Lecture 15: OS and Processes

CS 105 Spring 2025

Intro to Operating Systems

- the **operating system** is a piece of software that manages a computer's resources for its users and their applications
 - Examples: OSX, Windows, Ubuntu, iOS, Android, Chrome OS

Intro to Operating Systems

Intro to Operating Systems

- resource allocation
- isolation
- communication
- access control

- multiprocessing
- virtual memory
- reliable networking
- virtual machines

- user interface
- file I/O
- device management
- process control

Kernel Mode User Mode

Kernel Mode

 unrestricted access to hardware

User Mode

 must ask kernel to access hw (system call)

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User Mode

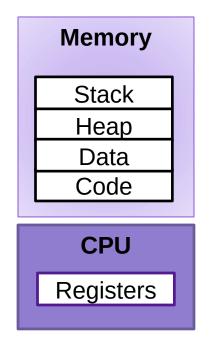
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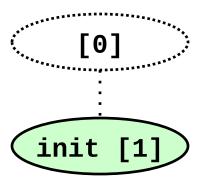
attempts to execute privileged instructions cause exceptions

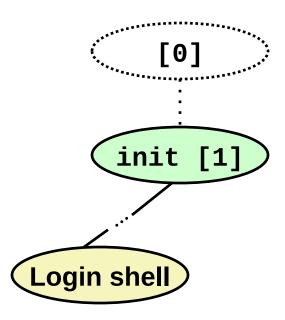
 Operating system mode is set in hardware, can't be changed by user-level code

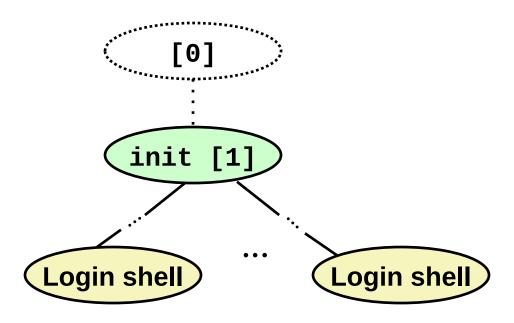
Processes

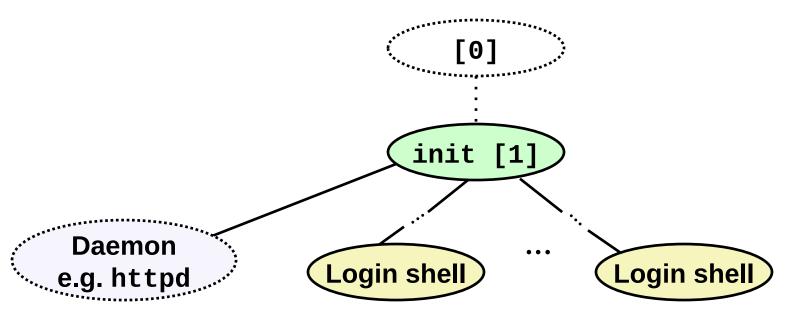
- A program is a file containing code + data that describes a computation
- A process is an instance of a running program.
 - One of the most profound ideas in computer science
 - Not the same as "program" or "processor"

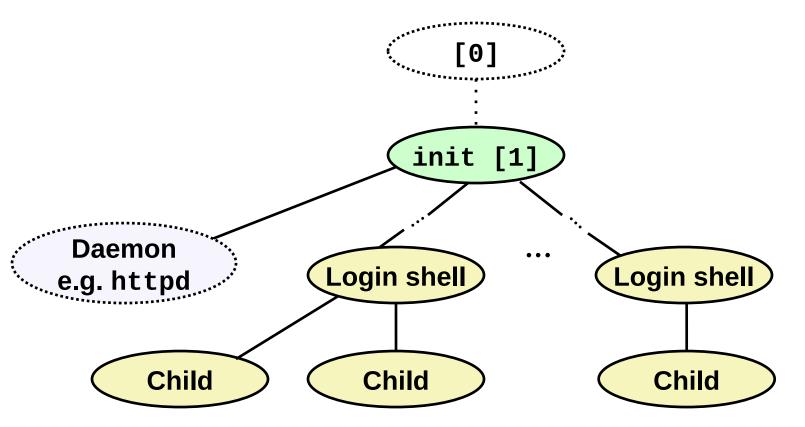


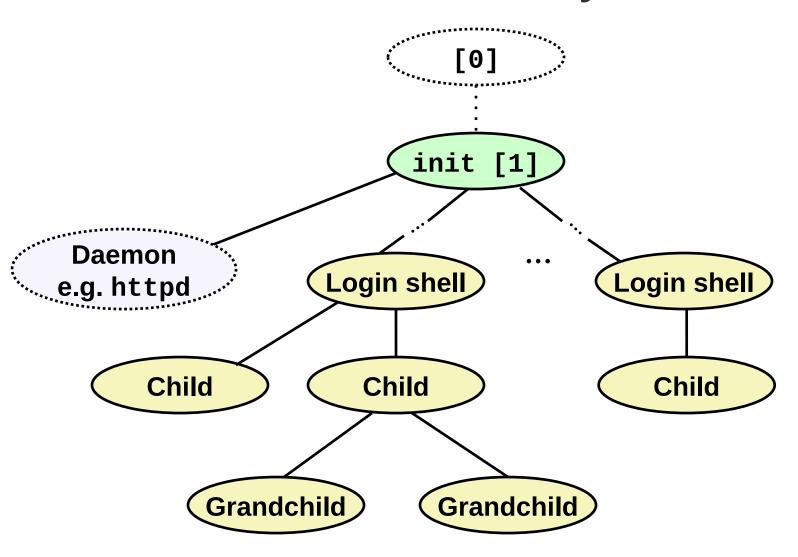


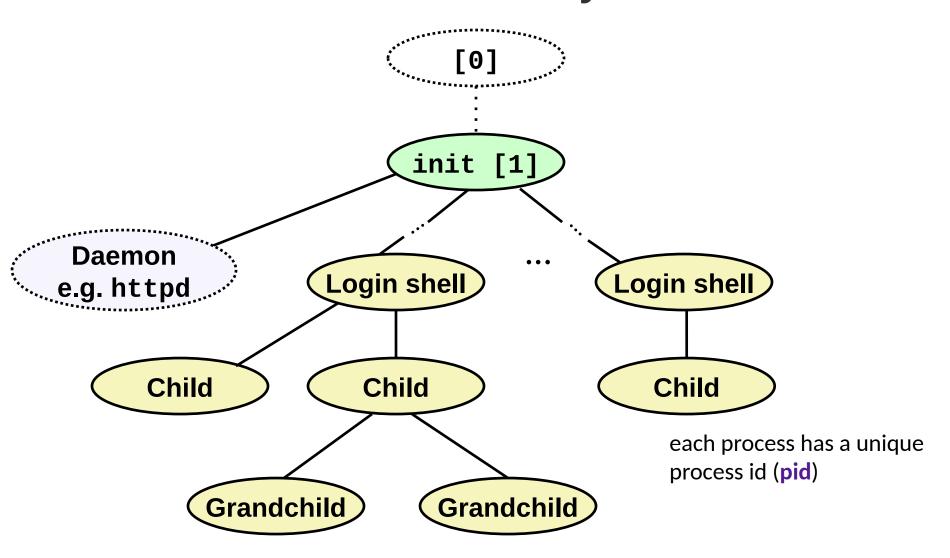


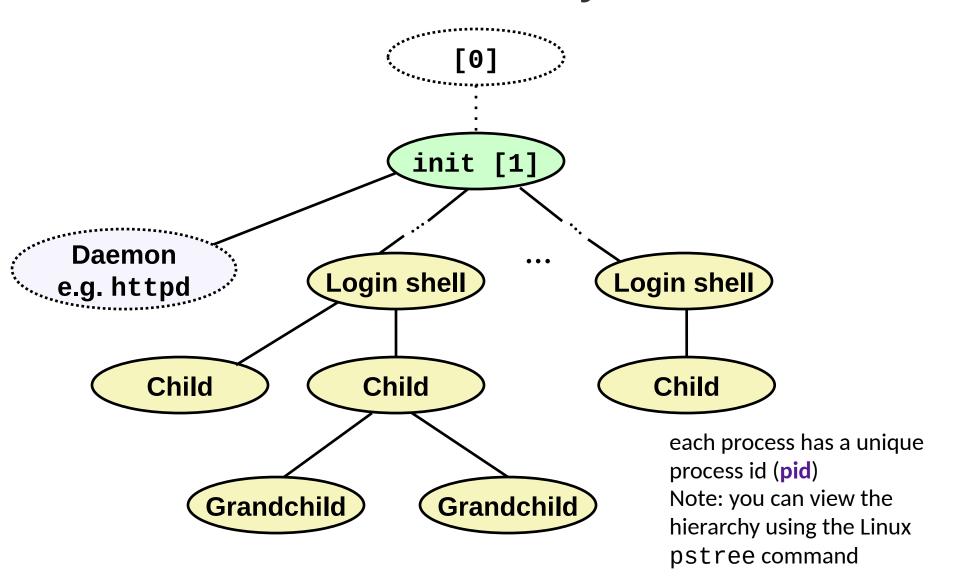












Creating Processes

 Parent process creates a new running child process by calling fork

int fork(void)

- Returns 0 to the child process, child's PID to parent process
- Child is *almost* identical to parent:
 - Child get an identical (but separate) copy of the parent's virtual address space.
 - Child gets identical copies of the parent's open file descriptors
 - Child has a different PID than the parent

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 fork

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- fork is interesting (and often confusing) because it is called once but returns twice

```
int main(){
  pid_t id;
  int x = 1;
  id = fork();
  if (id == 0) { /* Child */
     printf("child : x=%d\n", ++x);
        return 0;
  /* Parent */
  printf("parent: x=%d\n", --x);
  return 0;
}
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Call once, return twice

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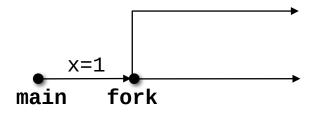
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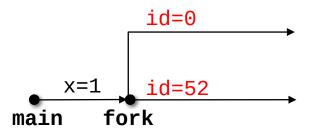


Child Process (pid: 52)

Original Process (pid:47)

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int main(){
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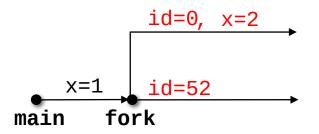


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id=0, x=2 child: x=2

printf

X=1 id=52

Main fork

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child: x=2
Child Process (pid: 52)

printf

x=1 id=52 x=0 parent: x=0
Original Process (pid:47)

main fork printf
```

int execve(char *filename, char *argv[], char *envp[])

- int execve(char *filename, char *argv[], char *envp[])
- Loads and runs in the current process:
 - Executable file filename
 - Can be object file or script file beginning with #!interpreter (e.g., #!/bin/bash)
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- Overwrites code, data, and stack
 - Retains PID, open files and signal context
- Called once and never returns
 - ...except if there is an error

execve Example

```
int main(int argc, char** argv){
  printf("0\n");
  pid t id = fork();
  if(id == 0){ // if child}
    execve("hello", NULL, NULL);
  } else { // if parent
    printf("1\n");
  printf("2\n");
  return 0;
                             exec.c
```

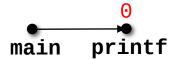
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int main(int argc, char** argv){
  printf("Hello!\n");

return 0;
}
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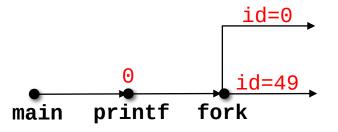
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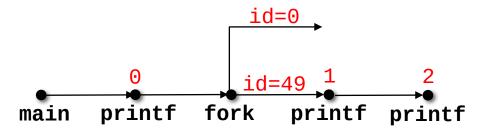
Child (pid = 49)

Parent (pid = 47)

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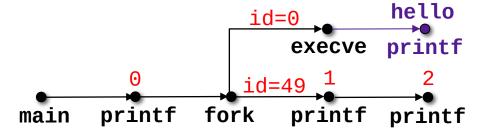
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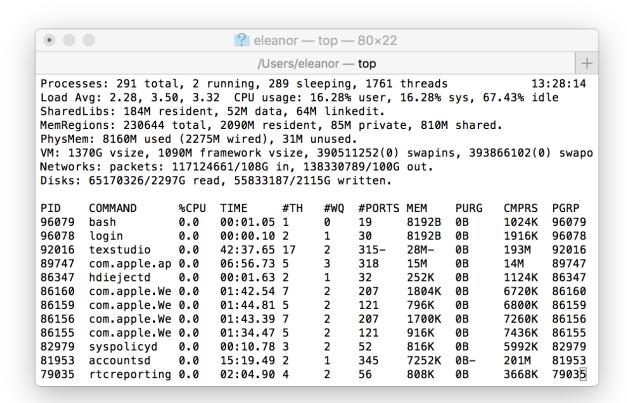


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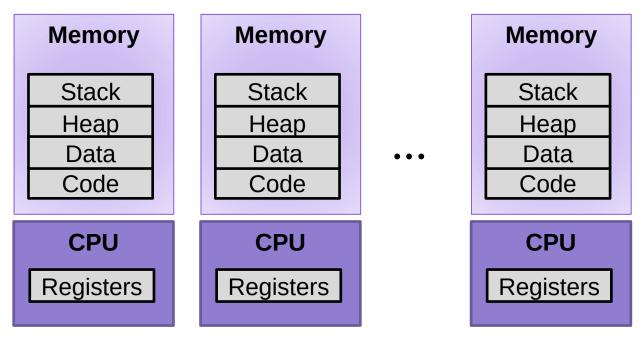
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Multiprocessing

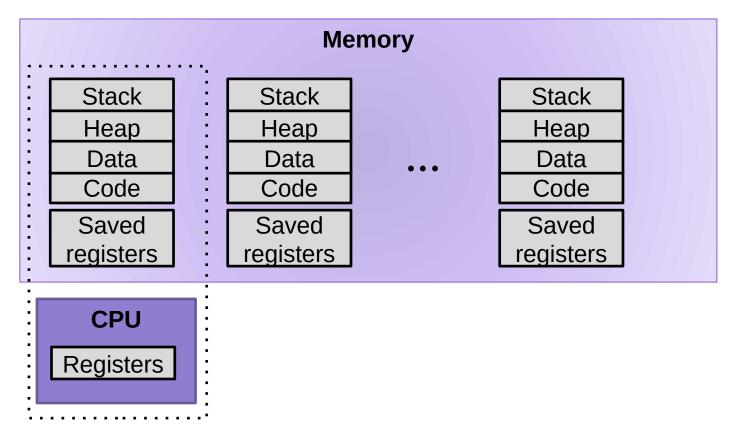
- Computer runs many processes simultaneously
- Running program "top" on Mac
 - Identified by Process ID (PID)



Multiprocessing: The Illusion



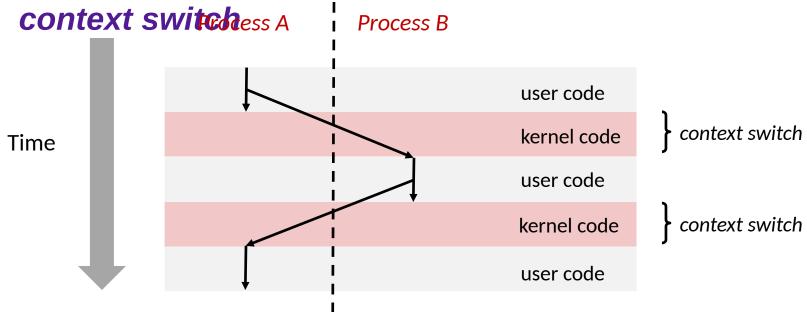
- Process provides each program with two key abstractions:
 - Logical control flow
 - Each program seems to have exclusive use of the CPU
 - Provided by kernel mechanism called context switching
 - Private address space
 - Each program seems to have exclusive use of main memory.
 - Provided by kernel mechanism called virtual memory



- Single processor executes multiple processes concurrently
 - Process executions interleaved (multitasking)
 - Register values for nonexecuting processes saved in memory
 - Address spaces managed by virtual memory system

Context Switching

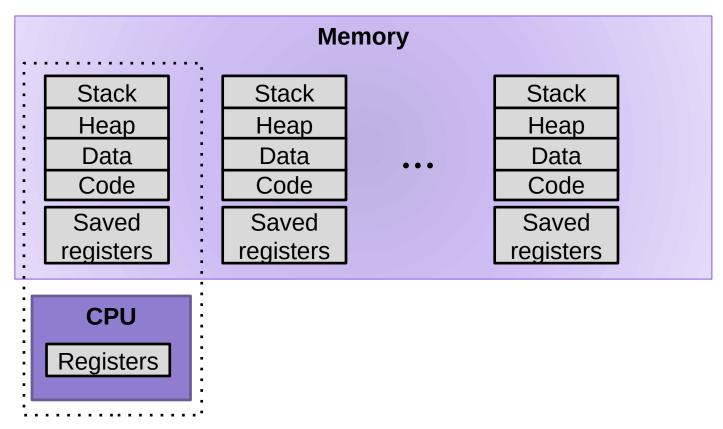
- Processes are managed by a shared chunk of memoryresident kernel code
 - Important: the kernel code is not a separate process, but rather code and data structures that the OS uses to manage all processes
- Control flow passes from one process to another via a



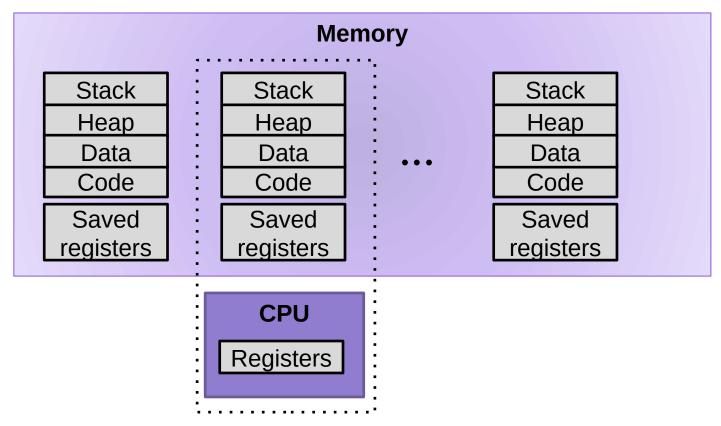
Process Control Block (PCB)

- To implement a context switch, OS maintains a PCB for each process containing:
 - process table, which contains information about the process (id, user, privilege level, arguments, status)
 - location of executable on disk
 - file table
 - register values (general-purpose registers, float registers, pc, eflags...)
 - memory state
 - scheduling information

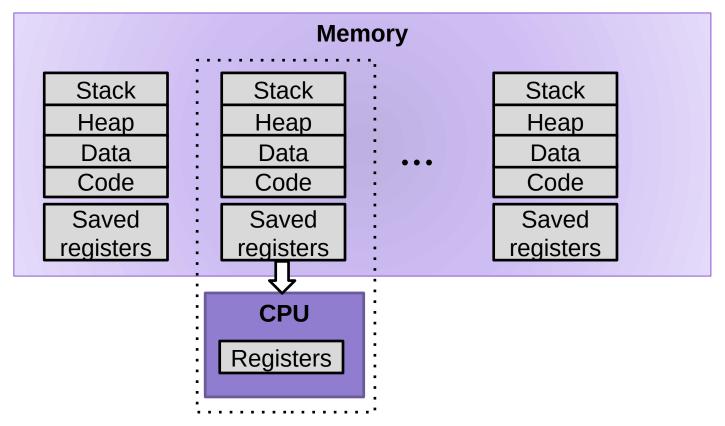
... and more!



Save current registers to memory (in PCB)

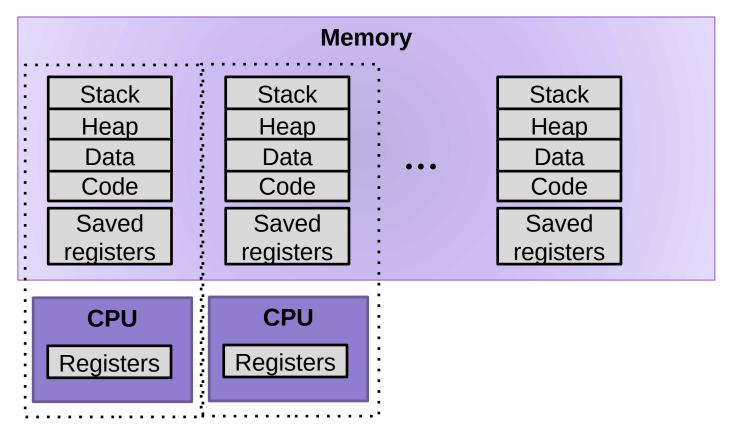


- 1. Save current registers to memory (in PCB)
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- 2. Schedule next process for execution
- 3. Load saved registers and switch address space

Multiprocessing: The (Modern) Reality

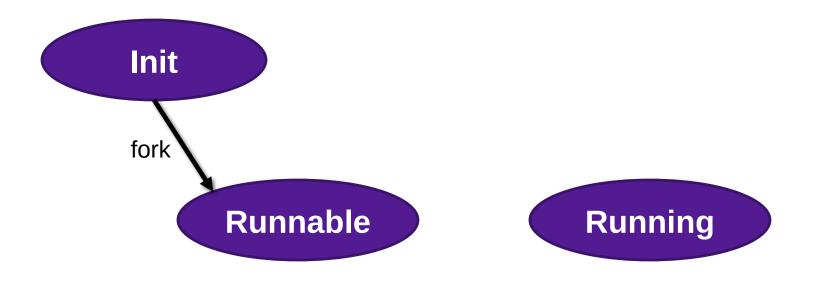


- Multicore processors
 - Multiple CPUs on single chip
 - Share main memory (and some of the caches)
 - Each can execute a separate process
 - Scheduling of processors onto cores done by kernel

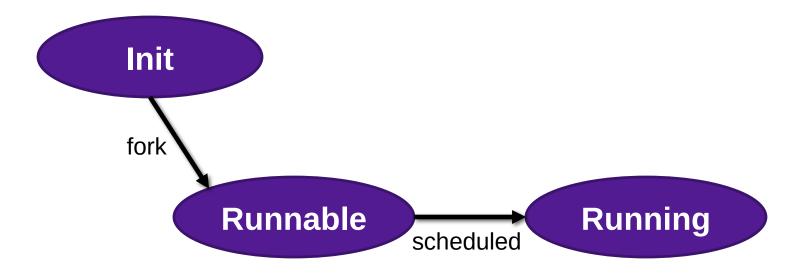
Exercise: Context Switching

A hardware designer argues that there are now enough onchip transistors to build a CPU with 1024 integer registers and 512 floating point registers. As a result, the compiler should almost never need to store anything on the stack. As a new operating systems expert, would you recommend building this new design.

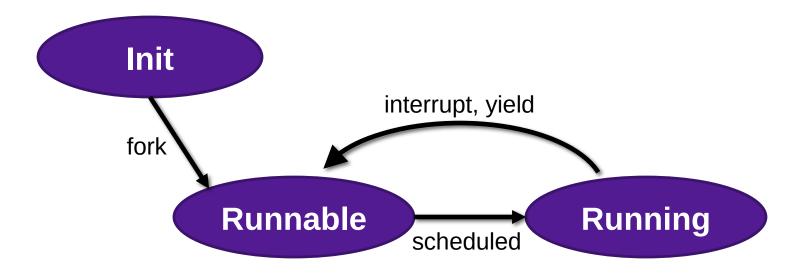
Process Life Cycle

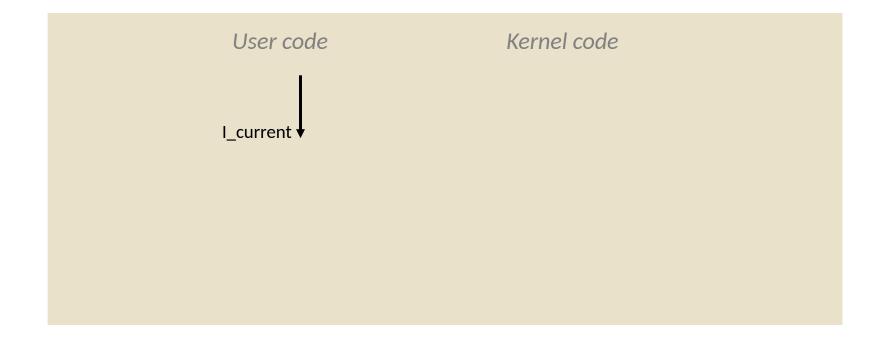


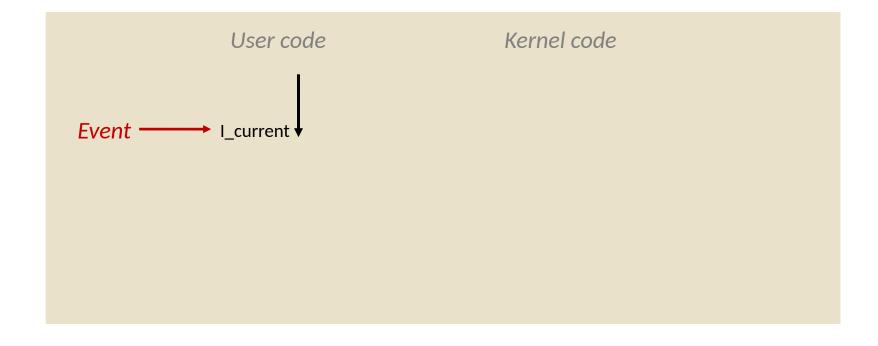
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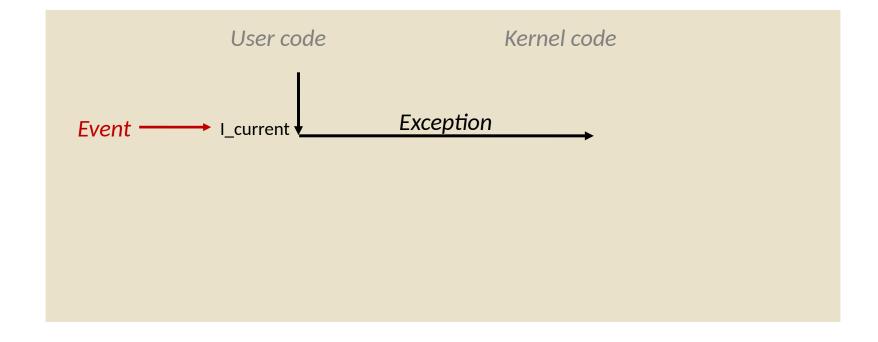


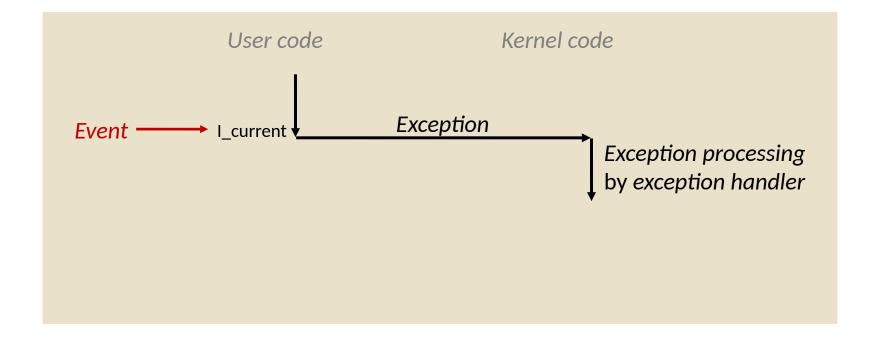
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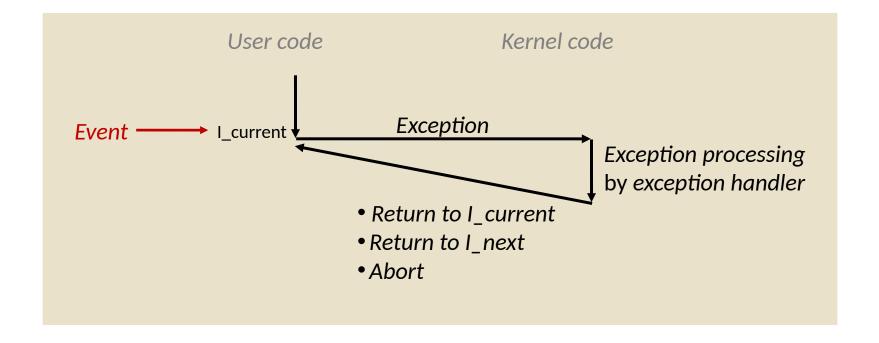


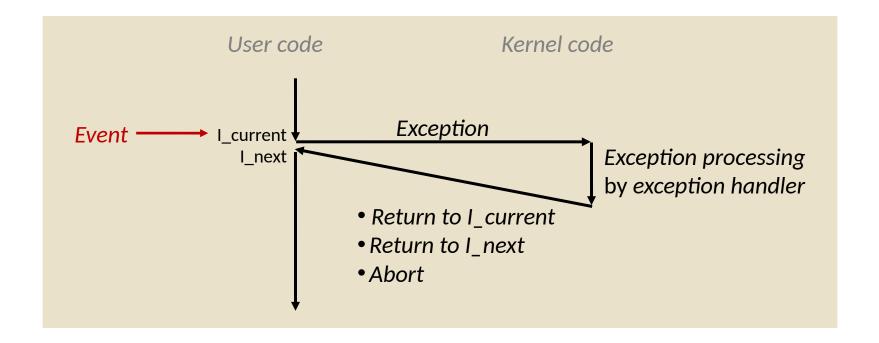




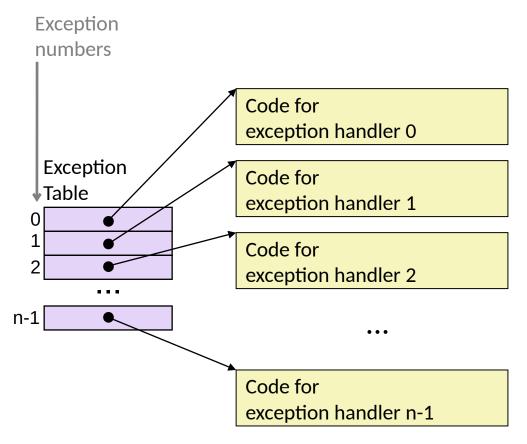








Exception Tables



- Each type of event has a unique exception number k
- k = index into exception table (a.k.a. interrupt vector)
- Handler k is called each time exception k occurs

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• Faults

- Unintentional but possibly recoverable
- Examples: page faults (recoverable), protection faults (unrecoverable), floating point exceptions
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Aborts

- Unintentional and unrecoverable
- Examples: illegal instruction, divide-by-zero, parity error, machine check
- Aborts current program

Interrupts (Asynchronous Exceptions)

Caused by events external to the process

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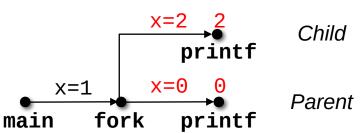
Examples:

- Timer interrupt
 - Every few ms, an external timer chip triggers an interrupt
 - Used by the kernel to take back control from user programs
- I/O interrupt from external device
 - Hitting Ctrl-C at the keyboard
 - Arrival of a packet from a network
 - Arrival of data from a disk

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  pid t pid;
  int x = 1;
  pid = Fork();
  if (pid == 0) { /* Child */
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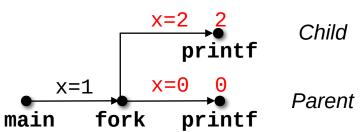
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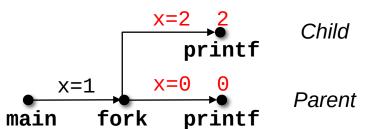
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 - X has a value of 1 when fork returns in parent and child
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- Shared open files
 - stdout is the same in both parent and child
- Concurrent execution
 - Can't predict execution order of parent and child

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         return 0;
  /* Parent */
  printf("parent: x = %d n", --x);
  return 0;
}
```



- Call once, return twice
- Duplicate but separate address space
 - X has a value of 1 when fork returns in parent and child
 - Subsequent changes to x are independent
- Shared open files
 - stdout is the same in both parent and child
- Concurrent execution
 - Can't predict execution order of parent and child

Exercise: What are all the possible outputs of this program?

Modeling fork with Process Graphs

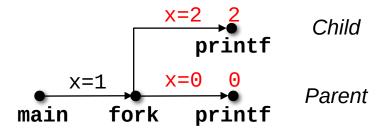
- A process graph is a useful tool for capturing the partial ordering of statements in a concurrent program:
 - Each vertex is the execution of a statement.
 - a -> b means a happens before b
 - Edges can be labeled with current value of variables
 - printf vertices can be labeled with output
 - Each graph begins with a vertex with no inedges

Modeling fork with Process Graphs

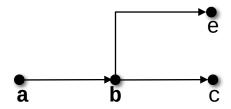
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 - Each graph begins with a vertex with no inedges
- Any topological sort of the graph corresponds to a feasible total ordering.
 - Total ordering of vertices where all edges point from left to right

Interpreting Process Graphs

Original graph:

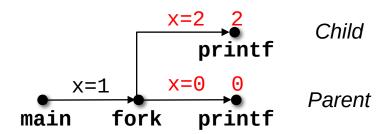


Relabeled graph:

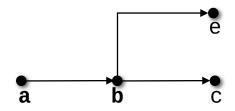


Interpreting Process Graphs

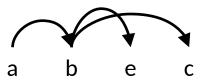
Original graph:



Relabeled graph:

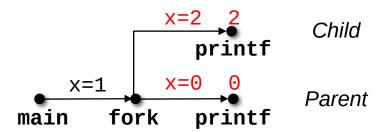


Feasible total ordering:

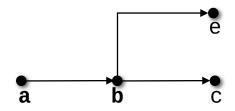


Interpreting Process Graphs

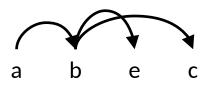
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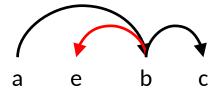
Relabeled graph:



Feasible total ordering:



Infeasible total ordering:



fork Example: Two consecutive forks

```
void fork1()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
```

fork Example: Two consecutive forks

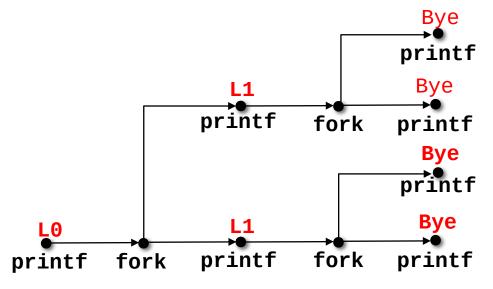
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void fork1()
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    printf("L0\n");
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    fork();
    printf("Bye\n");
}
```

Which of these outputs are feasible?

LO
L1
Bye
Bye
L1
Bye
L1
L1
Bye
Bye
Bye
Bye

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Which of these outputs are feasible?

LO	LO
L1	Bye
Bye	L1
Bye	Bye
L1	L1
Bye	Bye
Bye	Bye

Exercise: Forks and Feasible Schedules

 For each of the following programs, draw the process graph and then determine which of the possible outputs are feasible

Exercise: Forks and Feasible Schedules

 For each of the following programs, draw the process graph and then determine which of the possible outputs are feasible

```
void fork2(){
   printf("L0\n");
   if (fork() != 0) {
     printf("L1\n");
     if (fork() != 0) {
        printf("L2\n");
   printf("Bye\n");
    LO
                           LO
    11
                           Bye
     Bye
                           L1
     Bye
                           Bye
     L2
                           Bye
```

Bye

L2

Exercise: Forks and Feasible Schedules

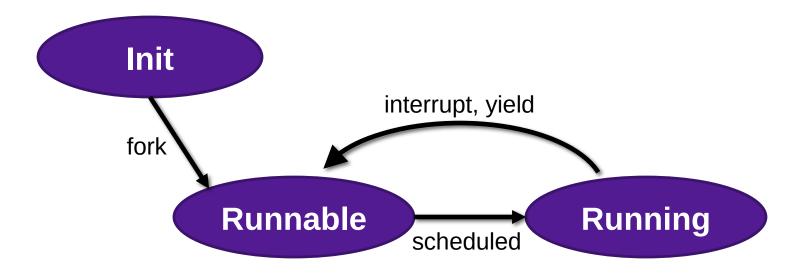
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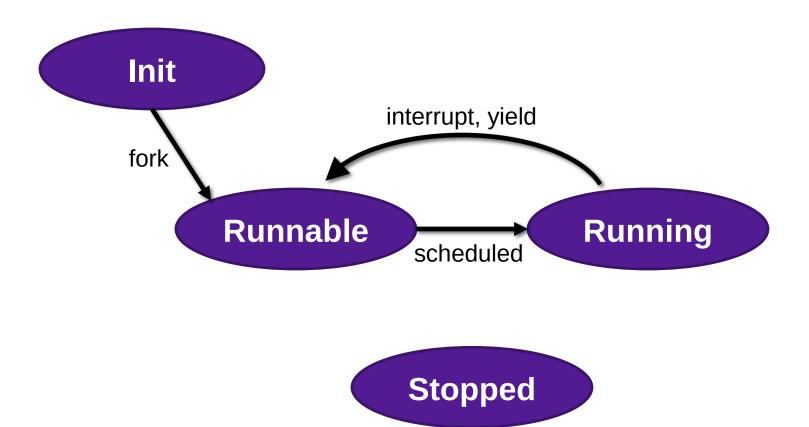
```
void fork2(){
    printf("L0\n");
    if (fork() != 0) {
        printf("L1\n");
        if (fork() != 0) {
            printf("L2\n");
            }
        printf("Bye\n");
    }
```

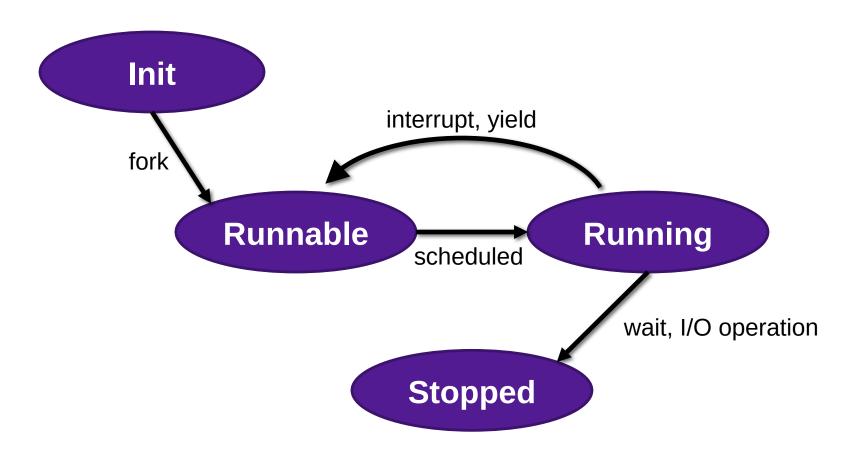
```
LO
L1
Bye
Bye
L1
Bye
L2
Bye
L2
Bye
L2
```

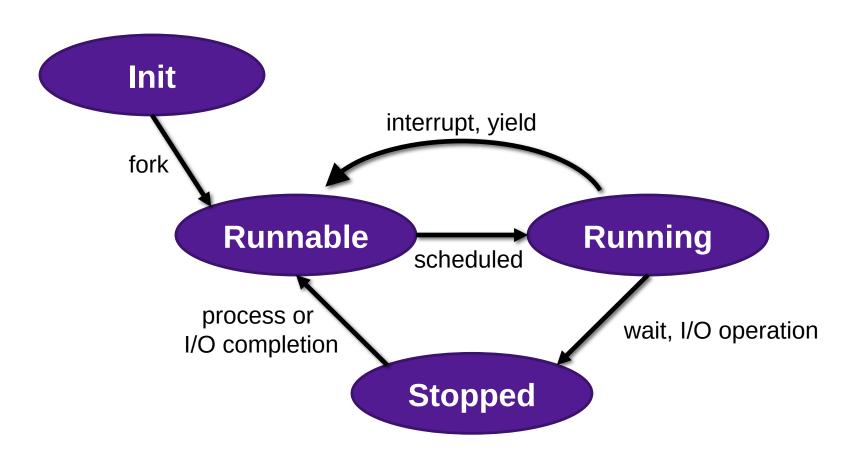
```
void fork3(){
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork() == 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
```

```
LO LO
Bye Bye
L1 L1
L2 Bye
Bye Bye
Bye
```









Reaping Children

Reaping

- Performed by parent on terminated child (using wait or waitpid)
- Parent is given exit status information
- Kernel then deletes zombie child process

int wait(int* child_status)

- Suspends current process until any one of its children terminates
- Return value is the pid of the child process that terminated
- If **child_status** != **NULL**, then the integer it points to will be set to a value that indicates reason the child terminated and the exit status

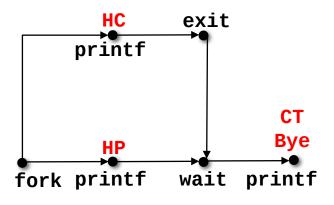
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 - If **child_status** != **NULL**, then the integer it points to will be set to a value that indicates reason the child terminated and the exit status
- •int waitpid(pid_t pid, int* child_status, int
 opt)
 - Suspends current process child with pid terminates

wait Example

```
void fork6() {
  int child_status;

if (fork() == 0) {
    printf("HC: hello from child\n");
        exit(0);
} else {
    printf("HP: hello from parent\n");
    wait(&child_status);
    printf("CT: child has terminated\n");
}
printf("Bye\n");
}
```



Feasible output: Infeasible output:

HC HP

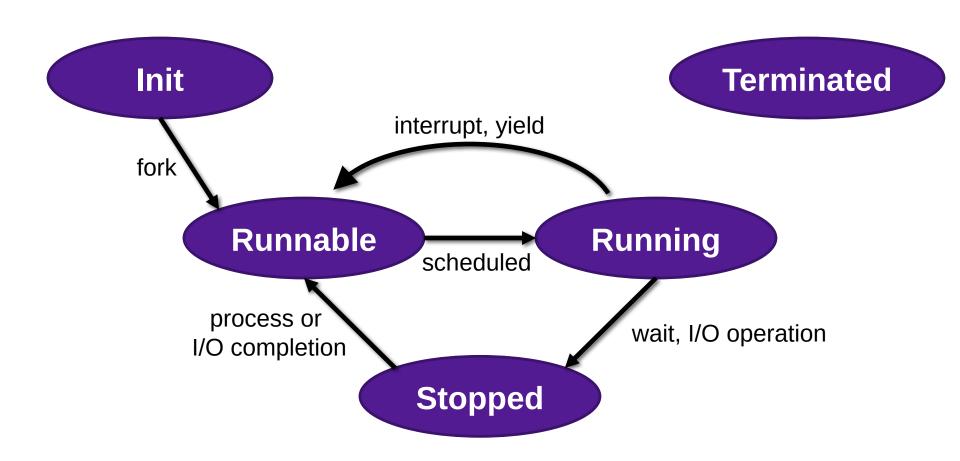
HP CT

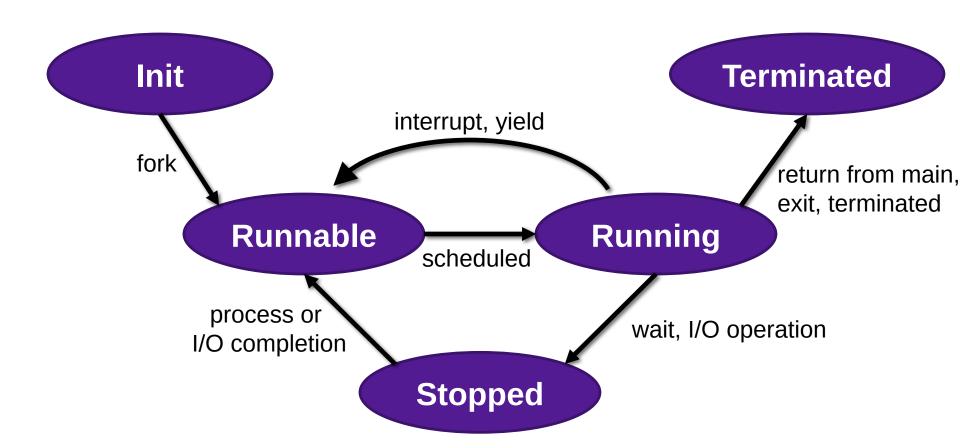
CT Bye

Bye HC

Reaping Children

- What if parent doesn't reap?
 - If any parent terminates without reaping a child, then the orphaned child will be reaped by init process (pid == 1)
 - So, only need explicit reaping in long-running processes
 - e.g., shells and servers





Terminating Processes

- Process becomes terminated for one of three reasons:
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 - Calling the exit function
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Terminating Processes

- Process becomes terminated for one of three reasons:
 - Returning from the main routine
 - Calling the exit function
 - Receiving a signal whose default action is to terminate
- void exit(int status)
 - Terminates with an exit status of status
 - Convention: normal return status is 0, nonzero on error
 - Another way to explicitly set the exit status is to return an integer value from the main routine
- exit is called once but never returns.