## **CS062**

## DATA STRUCTURES AND ADVANCED PROGRAMMING 16: Binary Trees, Binary Search, Heaps, and Priority Queues



Alexandra Papoutsaki she/her/hers

Lecture 16: Binary Trees, Binary Search, Heaps, and Priority Queues

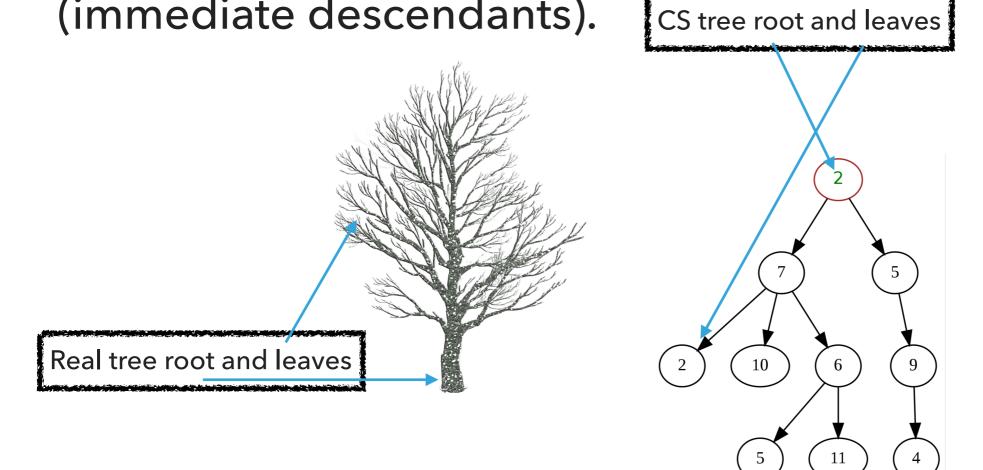
- Binary Trees
- Tree traversals
- Binary Search
- Binary Heaps
- Priority Queues

#### Trees in Computer Science

- Abstract data types that store elements hierarchically rather than linearly.
- Examples of hierarchical structures:
  - Organization charts for
    - Companies (CEO at the top followed by CFO, CMO, COO, CTO, etc).
    - Universities (Board of Trustees at the top, followed by President, then by VPs, etc).
  - Sitemaps (home page links to About, Products, etc. They link to other pages).
  - Computer file systems (user at top followed by Documents, Downloads, Music, etc. Each folder can hold more folders.).

#### Trees in Computer Science

 Hierarchical: Each element in a tree has a single parent (immediate ancestor) and zero or more children (immediate descendants).



#### Definition of a tree

- A tree T is a set of nodes that store elements based on a parent-child relationship:
  - ▶ If *T* is non-empty, it has a node called the root of *T*, that has no parent.
    - Here, the root is A.
  - Each node v, other than the root, has a unique parent node u. Every node with parent u is a child of u.
    - Here, E's parent is C and F has two children, H and I.

#### Tree Terminology

- ▶ Edge: a pair of nodes s.t. one is the parent of the other, e.g., (K,C).
- Parent node is directly above child node, e.g., K is parent of C and N.
- Sibling nodes have same parent, e.g., A and F.
- K is ancestor of B.
- B is descendant of K.
- Node plus all descendants gives subtree.
- Nodes without descendants are called leaves or external. The rest are called internal.
- A set of trees is called a forest.

## More Terminology

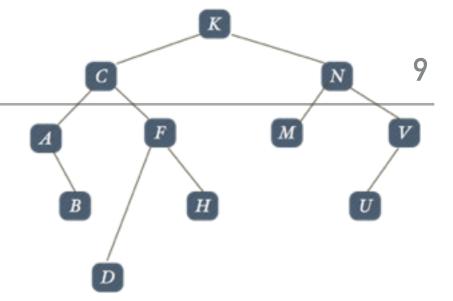
- Simple path: a series of distinct nodes s.t. there are edges between successive nodes, e.g., K-N-V-U.
- ▶ Path length: number of edges in path, e.g., path K-C-A has length 2.
- ▶ Height of node: length of longest path from the node to a leaf, e.g., N's height is 2 (for path N-V-U).
- ▶ Height of tree: length of longest path from the root to a leaf. Here 3.
- Degree of node: number of its children, e.g., F's degree is 2.
- Degree of tree (arity): max degree of any of its nodes. Here is 2.
- ▶ Binary tree: a tree with arity of 2, that is any node will have 0-2 children.

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#### **Even More Terminology**

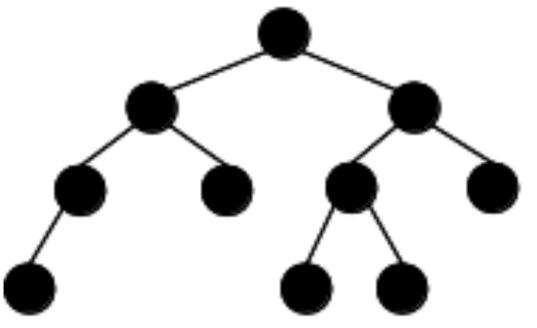
- Level/depth of node defined recursively:
  - Root is at level 0.
  - Level of any other node is equal to level of parent + 1.
  - It is also known as the length of path from root or number of ancestors excluding itself.
- Height of node defined recursively:
  - If leaf, height is 0.
  - Else, height is max height of child + 1.

#### But wait there's more!

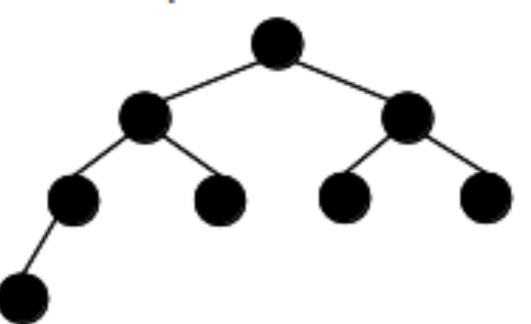


- Full (or proper): a binary tree whose every node has 0 or 2 children.
- Complete: a binary tree with minimal height. Any holes in tree would appear at last level to right, i.e., all nodes of last level are as left as possible.

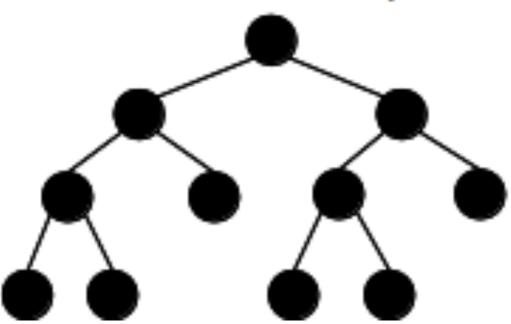
#### Neither complete nor full



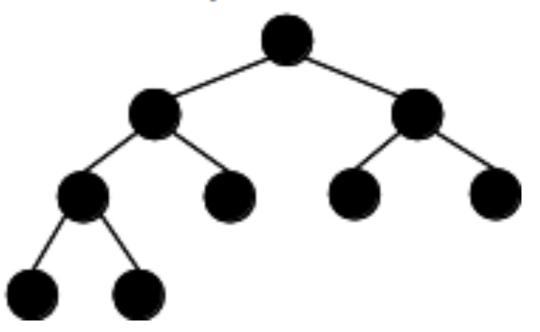
#### Complete but not full



Full but not complete



Complete and full

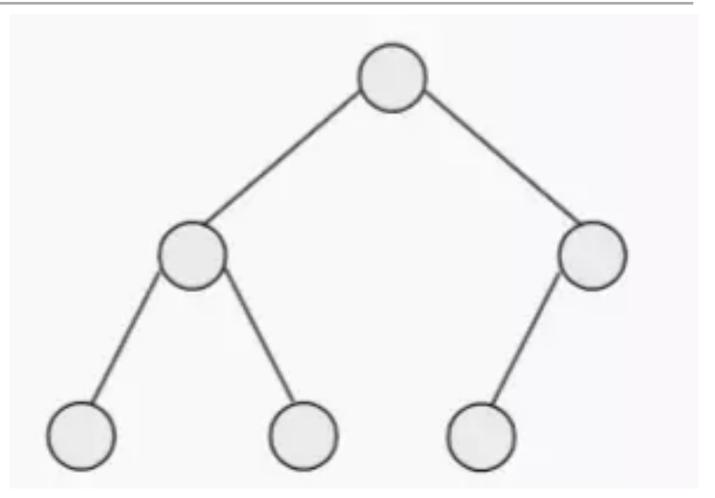


http://code.cloudkaksha.org/binary-tree/types-binary-tree

#### Practice Time: This tree is

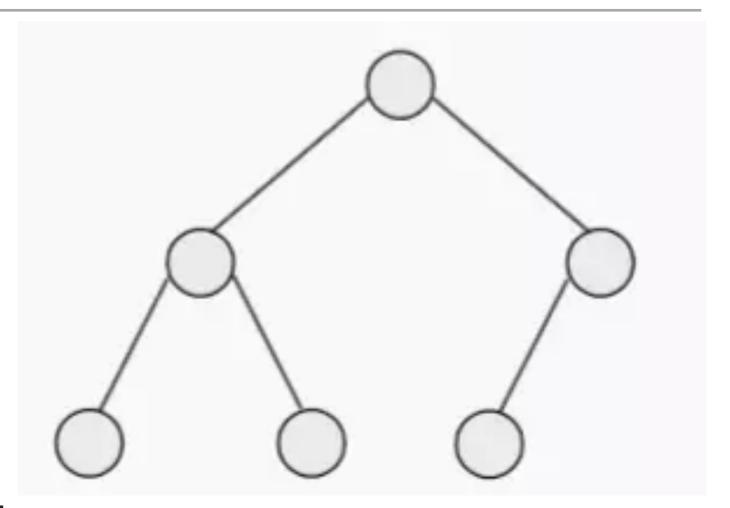
- A: Full
- B: Complete
- C: Full and Complete





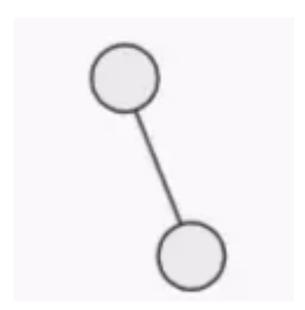
#### Answer

- A: Full
- **B: Complete**
- C: Full and Complete
- D: Neither Full nor Complete



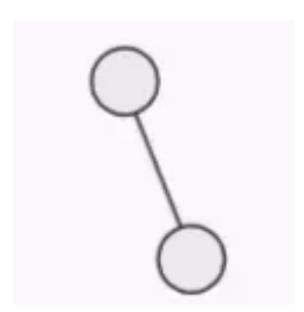
#### Practice Time: This tree is

- A: Full
- B: Complete
- C: Full and Complete
- D: Neither Full nor Complete



#### Answer

- A: Full
- B: Complete
- C: Full and Complete
- D: Neither Full nor Complete



# R N 15

#### Counting in binary trees

- ▶ Lemma: if T is a binary tree, then at level k, T has  $\leq 2^k$  nodes.
  - E.g., at level 2, at most 4 nodes (A, F, M, V)
- Theorem: If T has height h, then # of nodes n in T satisfy:  $h+1 \le n \le 2^{h+1}-1$ .
- ▶ Equivalently, if T has n nodes, then  $log(n+1) 1 \le h \le n-1$ .
  - ▶ Worst case: When h = n 1 or O(n), the tree looks like a left or right-leaning "stick".
  - ▶ Best case: When a tree is as compact as possible (e.g., complete) it has  $O(\log n)$  height.

#### Practice Time - Problem 1 Worksheet #16

Follow the instructions in the worksheet about the

following tree: 5 10

#### ANSWER 1 - Worksheet #16

Root: 2

Descendants of 7: 2, 10, 6, 5, 11

▶ Leaves: 2 (in black), 10, 5, 11, 4 ▶ Length of path 2-5-9-4: 3

Internal nodes: 7, 5, 6, 9

Height of 7: 2

Siblings of 10: 2, 6

Height of tree: 3

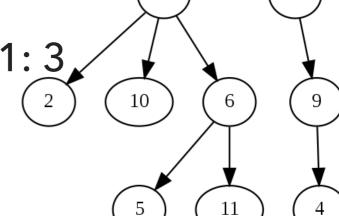
Parent of 6: 7

Degree of 7: 3

Children of 2 (in red): 7, 5

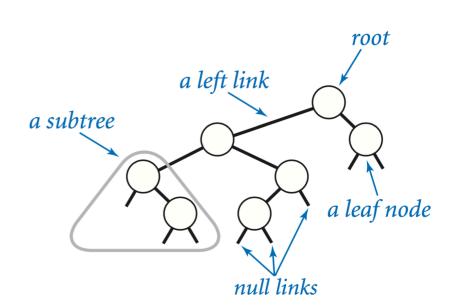
Arity/Degree of tree: 3

Ancestors of 10: 7 and 2 (in red) Level/depth of 11: 3



#### Basic idea behind a simple implementation

```
public class BinaryTree<E> {
   private Node root;
   /**
    * A node subclass which contains various recursive methods
      @param <E> The type of the contents of nodes
   private class Node {
       private E element;
       private Node left;
       private Node right;
       /**
        * Node constructor with subtrees
        * @param left the left node child
        * @param right the right node child
        * @param E
                        the element contained in the node
       public Node(Node left, Node right, E element) {
           this.left = left;
          this.right = right;
           this.element = item;
```



Lecture 16: Binary Trees, Binary Search, Heaps, and Priority Queues

- Binary Trees
- Tree traversals
- Binary Search
- Binary Heaps
- Priority Queues

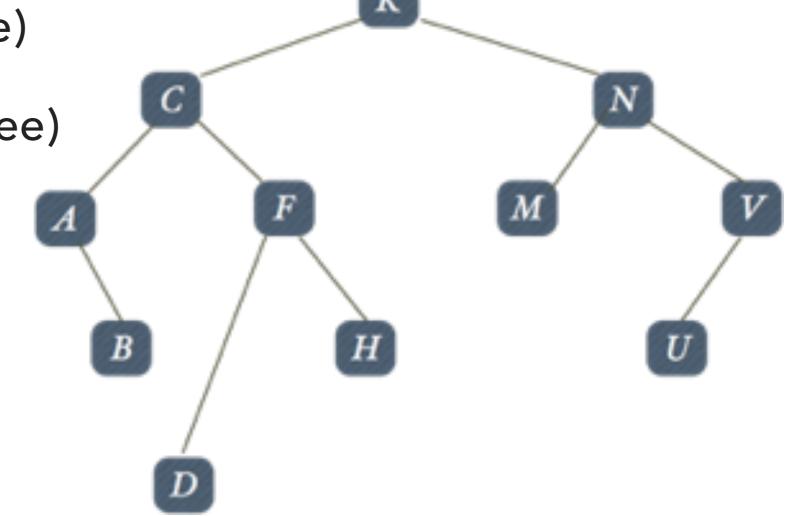
#### Pre-order traversal

- Preorder(Tree)
  - Mark root as visited

Preorder(Left Subtree)

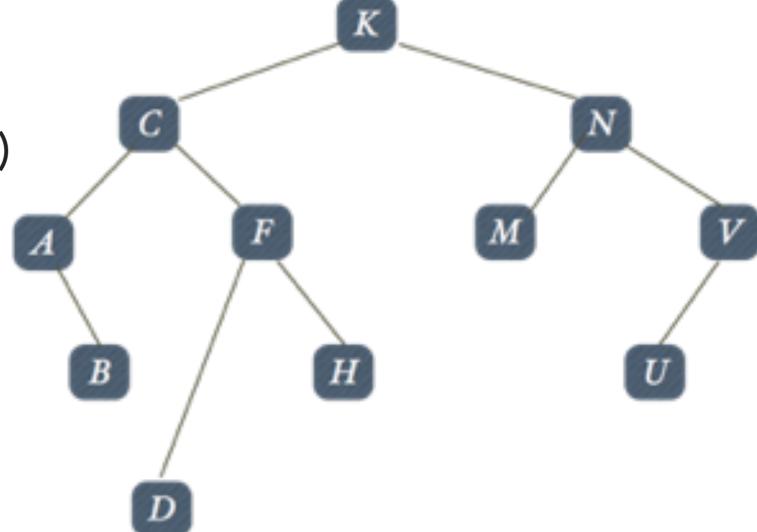
Preorder(Right Subtree)

KCABFDHNMVU



#### In-order traversal

- Inorder(Tree)
  - Inorder(Left Subtree)
  - Mark root as visited
  - Inorder(Right Subtree)
- A B C D F H K M N U V

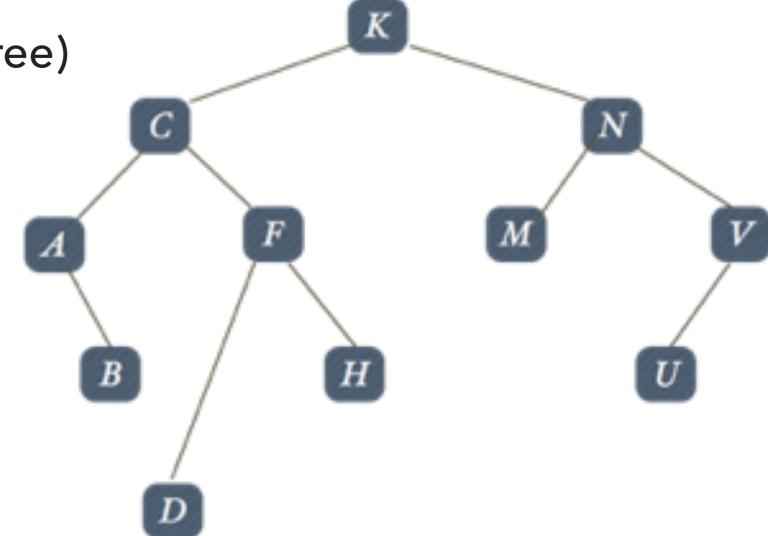


#### Post-order traversal

- Postorder(Tree)
  - Postorder(Left Subtree)

Postorder(Right Subtree)

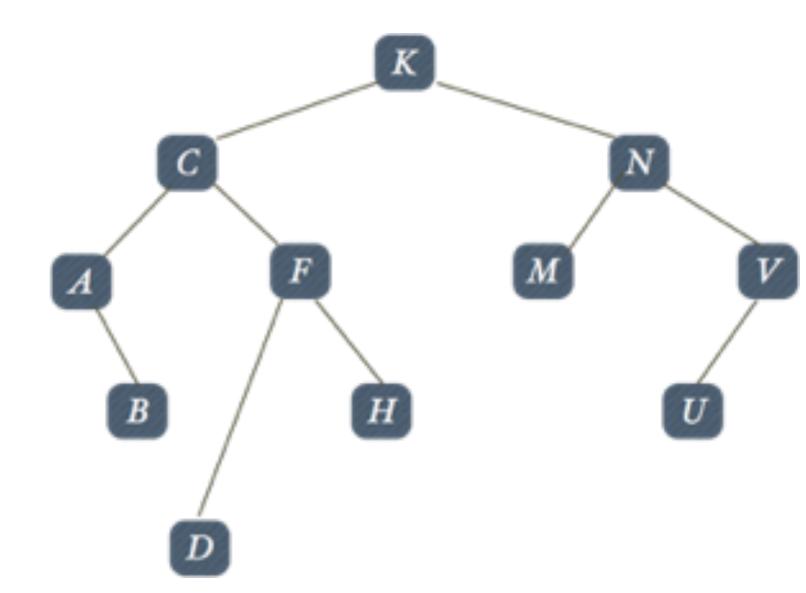
- Mark root as visited
- BADHFCMUVNK



#### Level-order traversal

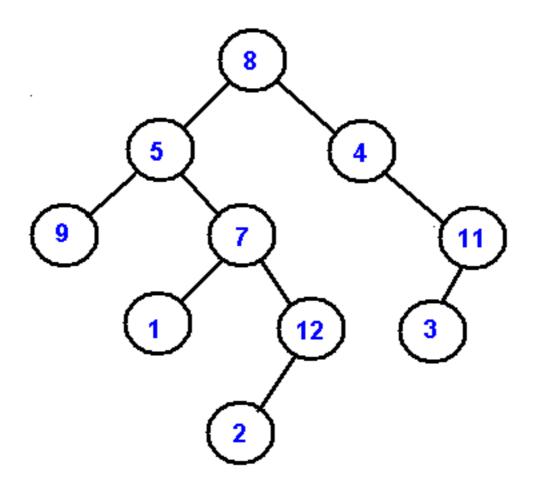
From left to right, mark nodes of level i as visited before nodes in level i+1. Start at level 0.

KCNAFMVBDHU



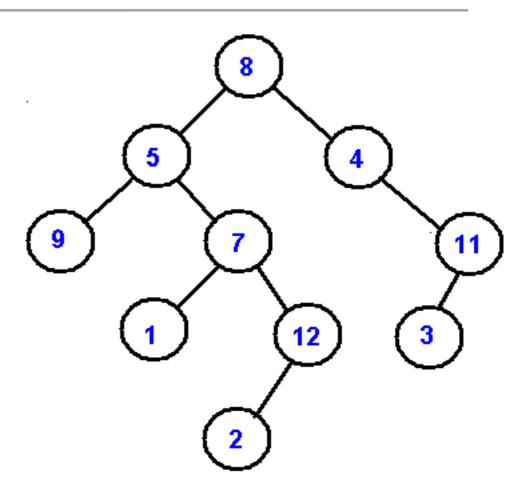
#### Practice Time - Problem 2 Worksheet #16

List the nodes in pre-order, in-order, post-order, and level order:



#### ANSWER Problem 2 Worksheet #16

- Pre-order: 8, 5, 9, 7, 1, 12, 2, 4, 11, 3
- In-order: 9, 5, 1, 7, 2, 12, 8, 4, 3, 11
- Post-order: 9, 1, 2, 12, 7, 5, 3, 11, 4, 8
- Level-order: 8, 5, 4, 9, 7, 11, 1, 12, 3, 2



Lecture 16: Binary Trees, Binary Search, Heaps, and Priority Queues

- Binary Trees
- Tree traversals
- Binary Search
- Binary Heaps
- Priority Queues

#### Binary search

- Goal: Given a sorted array and a key, find index of the key in the array.
- Basic mechanism: Compare key against middle entry.
  - If too small, repeat in left half.
  - If too large, repeat in right half.
  - If equal, you are done.

#### Binary search implementation

- First binary search published in 1946.
- First bug-free one in 1962.
- Bug in Java's Arrays.binarySearch() discovered in 2006 <a href="https://ai.googleblog.com/2006/06/extra-extra-read-all-about-it-nearly.html">https://ai.googleblog.com/2006/06/extra-extra-read-all-about-it-nearly.html</a>

```
public static int binarySearch(int[] a, int key) {
    int lo = 0, hi = a.length-1;
    while (lo <= hi) {
        int mid = lo + (hi - lo) / 2;
        if (key < a[mid])
            hi = mid - 1;
        else if (key > a[mid])
            lo = mid + 1;
        else return mid; }
    return -1;
}
```

• Uses at most  $1 + \log n$  key compares to search in a sorted array of size n, that is it is  $O(\log n)$ .

Lecture 16: Binary Trees, Binary Search, Heaps, and Priority Queues

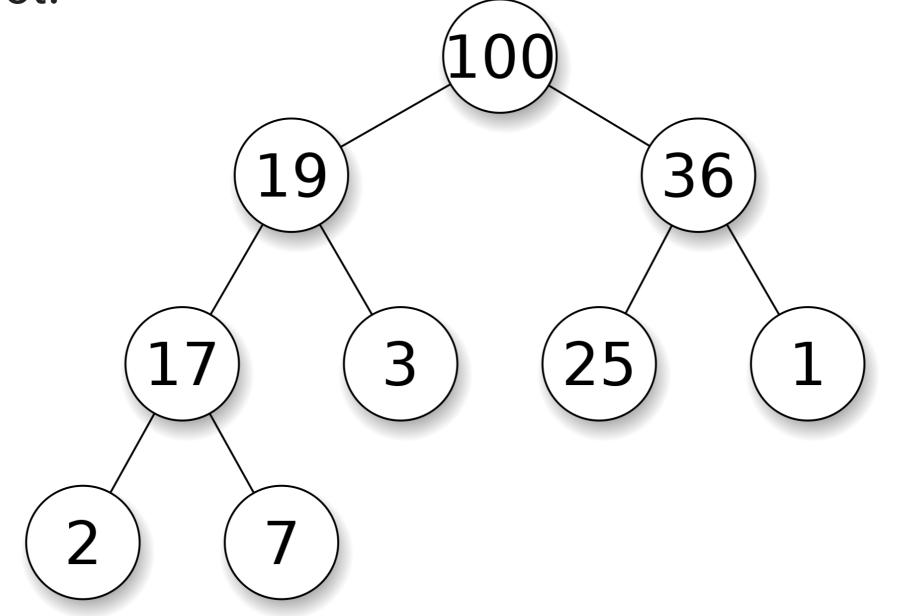
- Binary Trees
- Tree traversals
- Binary Search
- Binary Heaps
- Priority Queues

#### Heap-ordered binary trees

- A binary tree is heap-ordered if the key in each node is larger than or equal to the keys in that node's two children (if any).
- Equivalently, the key in each node of a heap-ordered binary tree is smaller than or equal to the key in that node's parent (if any).
- No assumption of which child is smaller.
- Moving up from any node, we get a non-decreasing sequence of keys.
- Moving down from any node we get a non-increasing sequence of keys.

## Heap-ordered binary trees

The largest key in a heap-ordered binary tree is found at the root!



#### Binary heap representation

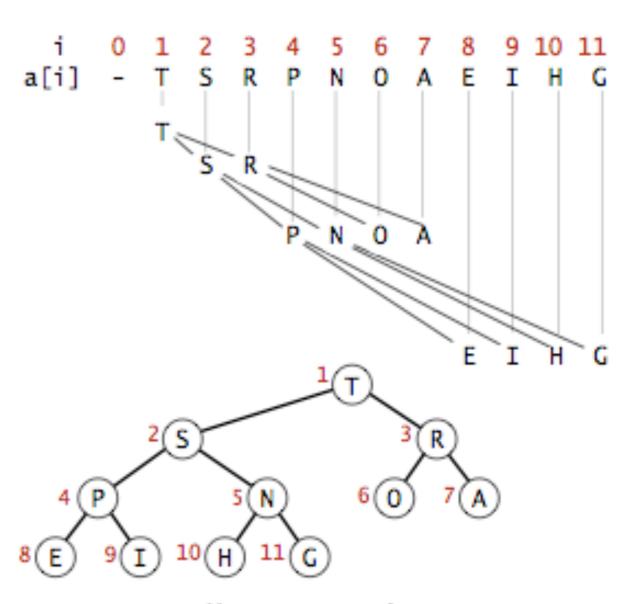
- We could use a linked representation but we would need three links for every node (one for parent, one for left subtree, one for right subtree).
- If we use complete binary trees, we can use instead an array.
  - Compact arrays vs explicit links means memory savings!

#### Binary heaps

- Binary heap: the array representation of a complete heapordered binary tree.
  - Items are stored in an array such that each key is guaranteed to be larger (or equal to) than the keys at two other specific positions (children).
- Max-heap but there are min-heaps, too.

## Array representation of heaps

- Nothing is placed at index 0.
- Root is placed at index 1.
- Rest of nodes are placed in level order.
- No unnecessary indices and no wasted space because it's complete.



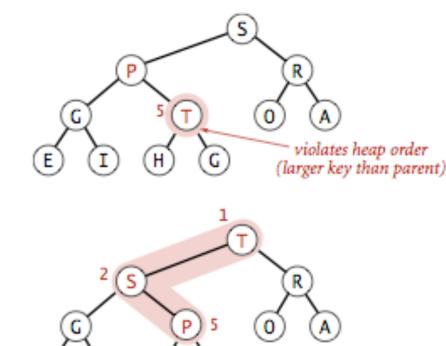
Heap representations

Reuniting immediate family members.

- For every node at index k, its parent is at index  $\lfloor k/2 \rfloor$ .
- Its two children are at indices 2k and 2k + 1.
- We can travel up and down the heap by using this simple arithmetic on array indices.

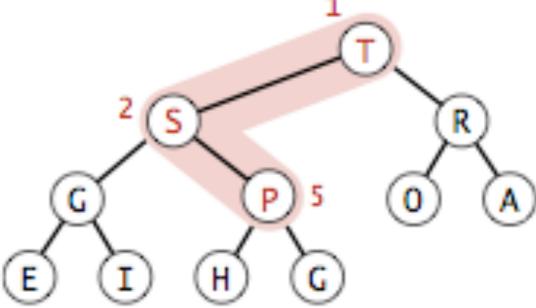
## Swim/promote/percolate up/bottom up reheapify

- Scenario: a key becomes larger than its parent therefore it violates the heap-ordered property.
- To eliminate the violation:
  - Exchange key in child with key in parent.
  - Repeat until heap order restored.



# Swim/promote/percolate up

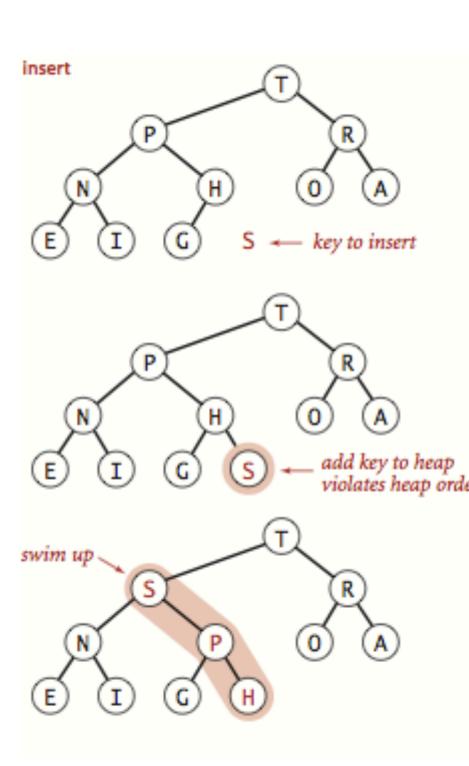
```
private void swim(int k) {
    while (k > 1 && a[k/2].compareTo(a[k])<0) {
        E temp = a[k];
        a[k] = a[k/2];
        a[k/2] = temp;
        k = k/2;
    }
}</pre>
E I H G violates heap order (larger key than parent)
```



# Binary heap: insertion

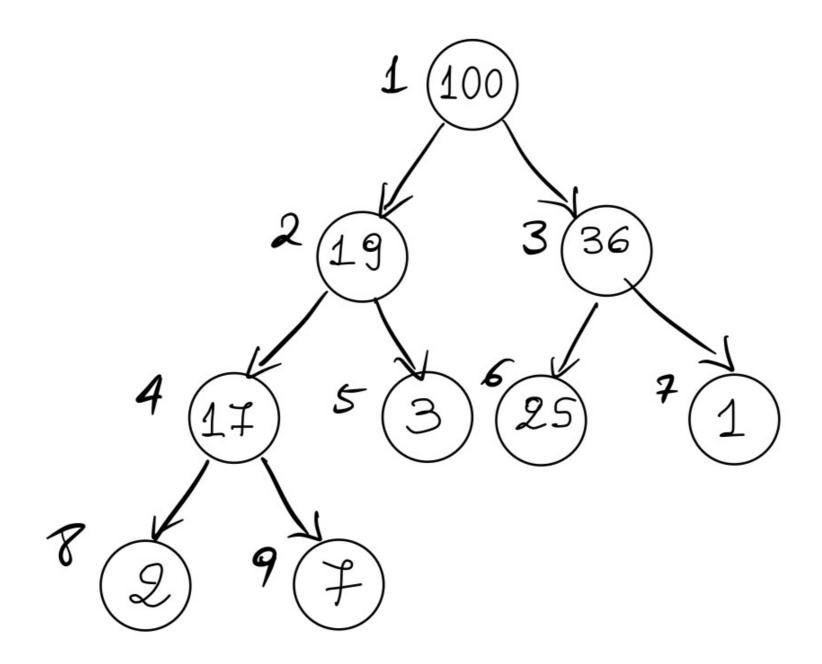
- Insert: Add node at end in bottom level, then swim it up.
- Cost: At most  $\log n + 1$  compares.

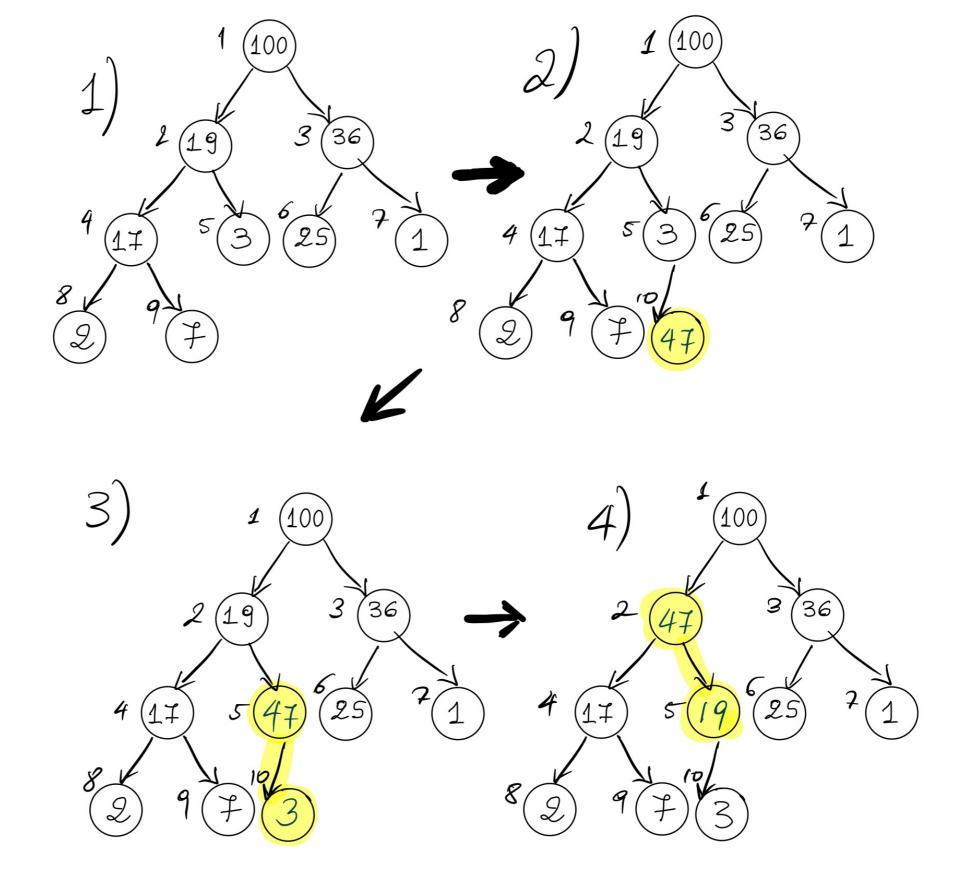
```
public void insert(E x) {
    a[++n] = x;
    swim(n);
}
```



### Practice Time - Problem 3 Worksheet #16

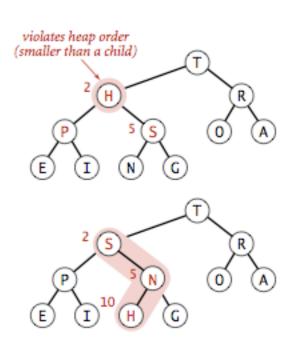
Insert 47 in this binary heap.





# Sink/demote/top down heapify

- Scenario: a key becomes smaller than one (or both) of its children's keys.
- To eliminate the violation:
  - Exchange key in parent with key in larger child.
  - > Repeat until heap order is restored.

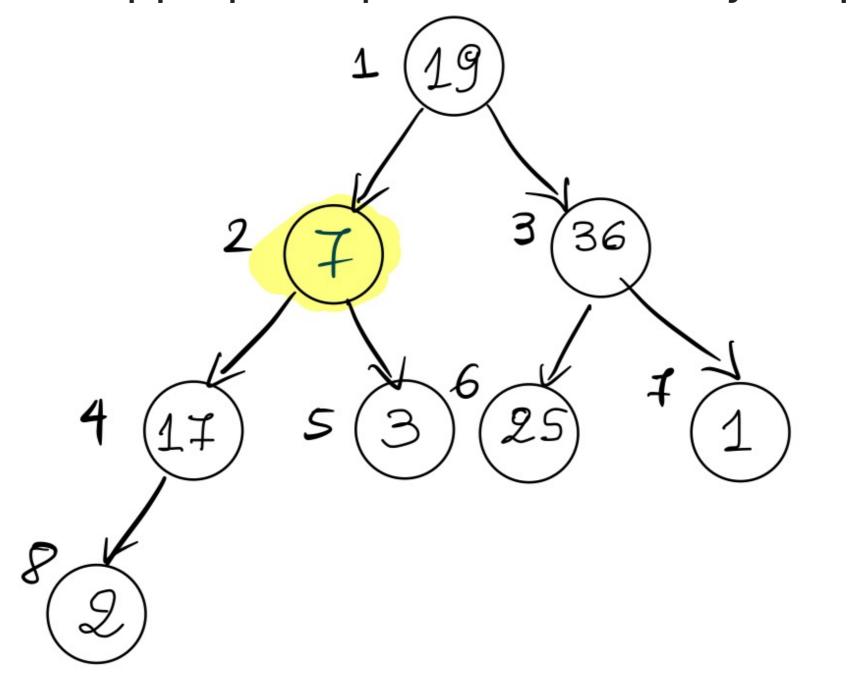


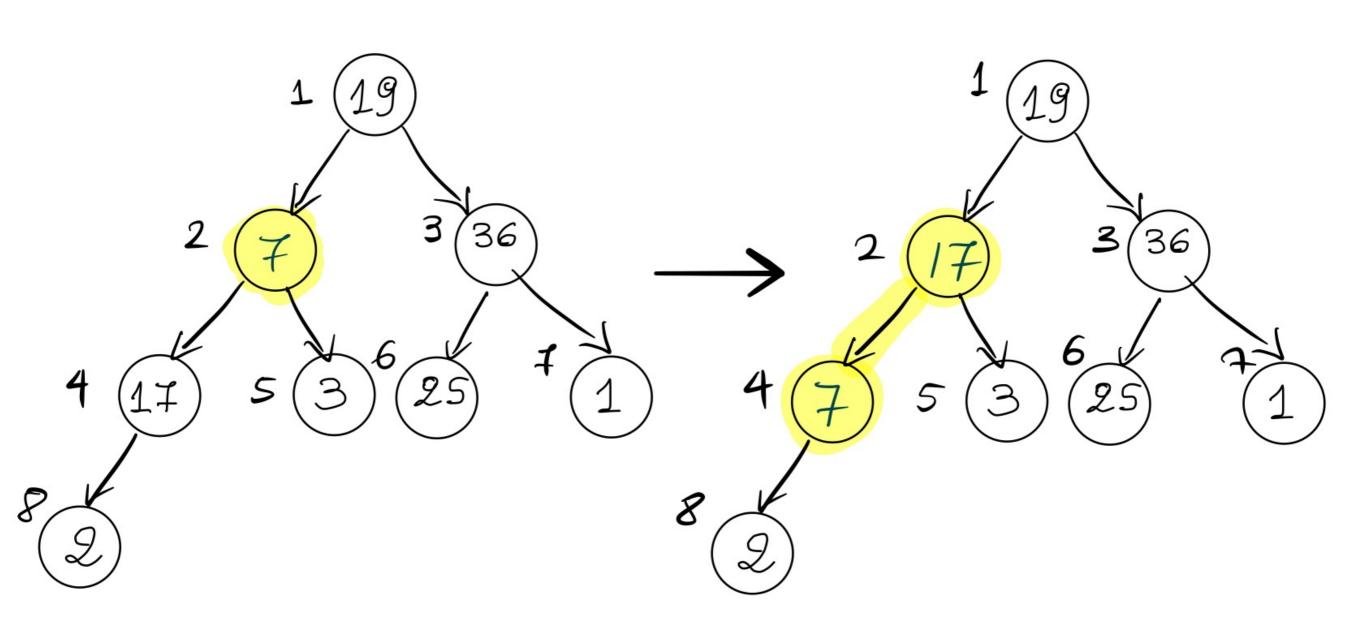
# Sink/demote/top down heapify

```
violates heap order
private void sink(int k) {
                                            (smaller than a child)
    while (2*k <= n) {
         int j = 2*k;
         if (j < n \& a[j].compareTo(a[j+1])<0)
             j++;
         if (a[k].compareTo(a[j])>=0))
             break;
         E \text{ temp} = a[k];
         a[k] = a[j];
         a[j] = temp;
         k = j;
```

#### Practice Time - Problem 4 Worksheet #16

Sink 7 to its appropriate place in this binary heap.

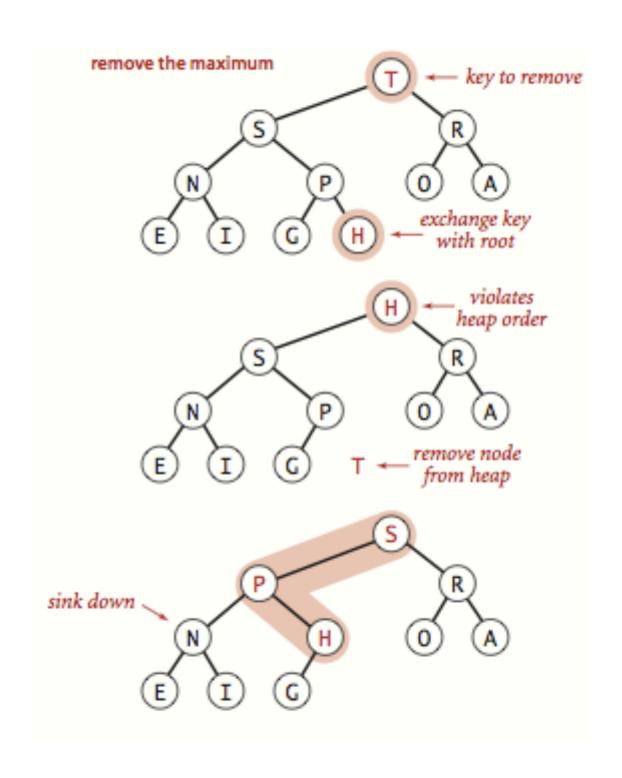




Binary heap: return (and delete) the maximum

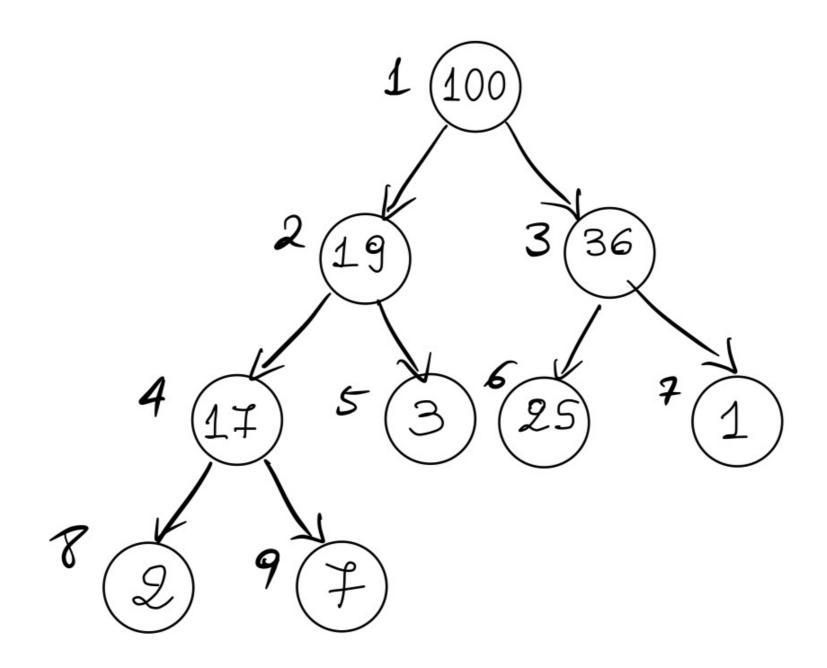
- Delete max: Exchange root with node at end. Return it and delete it. Sink the new root down.
- $\triangleright$  Cost: At most  $2 \log n$  compares.

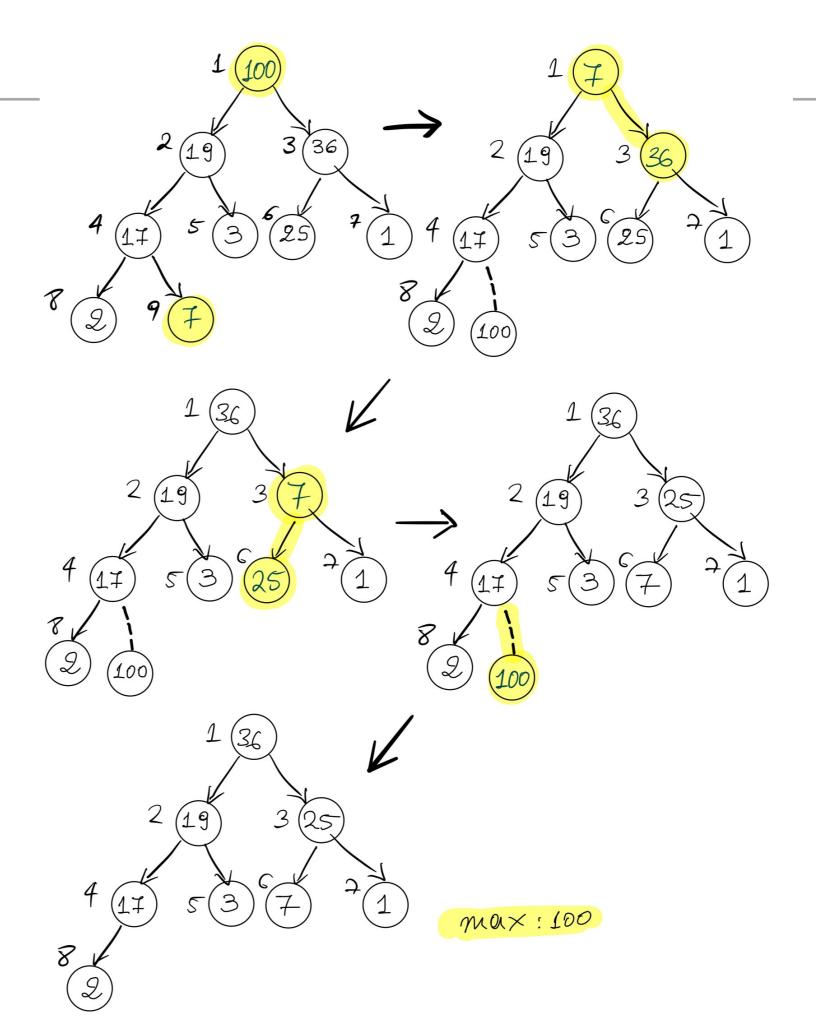
# Binary heap: delete and return maximum



### Practice Time - Problem 5 Worksheet #16

Delete max (and return it!)

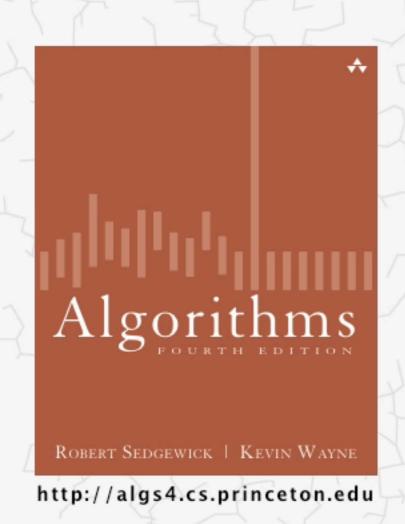




Things to remember about running time complexity of heaps

- Insertion is  $O(\log n)$ .
- ▶ Delete max is  $O(\log n)$ .
- **Space** efficiency is O(n).

# Algorithms



# 2.4 BINARY HEAP DEMO

Lecture 16: Binary Trees, Binary Search, Heaps, and Priority Queues

- Binary Trees
- Tree traversals
- Binary Search
- Binary Heaps
- Priority Queues

# **Priority Queue ADT**

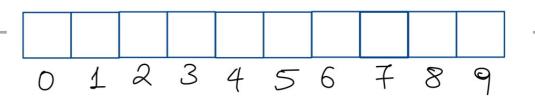
- Two operations:
  - Delete the maximum
  - Insert
- Applications: load balancing and interruption handling in OS, Huffman codes for compression, A\* search for AI, Dijkstra's and Prim's algorithm for graph search, etc.
- How can we implement a priority queue efficiently?



# Option 1: Unordered array

- The lazy approach where we defer doing work (deleting the maximum) until necessary.
- Insert is O(1) and assumes we have the space in the array.
- Delete maximum is O(n) (have to traverse the entire array to find the maximum element and exchange it with the last element).

```
public class UnorderedArrayMaxPQ<Key extends Comparable<Key>> {
   private Key[] pq; // elements
   private int n;  // number of elements
   // set inititial size of heap to hold size elements
   public UnorderedArrayMaxPQ(int capacity) {
       pq = (Key[]) new Comparable[capacity];
       n = 0;
    }
   public boolean isEmpty() { return n == 0; }
   public int size()
                     { return n;
   public void insert(Key x) { pq[n++] = x; }
   public Key delMax() {
       int max = 0;
       for (int i = 1; i < n; i++){
           if (pq[max].compareTo(pq[i]) < 0) {</pre>
                max = i;
       Key temp = pq[max];
       pq[max] = pq[n-1];
       pq[n-1] = temp;
       return pq[--n];
```



#### **Practice Time**

Given an empty array of capacity 10, perform the following operations in a priority queue based on an unordered array (lazy approach):

1. Insert P

7. Insert M

2. Insert Q

8. Delete max

3. Insert E

9. Insert P

4. Delete max

10. Insert L

5. Insert X

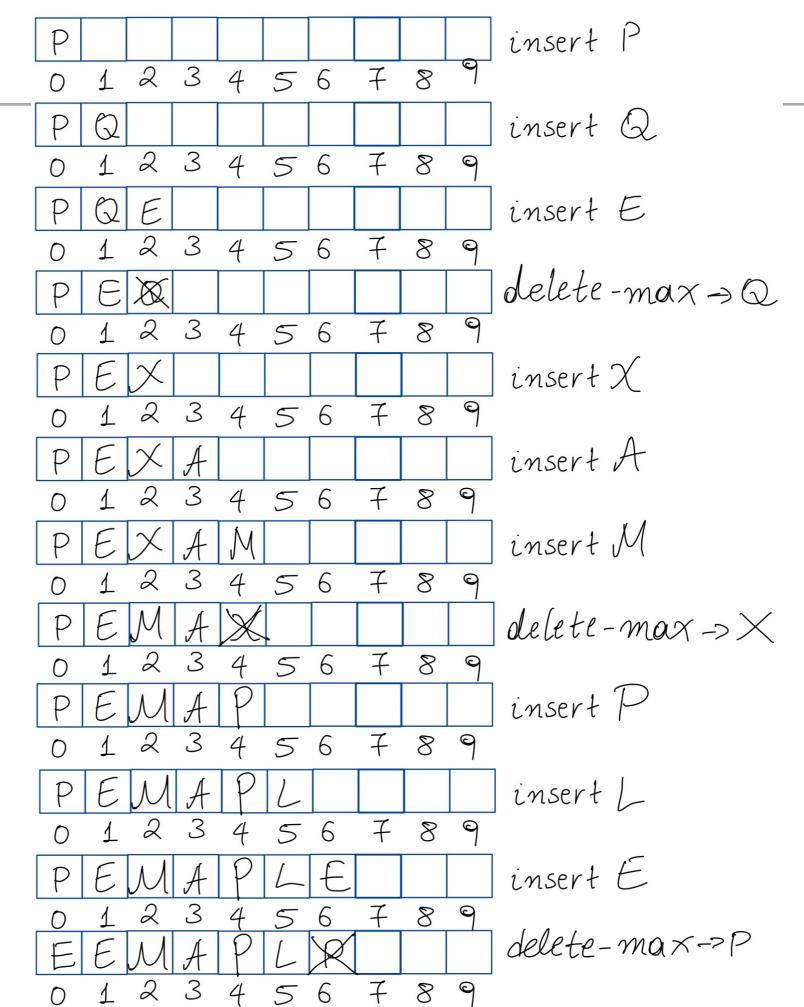
11. Insert E

6. Insert A

12. Delete max

#### **PRIORITY QUEUES**

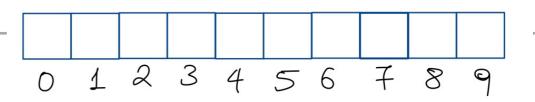
Answer



# Option 2: Ordered array

- The eager approach where we do the work (keeping the array sorted) up front to make later operations efficient.
- Insert is O(n) (we have to find the index to insert and shift elements to perform insertion).
- Delete maximum is O(1) (just take the last element which will be the maximum).

```
public class OrderedArrayMaxPQ<Key extends Comparable<Key>> {
   private Key[] pq; // elements
   private int n;  // number of elements
   // set inititial size of heap to hold size elements
   public OrderedArrayMaxPQ(int capacity) {
       pq = (Key[]) (new Comparable[capacity]);
       n = 0;
   public boolean isEmpty() { return n == 0; }
   public int size() { return n;
   public Key delMax() { return pq[--n]; }
   public void insert(Key key) {
       int i = n-1;
       while (i \geq 0 && key.compareTo(pq[i]) < 0) {
           pq[i+1] = pq[i];
           i--;
       }
       pq[i+1] = key;
       n++;
```



#### **Practice Time**

Given an empty array of capacity 10, perform the following operations in a priority queue based on an ordered array (eager approach):

1. Insert P

7. Insert M

2. Insert Q

8. Delete max

3. Insert E

9. Insert P

4. Delete max

10. Insert L

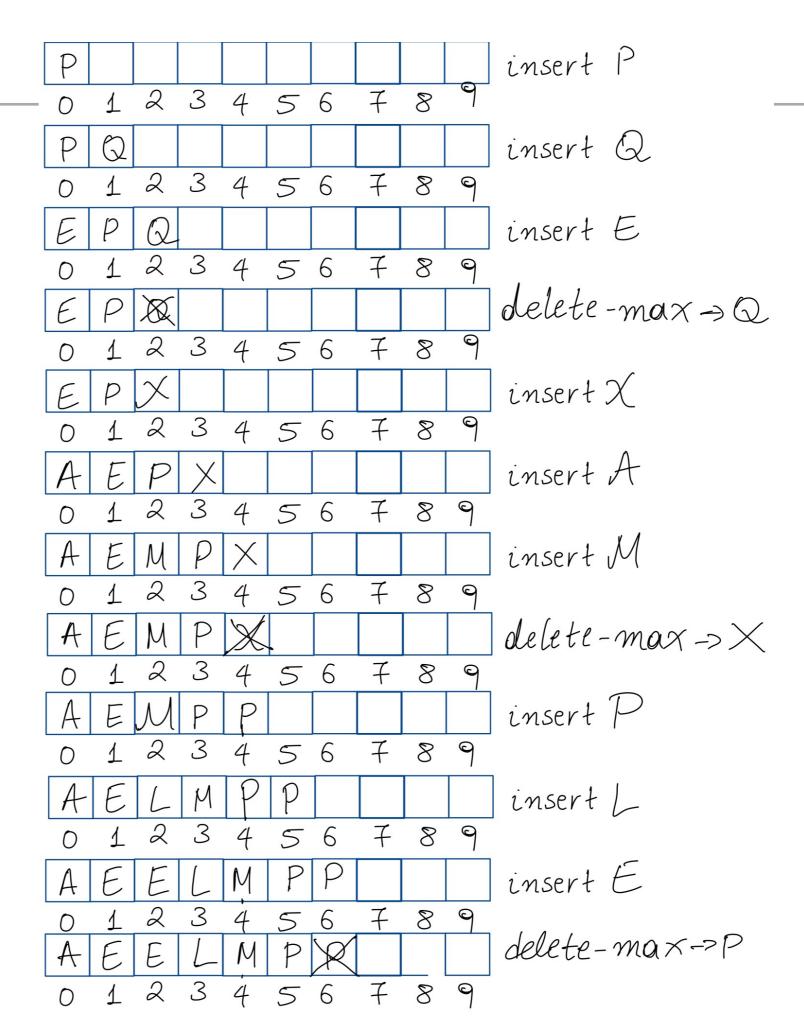
5. Insert X

11. Insert E

6. Insert A

12. Delete max

#### Answer



### Option 3: Binary heap

- Will allow us to both insert and delete max in  $O(\log n)$  running time.
- There is no way to implement a priority queue in such a way that insert and delete max can be achieved in O(1) running time.
- Priority queues are synonyms to binary heaps.

#### **Practice Time**

Given an empty binary heap that represents a priority queue, perform the following operations:

1. Insert P

7. Insert M

2. Insert Q

8. Delete max

3. Insert E

9. Insert P

4. Delete max

10. Insert L

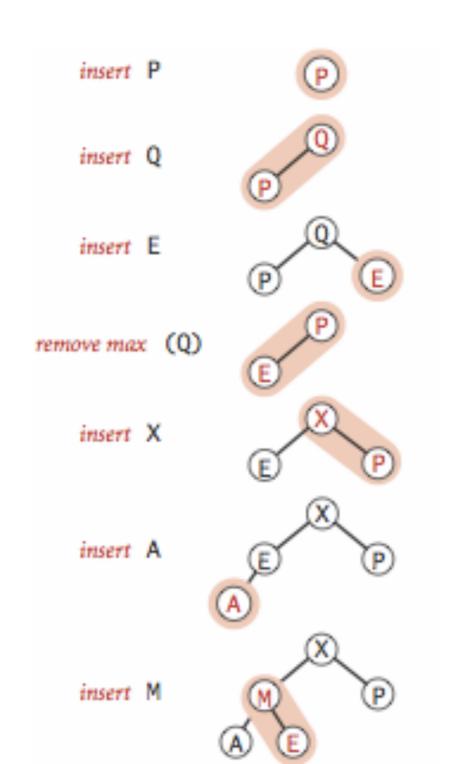
5. Insert X

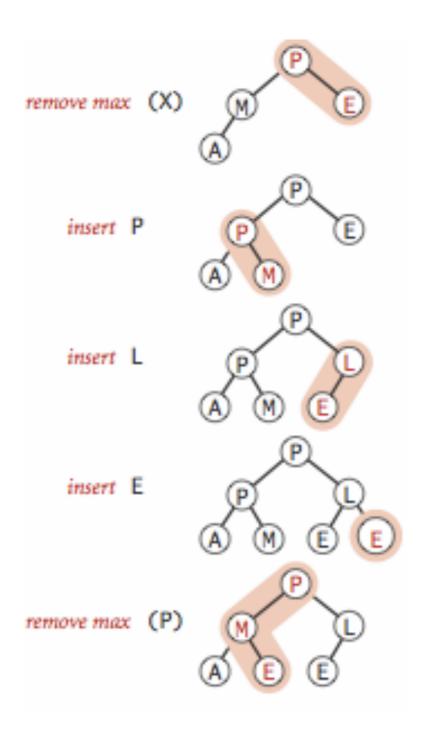
11. Insert E

6. Insert A

12. Delete max

#### Answer





### Lecture 16: Binary Trees, Binary Search, Heaps, and Priority Queues

- Binary Trees
- Tree traversals
- Binary Search
- Binary Heaps
- Priority Queues

# Readings:

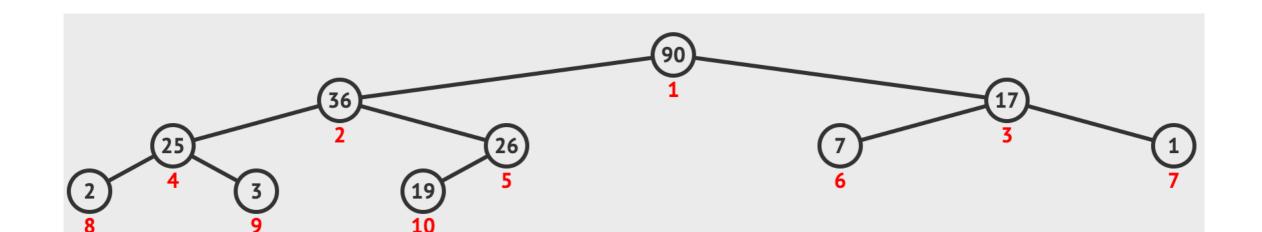
- Recommended Textbook:
  - Chapter 2.4 (Pages 308-327)
- Website:
  - Heaps: <a href="https://algs4.cs.princeton.edu/24pq/">https://algs4.cs.princeton.edu/24pq/</a>
- Visualization:
  - Insert and ExtractMax: <a href="https://visualgo.net/en/heap">https://visualgo.net/en/heap</a>

### Worksheet

<u>Lecture 16 worksheet</u>

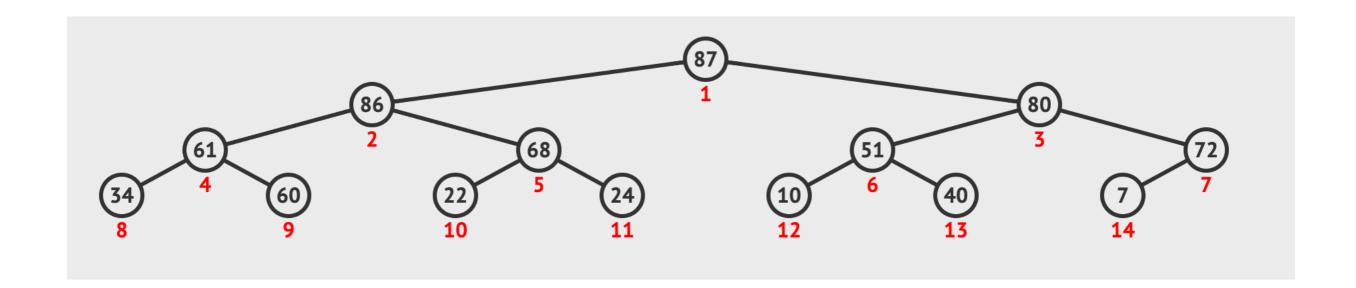
#### **Practice Problem 1**

- Given the tree below, list the nodes in order of visit in a:
  - pre-order traversal
  - in-order traversal
  - post-order traversal
  - level-order traversal



#### Practice Problem 2

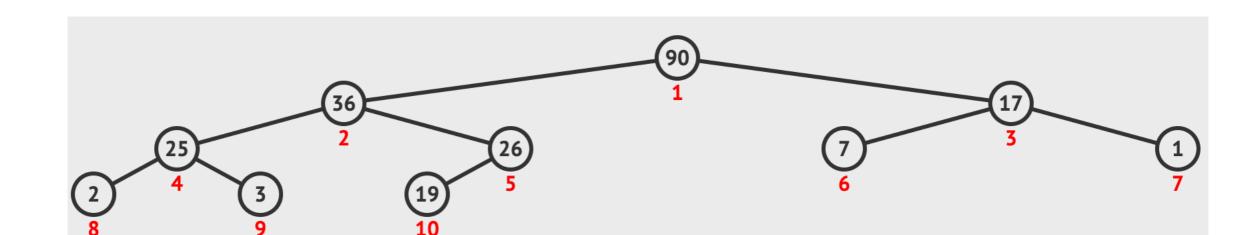
• Given the binary heap below, delete and return the max.



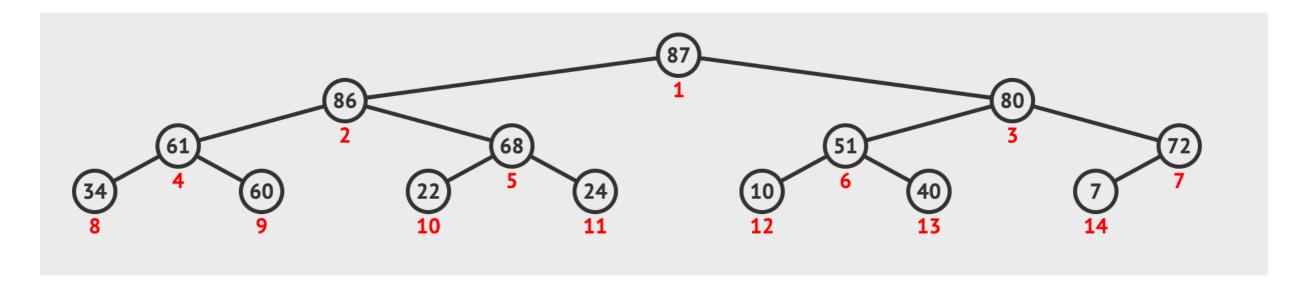
#### **Practice Problem 3**

Suppose that the sequence 16, 18, 9, 15, \*, 18, \*, \*, 9, \*, 20, \*, 25, \*, \*, \*, 17, 21, 5, \*, \*, \*, 21, \*, 5 (where a number means insert and an asterisk means delete the maximum) is applied to an initially empty priority queue. Give the sequence of numbers returned by the delete maximum operations.

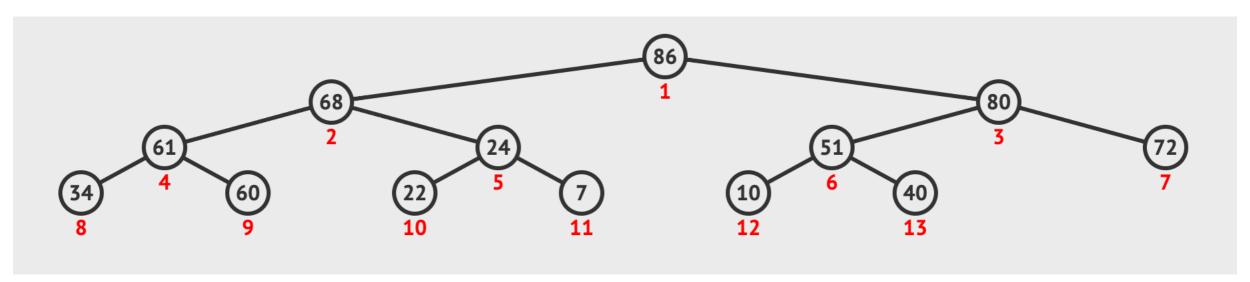
- pre-order: 90, 36, 25, 2, 3, 26, 19, 17, 7, 1
- in-order: 2, 25, 3, 36, 19, 26, 90, 7, 17, 1
- post-order: 2, 3, 25, 19, 26, 36, 7, 1, 17, 90
- level-order: 90, 36, 17, 25, 26, 7, 1, 2, 3, 19



Given the binary heap below, delete and return the max.







- Suppose that the sequence 16, 18, 9, 15, \*, 18, \*, \*, 9, \*, 20, \*, 25, \*, \*, \*, 17, 21, 5, \*, \*, \*, 21, \*, 5 (where a number means insert and an asterisk means delete the maximum) is applied to an initially empty priority queue. Give the sequence of numbers returned by the delete maximum operations.
- 18, 18, 16, 15, 20, 25, 9, 9, 21, 17, 5, 21