Disks: 65170326/2297G read, 55833187/2115G written.

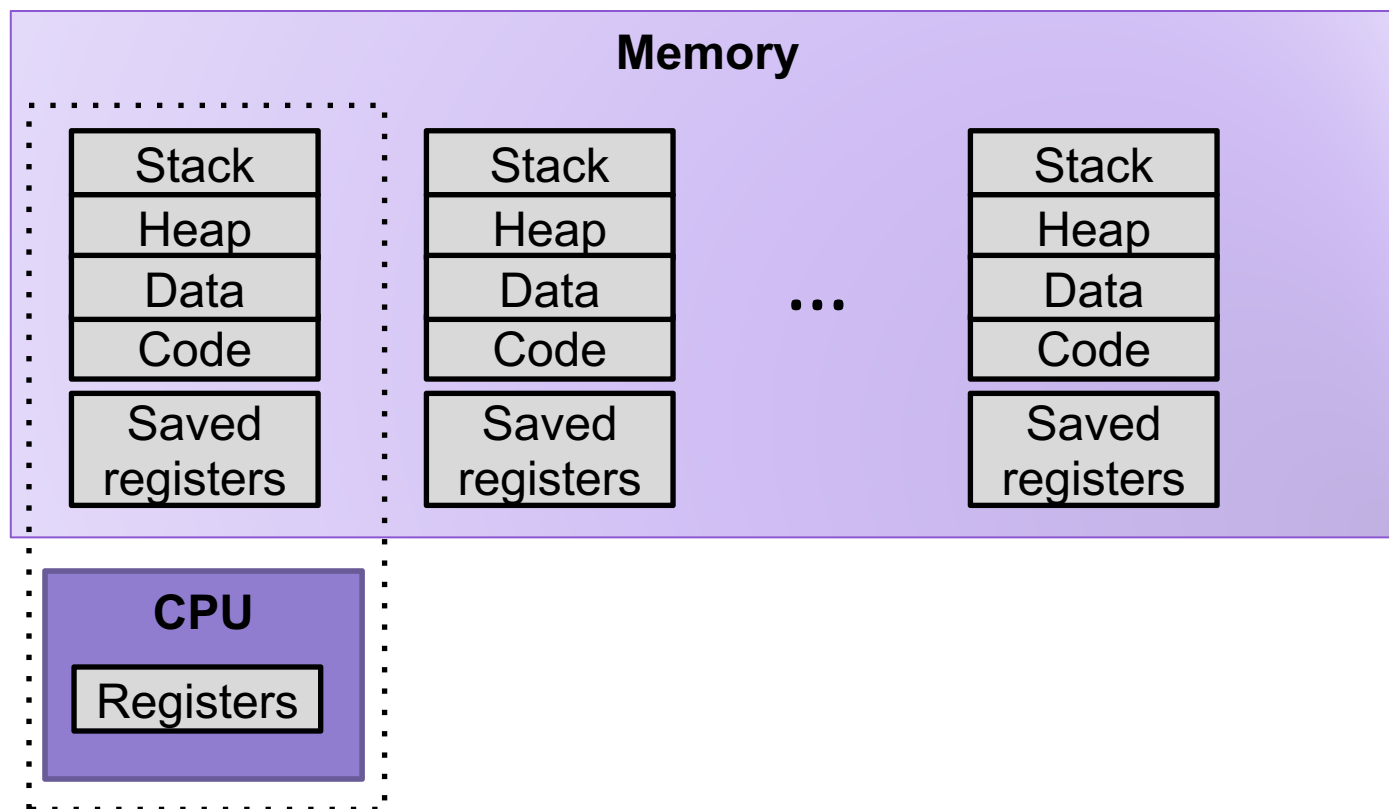
PID    COMMAND      %CPU  TIME    #TH   #WQ   #PORTS MEM    PURG   CMPRS  PGRP
96079  bash         0.0   00:01.05 1     0     19     8192B  0B     1024K 96079
96078  login        0.0   00:00.10 2     1     30     8192B  0B     1916K 96078
92016  texstudio    0.0   42:37.65 17    2     315-   28M-   0B     193M  92016
89747  com.apple.ap 0.0   06:56.73 5     3     318    15M    0B     14M   89747
86347  hdiejectd   0.0   00:01.63 2     1     32     252K   0B     1124K 86347
86160  com.apple.We 0.0   01:42.54 7     2     207    1804K  0B     6720K 86160
86159  com.apple.We 0.0   01:44.81 5     2     121    796K   0B     6800K 86159
86156  com.apple.We 0.0   01:43.39 7     2     207    1700K  0B     7260K 86156
86155  com.apple.We 0.0   01:34.47 5     2     121    916K   0B     7436K 86155
82979  syspolicyd  0.0   00:10.78 3     2     52     816K   0B     5992K 82979
81953  accountsd   0.0   15:19.49 2     1     345    7252K  0B-   201M  81953
79035  rtcreporting 0.0   02:04.90 4     2     56     808K   0B     3668K 79035
```


Multiprocessing: The Illusion



- Process provides each program with two key abstractions:
 - **Logical control flow**
 - Each program seems to have exclusive use of the CPU
 - Provided by kernel mechanism called **context switching**
 - **Private address space**
 - Each program seems to have exclusive use of main memory.
 - Provided by kernel mechanism called **virtual memory**

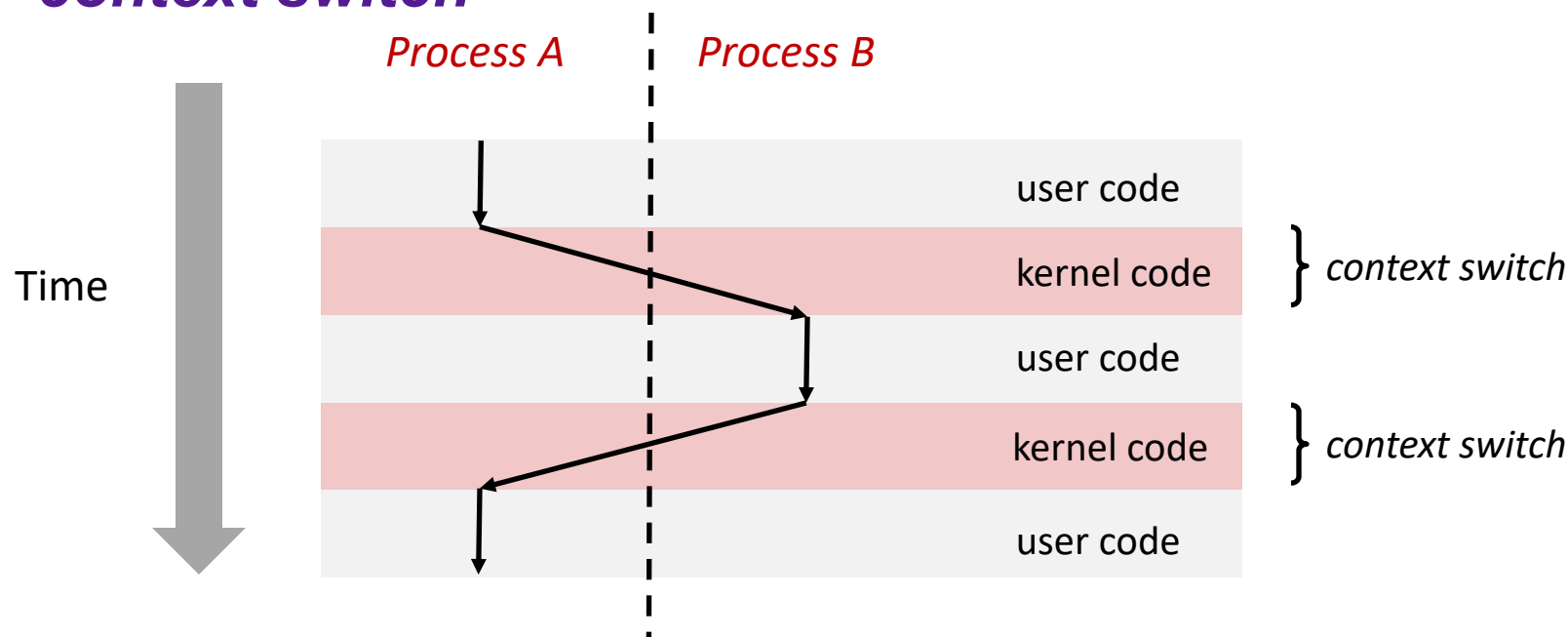
Multiprocessing: The (Traditional) Reality



- Single processor executes multiple processes concurrently
 - Process executions interleaved (multitasking)
 - Register values for nonexecuting processes saved in memory
 - Address spaces managed by virtual memory system

Context Switching

- Processes are managed by a shared chunk of memory-resident kernel code
 - Important: the kernel code is not a separate process, but rather code and data structures that the OS uses to manage all processes
- Control flow passes from one process to another via a **context switch**

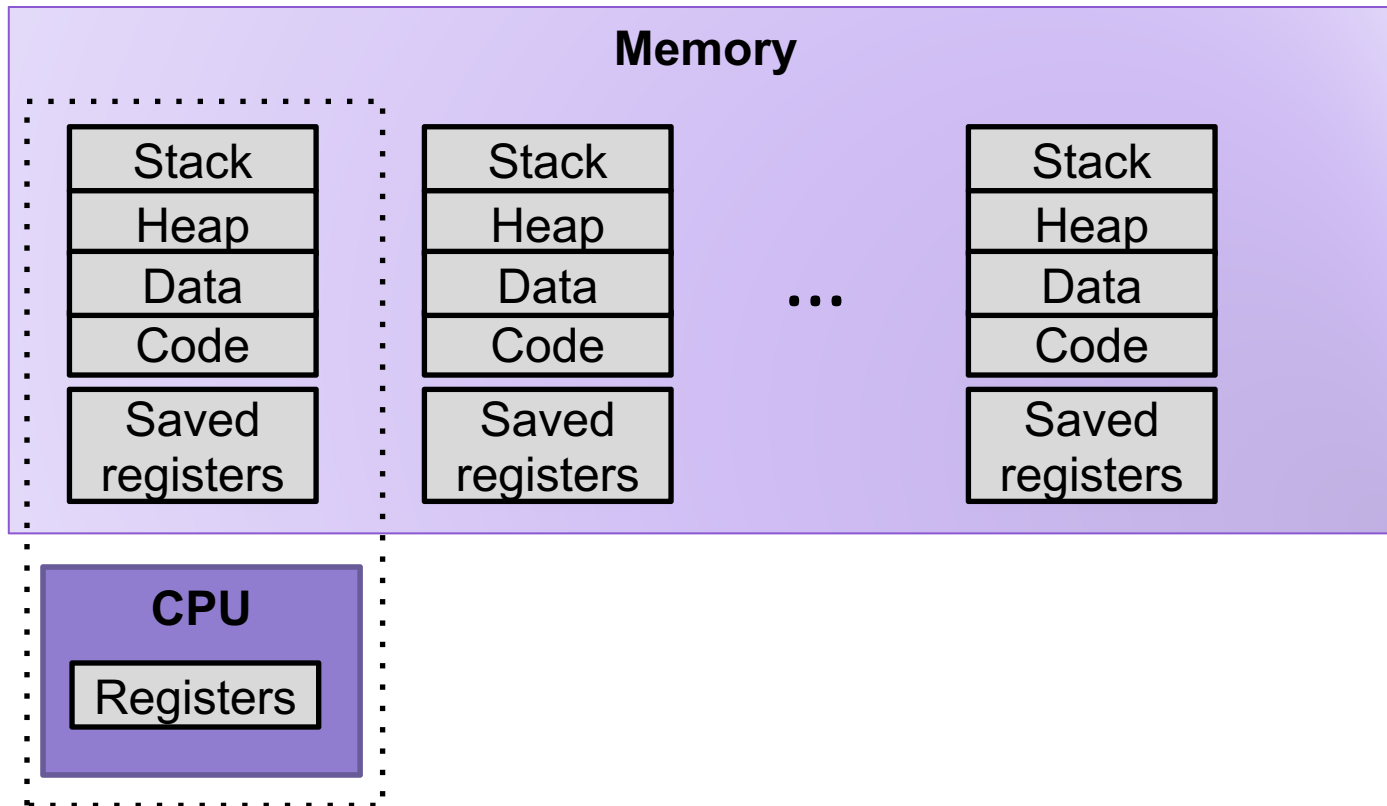


Process Control Block (PCB)

- To implement a context switch, OS maintains a PCB for each process containing:
 - process table, which contains information about the process (id, user, privilege level, arguments, status)
 - location of executable on disk
 - file table
 - register values (general-purpose registers, float registers, pc, eflags...)
 - memory state
 - scheduling information

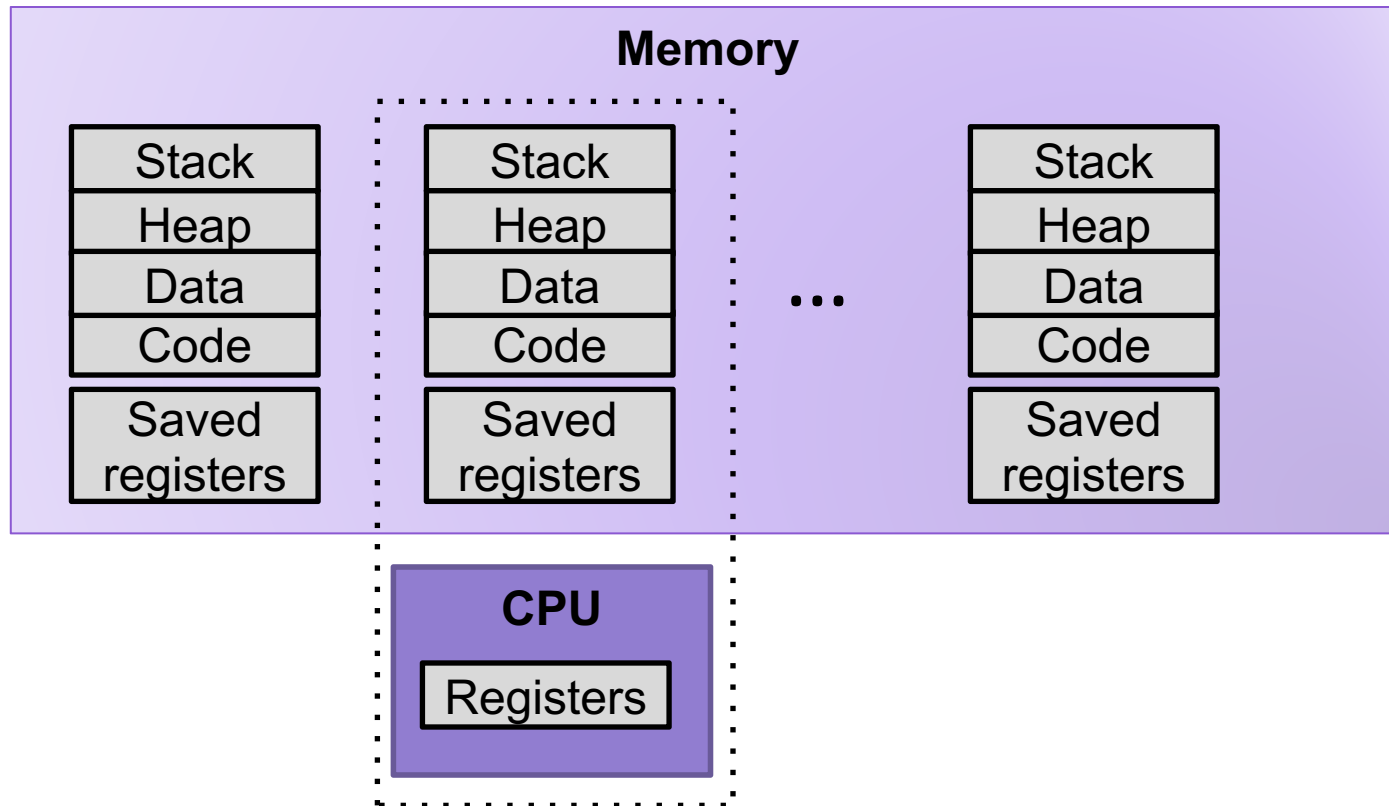
... and more!

Multiprocessing: The (Traditional) Reality



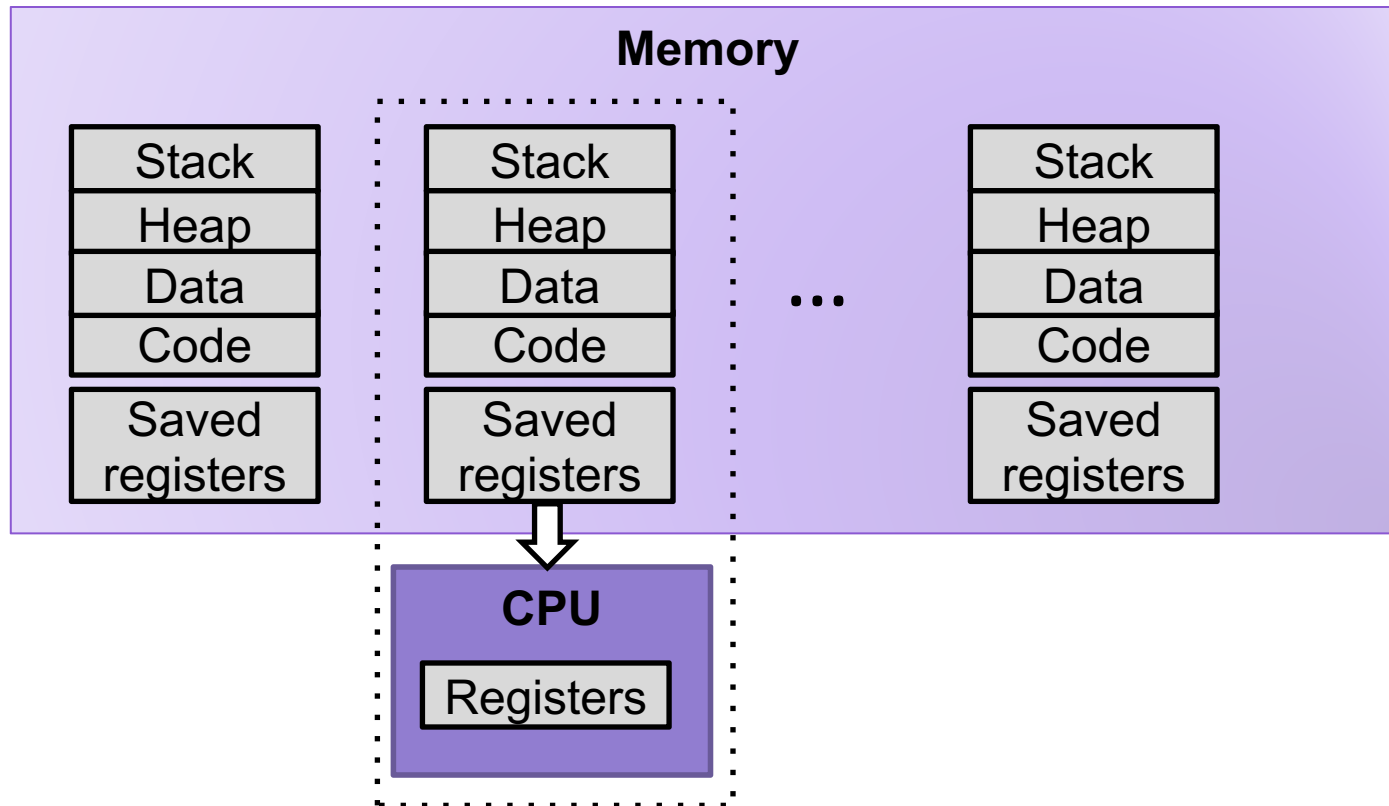
1. Save current registers to memory (in PCB)

Multiprocessing: The (Traditional) Reality



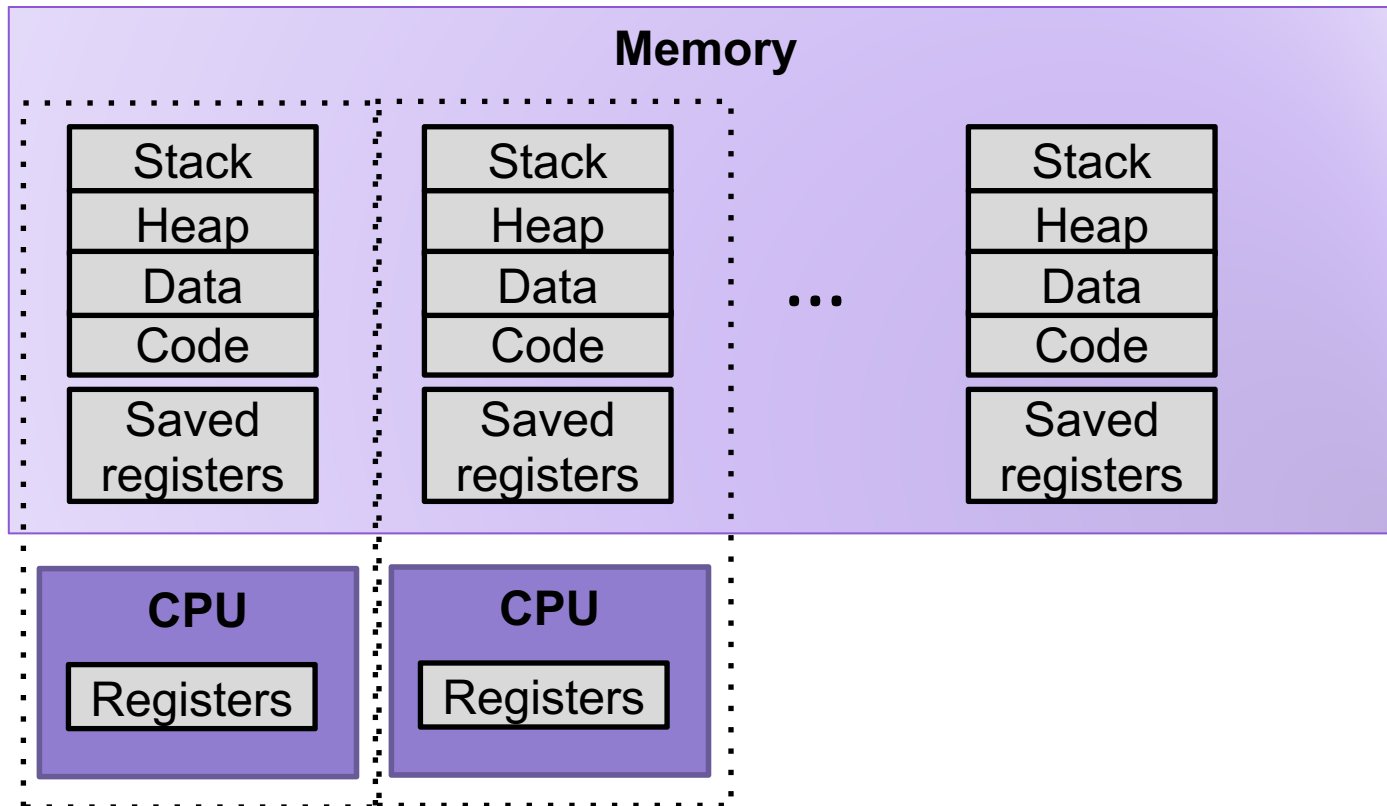
1. Save current registers to memory (in PCB)
2. Schedule next process for execution

Multiprocessing: The (Traditional) Reality



1. Save current registers to memory (in PCB)
2. Schedule next process for execution
3. Load saved registers and switch address space

Multiprocessing: The (Modern) Reality

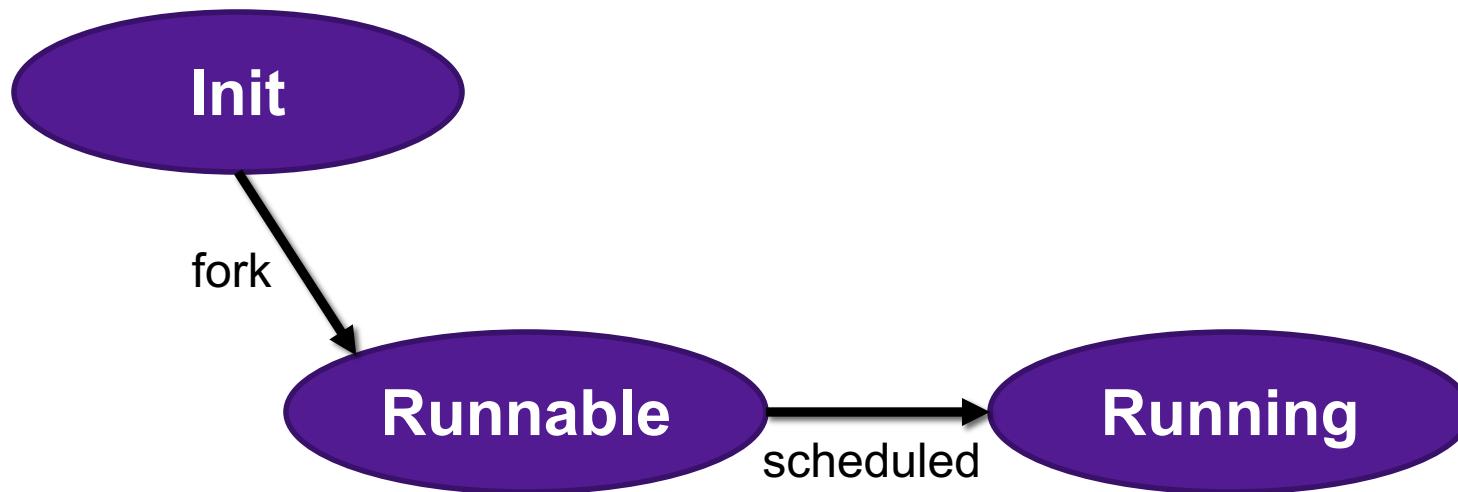


- Multicore processors
 - Multiple CPUs on single chip
 - Share main memory (and some of the caches)
 - Each can execute a separate process
 - Scheduling of processors onto cores done by kernel

Exercise: Context Switching

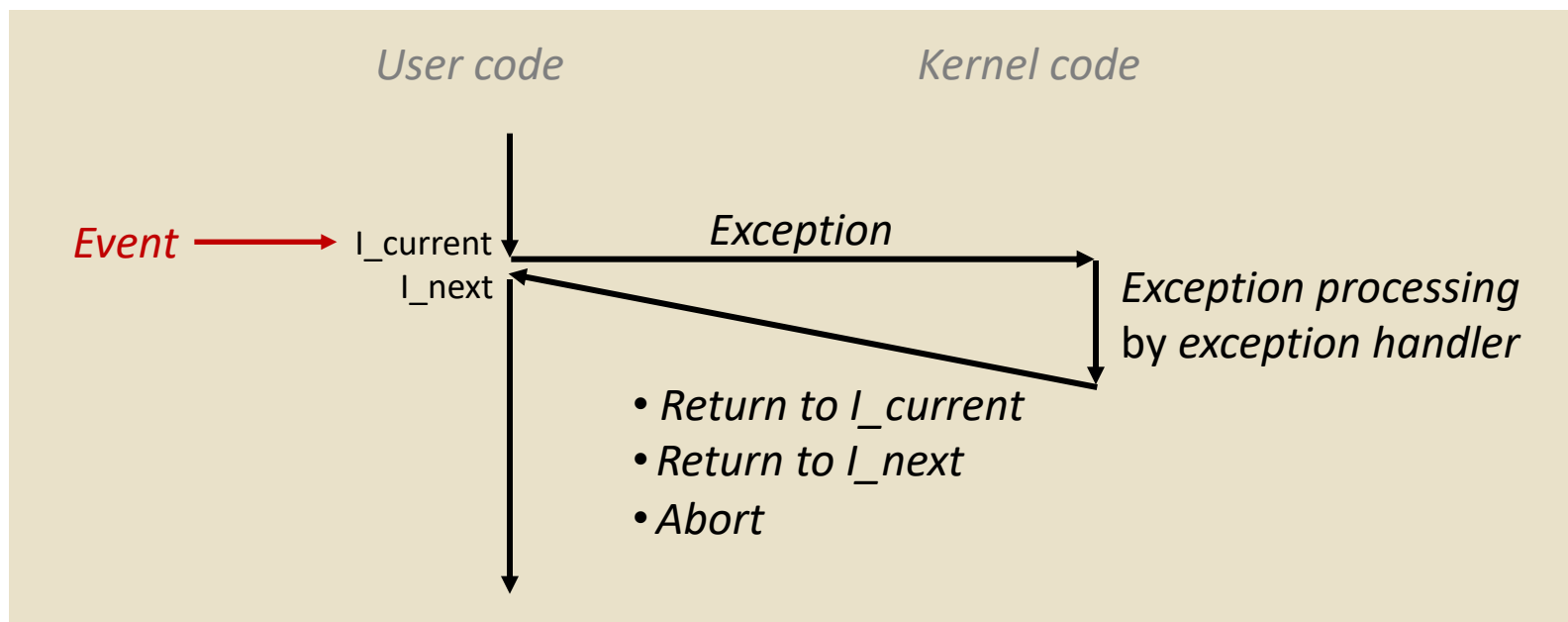
A hardware designer argues that there are now enough on-chip transistors to build a CPU with 1024 integer registers and 512 floating point registers. As a result, the compiler should almost never need to store anything on the stack. As a new operating systems expert, would you recommend building this new design.

Process Life Cycle

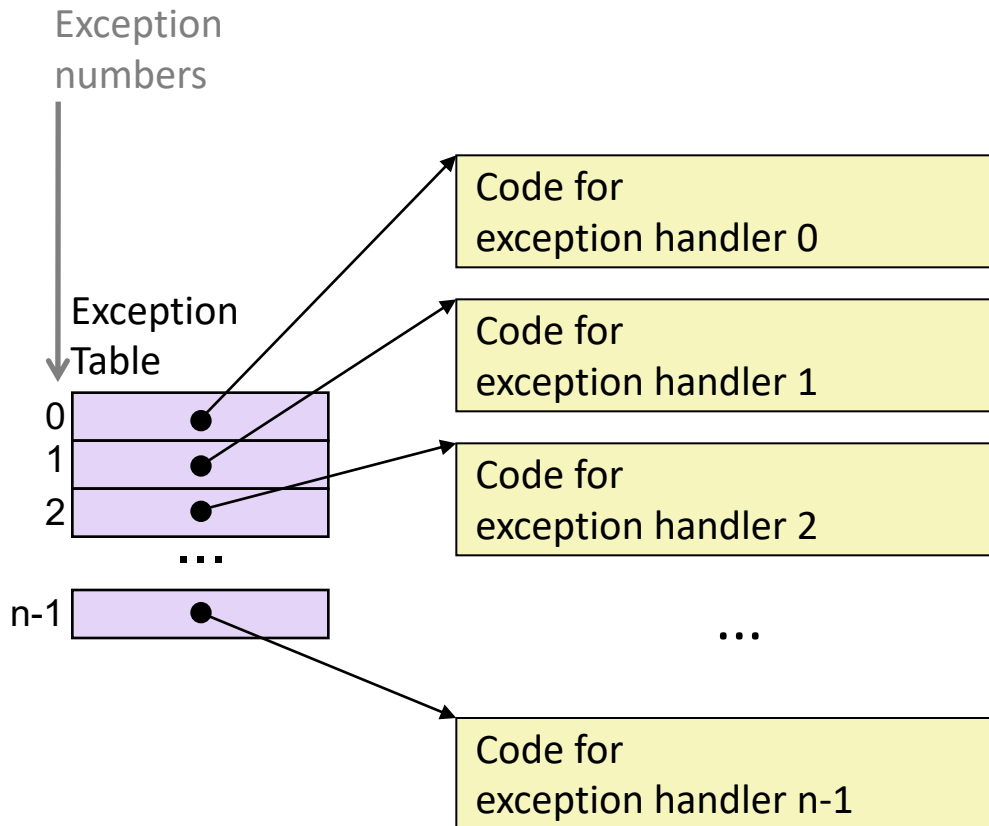


Exceptions

- An **exception** is a transfer of control to the OS *kernel* in response to some *event* (i.e., change in processor state)
 - Kernel is the memory-resident part of the OS



Exception Tables



- Each type of event has a unique exception number k
- k = index into exception table (a.k.a. interrupt vector)
- Handler k is called each time exception k occurs

Synchronous Exceptions

Caused by events that occur as a result of executing an instruction:

- **Traps**

- Intentional
- Examples: **system calls**, breakpoint traps, special instructions
- Returns control to “next” instruction

- **Faults**

- Unintentional but possibly recoverable
- Examples: page faults (recoverable), protection faults (unrecoverable), floating point exceptions
- Either re-executes faulting (“current”) instruction or aborts

- **Aborts**

- Unintentional and unrecoverable
- Examples: illegal instruction, divide-by-zero, parity error, machine check
- Aborts current program

Interrupts (Asynchronous Exceptions)

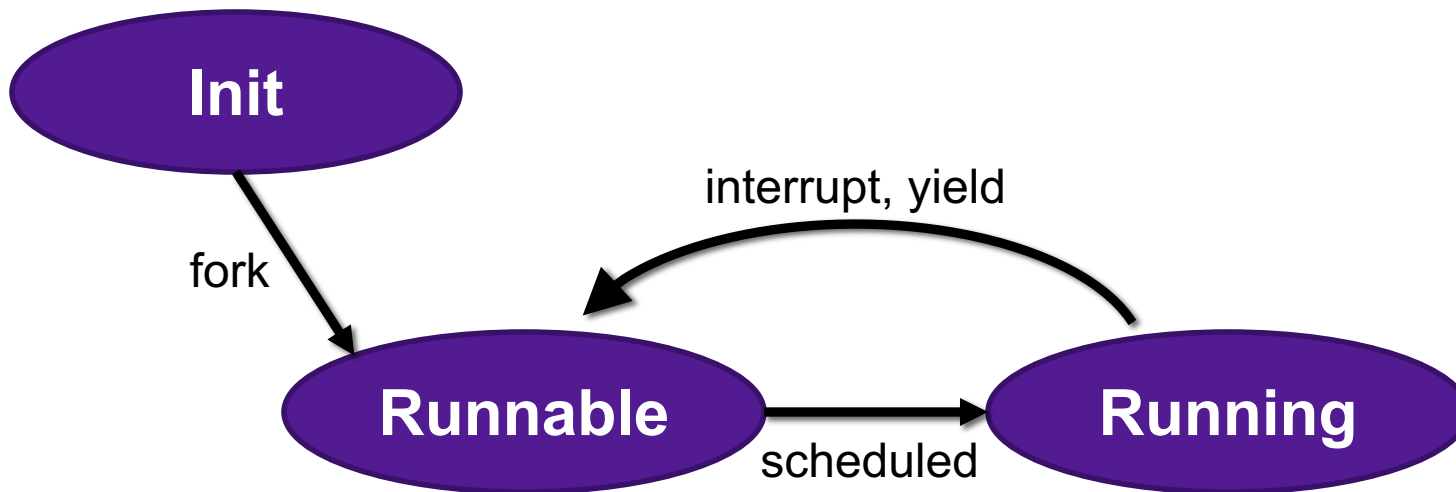
Caused by events external to the process

- Indicated by setting the processor's *interrupt pin*
- Handler returns to “next” instruction

Examples:

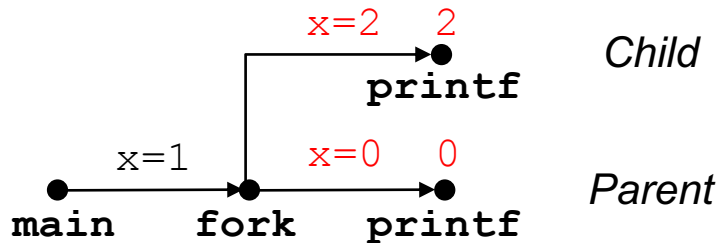
- Timer interrupt
 - Every few ms, an external timer chip triggers an interrupt
 - Used by the kernel to take back control from user programs
- I/O interrupt from external device
 - Hitting Ctrl-C at the keyboard
 - Arrival of a packet from a network
 - Arrival of data from a disk

Process Life Cycle



fork Example

```
int main(){  
  
    pid_t pid;  
    int x = 1;  
  
    pid = Fork();  
    if (pid == 0) { /* Child */  
        printf("child : x=%d\n", ++x);  
        return 0;  
    }  
  
    /* Parent */  
    printf("parent: x=%d\n", --x);  
    return 0;  
}
```



- **Call once, return twice**
- **Duplicate but separate address space**
 - x has a value of 1 when fork returns in parent and child
 - Subsequent changes to x are independent
- **Shared open files**
 - `stdout` is the same in both parent and child
- **Concurrent execution**
 - Can't predict execution order of parent and child

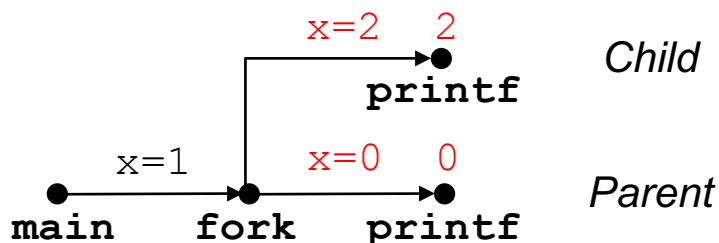
Exercise: What are all the possible outputs of this program?

Modeling `fork` with Process Graphs

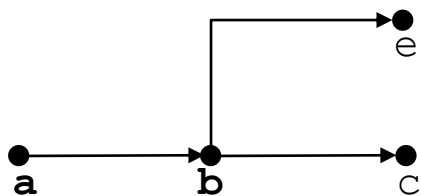
- A **process graph** is a useful tool for capturing the partial ordering of statements in a concurrent program:
 - Each vertex is the execution of a statement
 - $a \rightarrow b$ means a happens before b
 - Edges can be labeled with current value of variables
 - `printf` vertices can be labeled with output
 - Each graph begins with a vertex with no inedges
- Any topological sort of the graph corresponds to a feasible total ordering.
 - Total ordering of vertices where all edges point from left to right

Interpreting Process Graphs

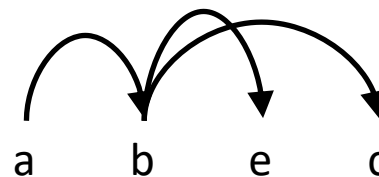
- Original graph:



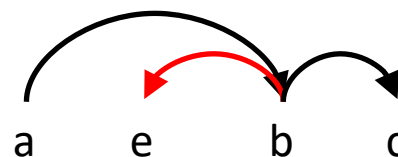
- Relabeled graph:



Feasible total ordering:



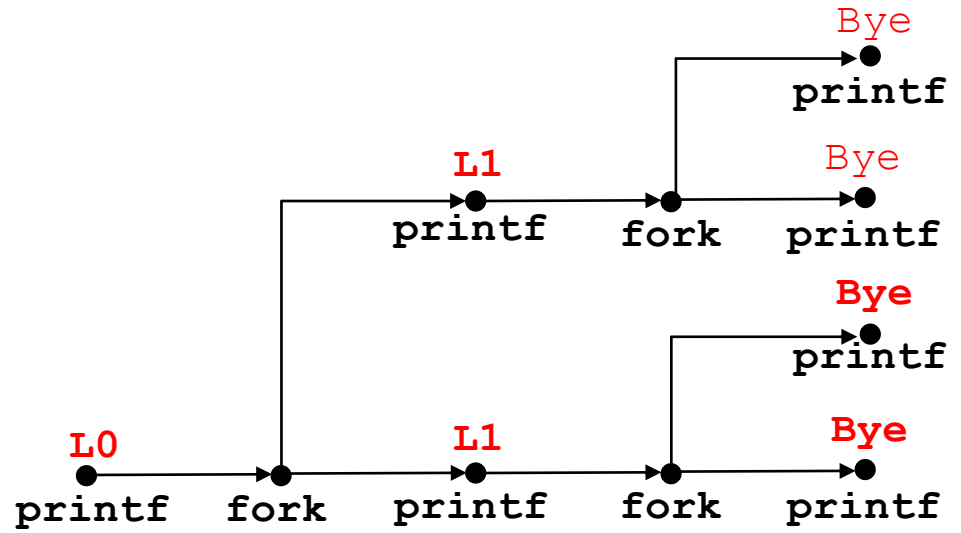
Infeasible total ordering:



fork Example: Two consecutive forks

```

void fork1()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
    
```



Which of these outputs are feasible?

- | | |
|-----|-----|
| L0 | L0 |
| L1 | Bye |
| Bye | L1 |
| Bye | Bye |
| L1 | L1 |
| Bye | Bye |
| Bye | Bye |

Exercise: Forks and Feasible Schedules

- For each of the following programs, draw the process graph and then determine which of the possible outputs are feasible

```
void fork2(){
    printf("L0\n");
    if (fork() != 0) {
        printf("L1\n");
        if (fork() != 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
```

L0

L1

Bye

Bye

L2

Bye

L0

Bye

L1

Bye

Bye

L2

```
void fork3(){
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork() == 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
```

L0

Bye

L1

L2

Bye

Bye

L0

Bye

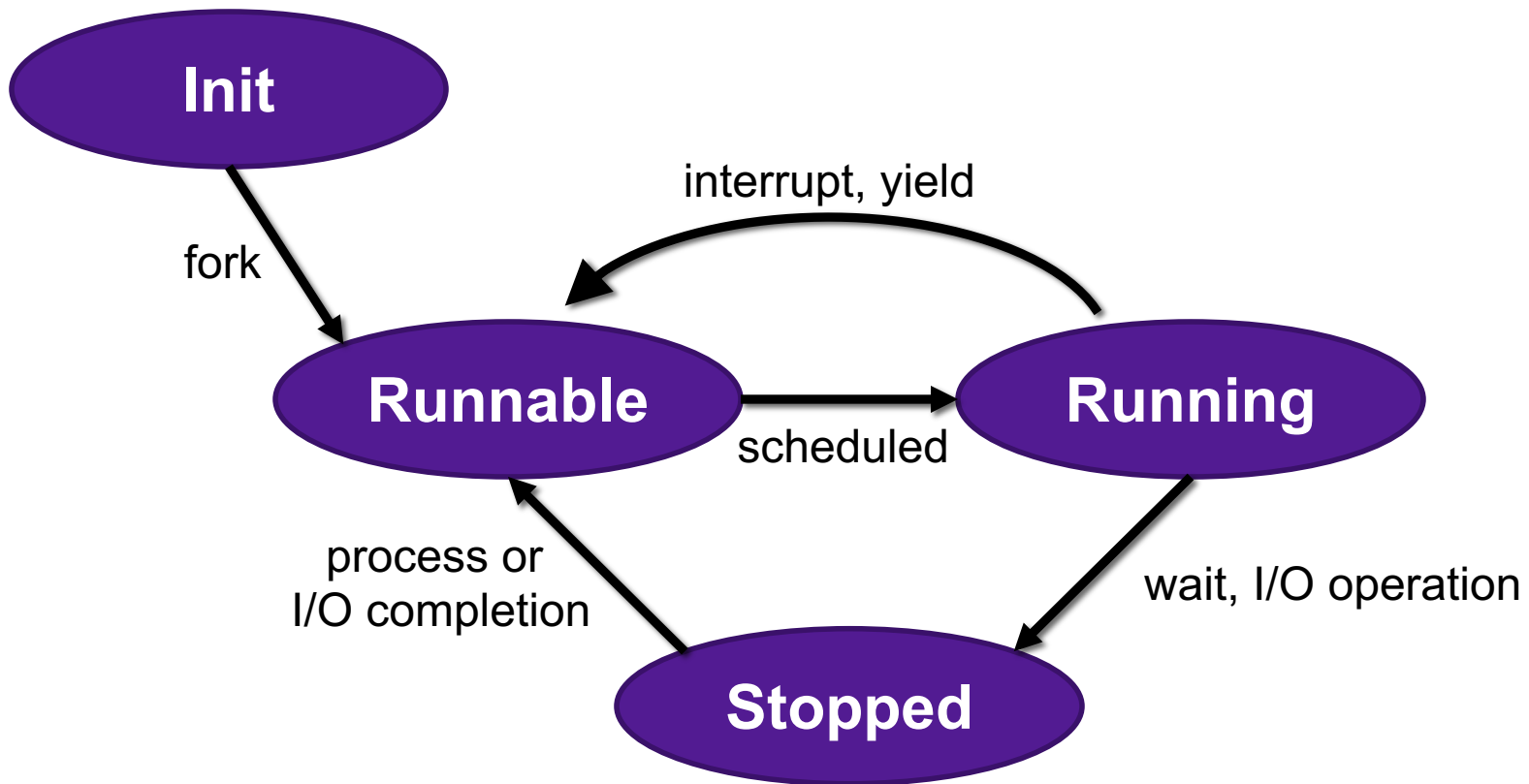
L1

Bye

Bye

L2

Process Life Cycle

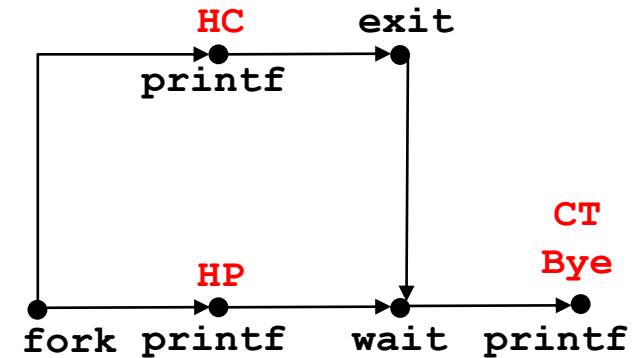


Reaping Children

- Reaping
 - Performed by parent on terminated child (using `wait` or `waitpid`)
 - Parent is given exit status information
 - Kernel then deletes zombie child process
- **`int wait(int *child_status)`**
 - Suspends current process until one of its children terminates
 - Return value is the `pid` of the child process that terminated
 - If `child_status != NULL`, then the integer it points to will be set to a value that indicates reason the child terminated and the exit status:
 - Checked using macros defined in `wait.h`
 - `WIFEXITED`, `WEXITSTATUS`, `WIFSIGNALED`, `WTERMSIG`, `WIFSTOPPED`, `WSTOPSIG`, `WIFCONTINUED`
 - See textbook for details

wait Example

```
void fork6() {  
    int child_status;  
  
    if (fork() == 0) {  
        printf("HC: hello from child\n");  
        exit(0);  
    } else {  
        printf("HP: hello from parent\n");  
        wait(&child_status);  
        printf("CT: child has terminated\n");  
    }  
    printf("Bye\n");  
}
```



Feasible output:

HC
HP
CT
Bye

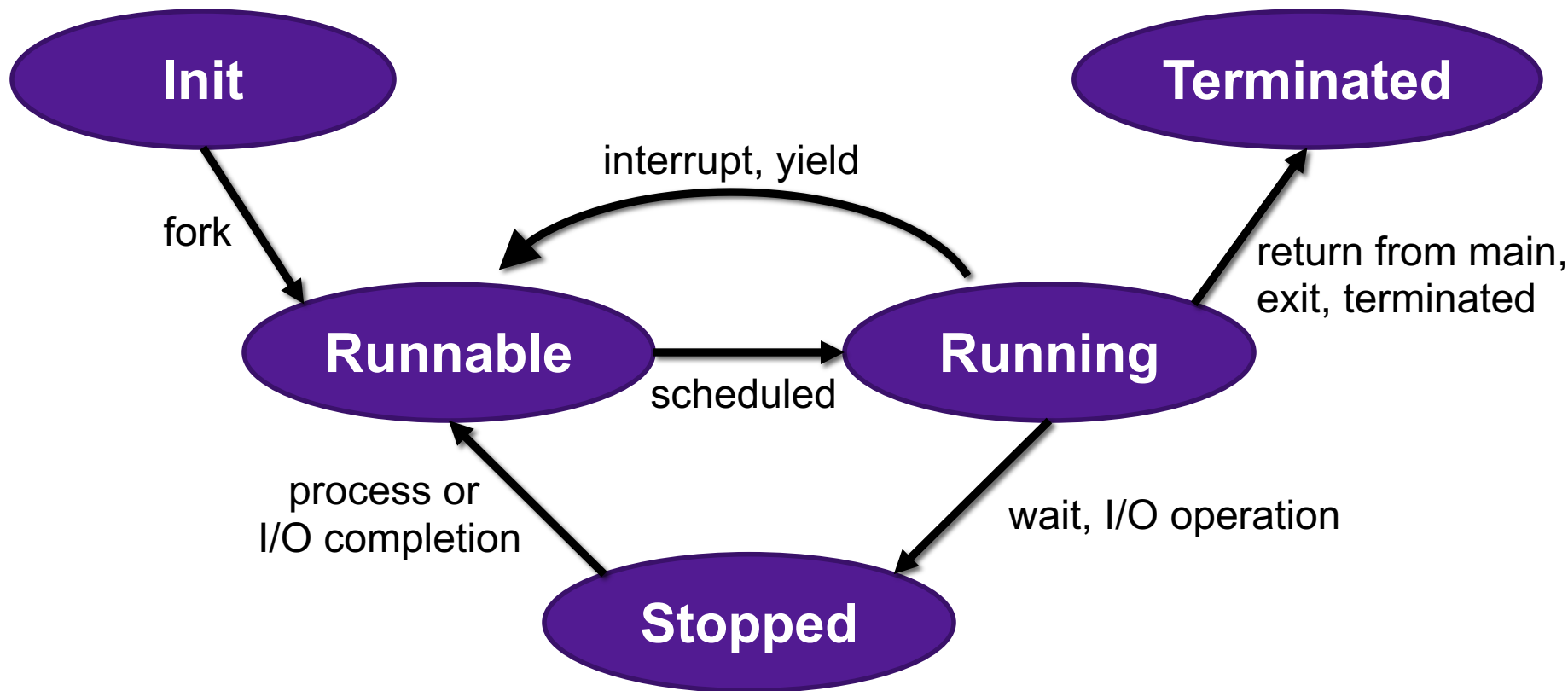
Infeasible output:

HP
CT
Bye
HC

Reaping Children

- What if parent doesn't reap?
 - If any parent terminates without reaping a child, then the orphaned child will be reaped by `init` process (`pid == 1`)
 - So, only need explicit reaping in long-running processes
 - e.g., shells and servers

Process Life Cycle



Terminating Processes

- Process becomes terminated for one of three reasons:
 - Returning from the `main` routine
 - Calling the `exit` function
 - Receiving a signal whose default action is to terminate
- `void exit(int status)`
 - Terminates with an **exit status** of `status`
 - Convention: normal return status is 0, nonzero on error
 - Another way to explicitly set the exit status is to return an integer value from the main routine
- `exit` is called **once** but **never** returns.