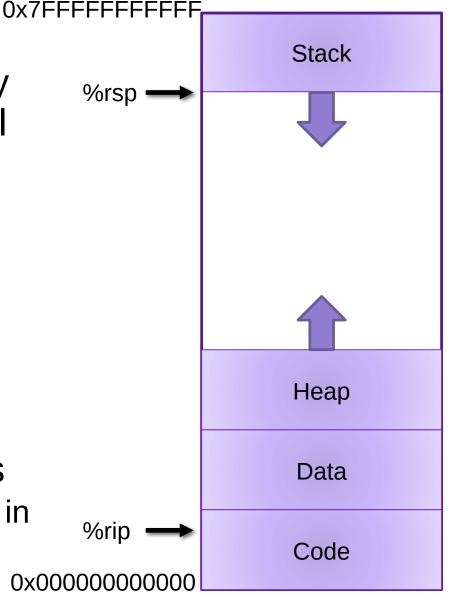
Lecture 14: Dynamic Memory

CS 105 Fall 2025

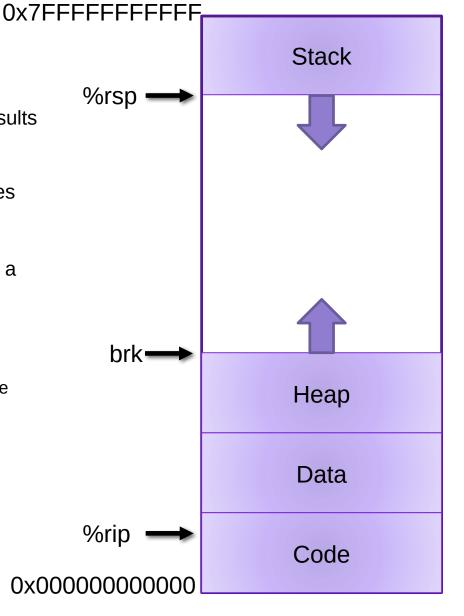
Memory

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 - "top" of the stack stored in register %rsp
- heap is an area of memory maintained by a dynamic memory allocator
 - operating system maintains variable brk that points to the top of heap
 - program can dynamically allocate/deallocate heap memory
 - program can use system call sbrk() to change size of heap
- data stores global variables
- code stores program instructions



Dynamic memory allocator

- Manages the heap
 - organizes the heap as a collection of (variable-size) blocks, each of which is either allocated or free
 - allocates and deallocates memory
 - may ask OS for additional heap space using system call sbrk()
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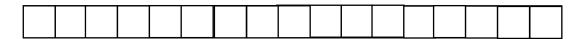
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Example dynamic memory allocators

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- new and delete in C++ explicit allocators
- object creation & garbage collection in Java
- object creation & garbage collection in Python implicit allocators

Allocation Example using malloc

```
#include <stdio.h>
#include <stdlib.h>
void foo(int n) {
    /* Allocate a block of n ints */
    int* p = (int*) malloc(n * sizeof(int));
    if (p == NULL) {
        perror("malloc");
        exit(0);
    /* Initialize allocated block */
    for (int i=0; i<n; i++) {
           p[i] = i;
    /* Return allocated block to the heap */
    free(p);
```

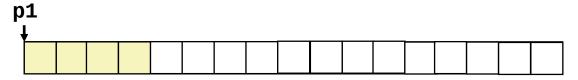




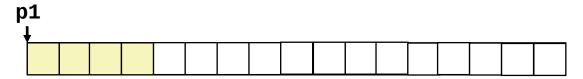


Assume each diagram block depicts 4 bytes

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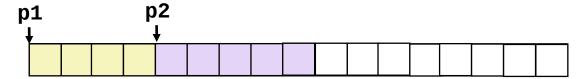


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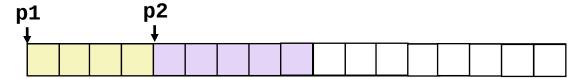
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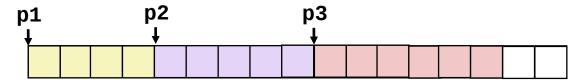
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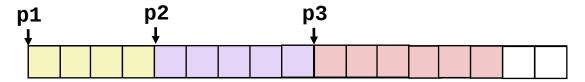
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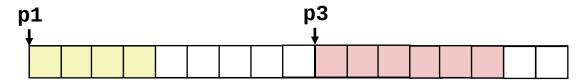
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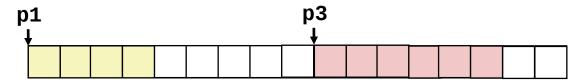
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free(p2)

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5) Must only use the heap:

any data structures used by the allocator must be stored in the heap

First Example: A Simple Allocator

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void* malloc (size_t size) {
  return sbrk(align(size));
}

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Advantages

- Simple
- Blazing fast

Disadvantages

- Memory is never recycled
- Wastes a lot of space

Allocator Goals

•

- Throughput: number of requests completed per time unit
 - Make allocator efficient
 - Example: if your allocator processes 5,000 malloc calls and 5,000 free calls in 10 seconds then throughput is 1,000 operations/second
- Memory Utilization: fraction of heap memory allocated
 - Minimize wasted space
 - Peak Memory Utilization $U_t = \frac{\max\limits_{i \leq t} space \ allocated \ at \ time \ i}{size \ of \ heap \ at \ time \ t}$
- These goals are often conflicting

- What is the Peak Memory Utilization at time t = 2?
- What is the Peak Memory Utilization at time t = 5?

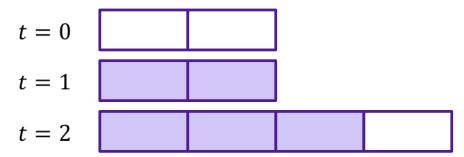
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```
t = 0
```

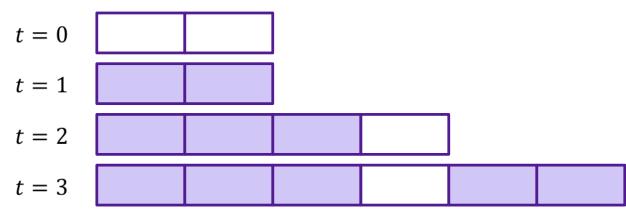
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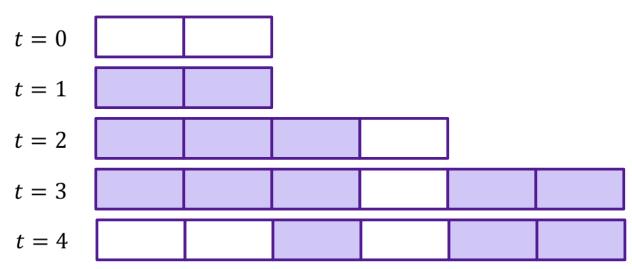
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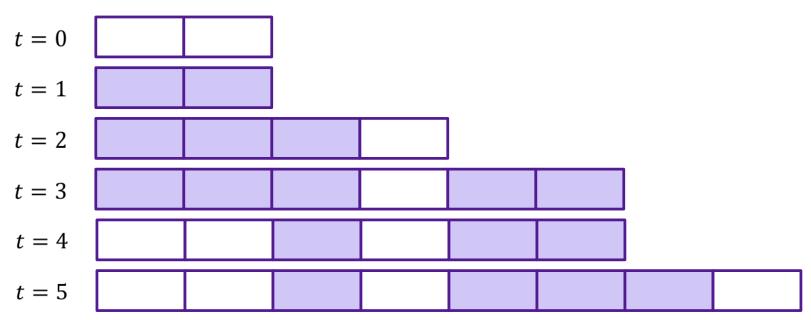
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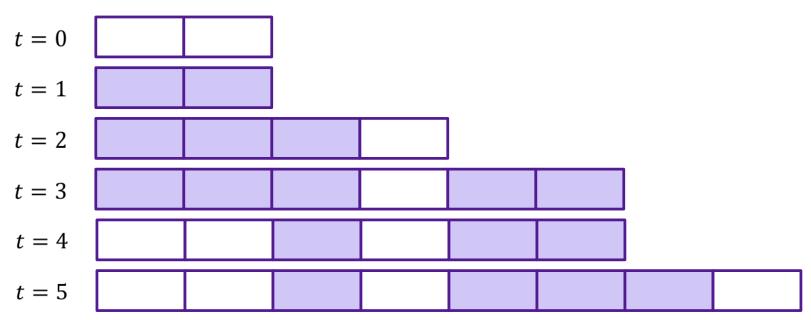
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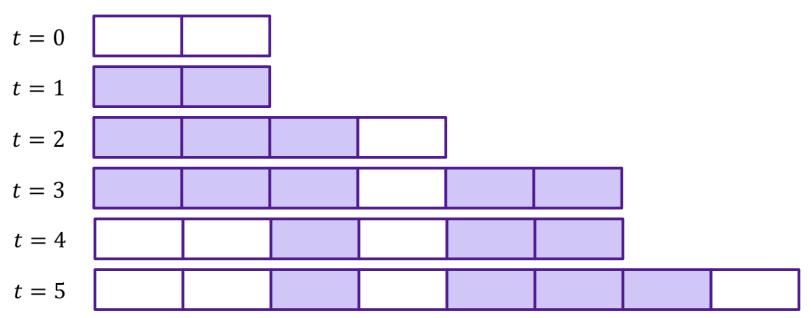
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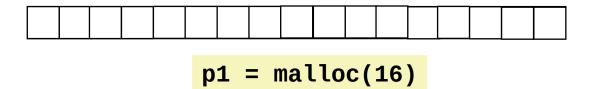
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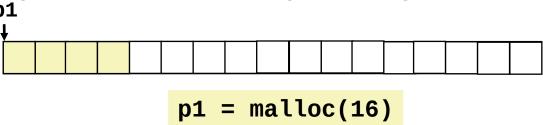


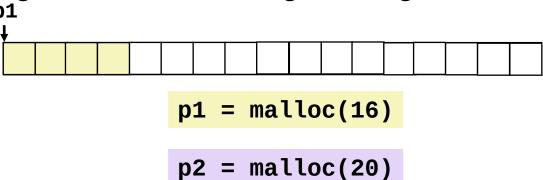
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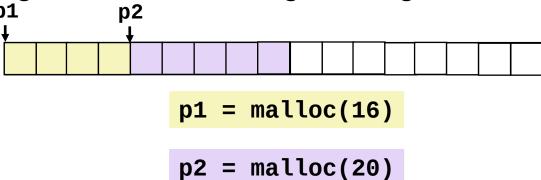


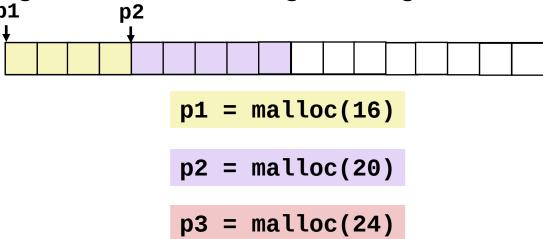


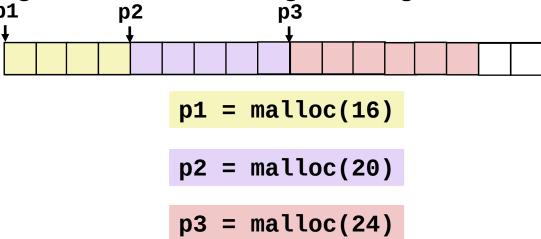


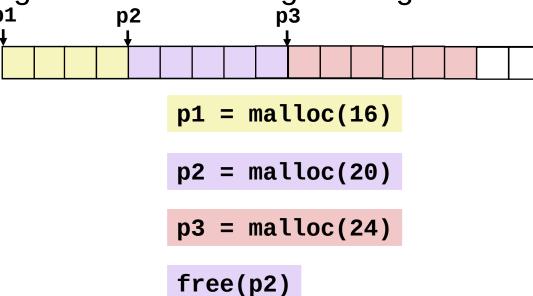


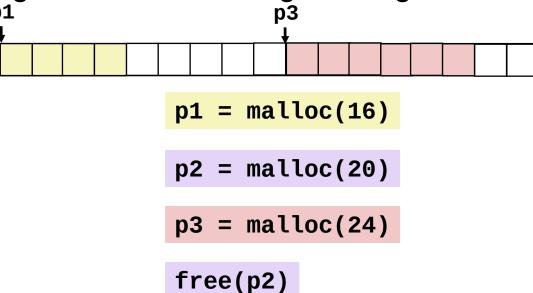


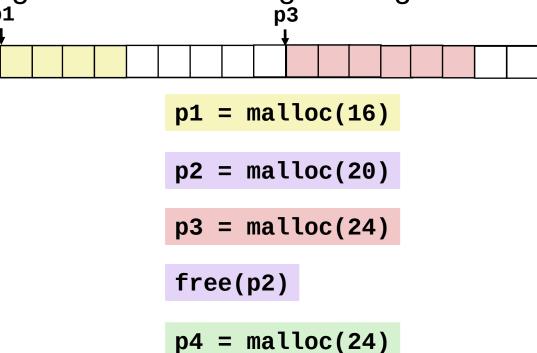


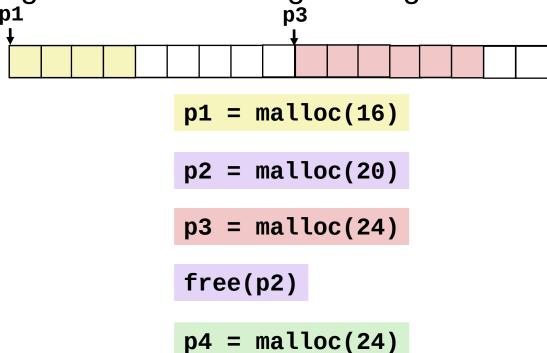






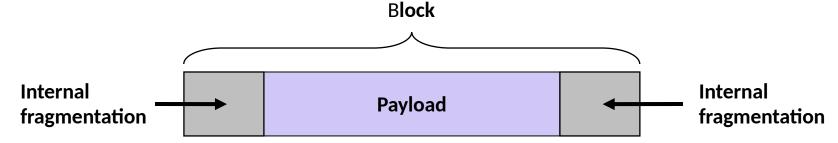






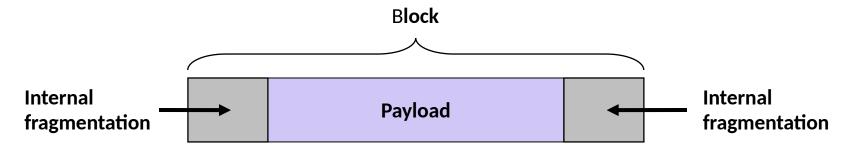
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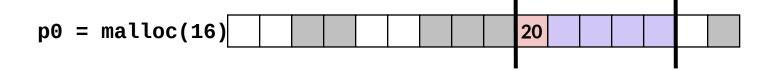
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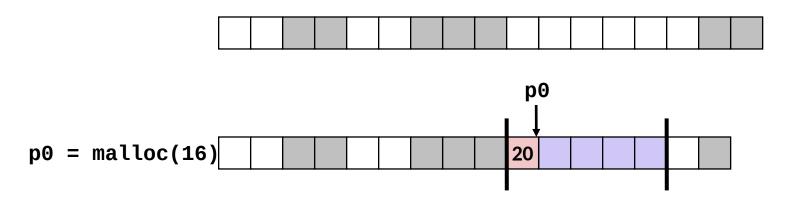


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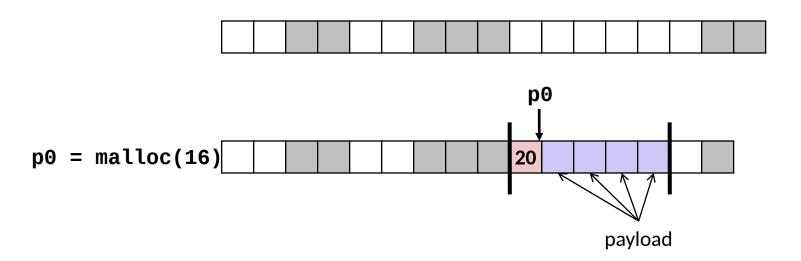




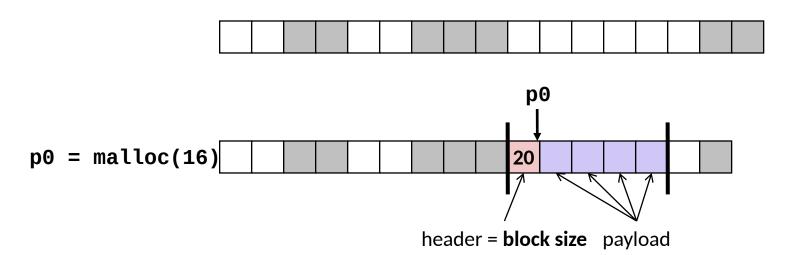
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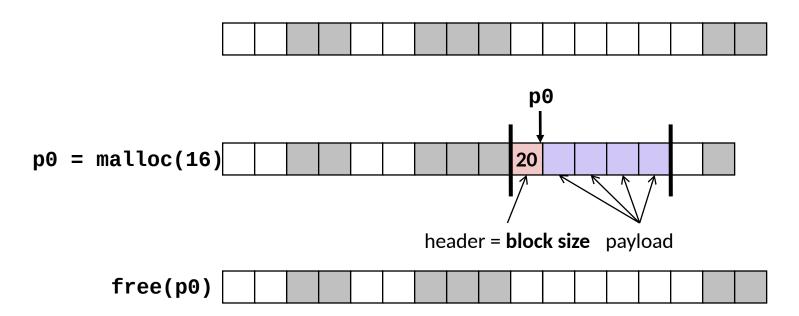
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Keeping Track of Free Blocks

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Method 1: Implicit List

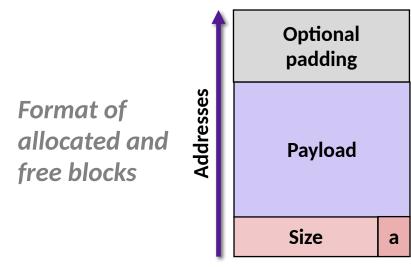
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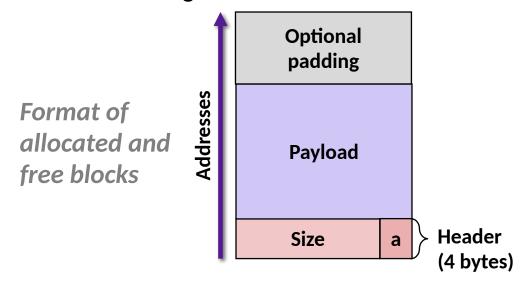
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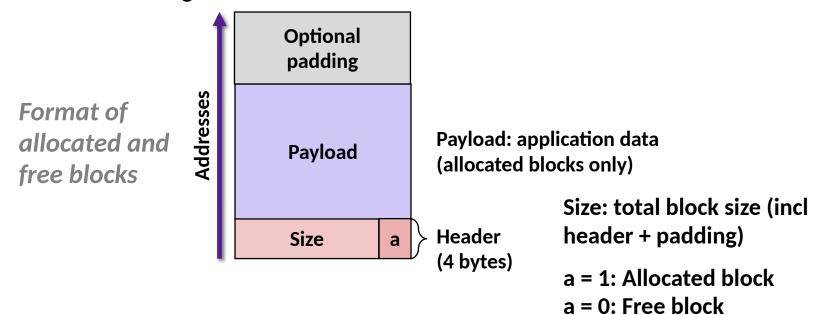
Size: total block size (incl header + padding)

a = 1: Allocated block

a = 0: Free block

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Method 1: Implicit list using length—links all blocks



Allocated blocks: shaded

Free blocks: unshaded

Headers: labeled with size in bytes/allocated bit

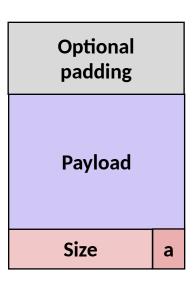
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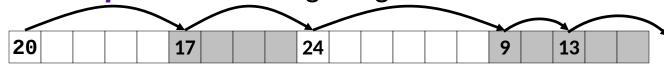


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		Header <	Size a

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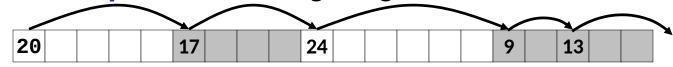


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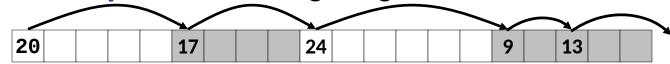
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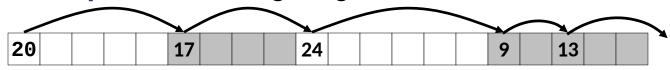
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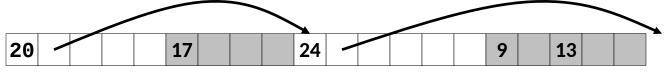


- Method 3: Segregated free list
 - Different free lists for different size classes

Method 1: Implicit list using length—links all blocks



Method 2: Explicit list among the free blocks using pointers



- Method 3: Segregated free list
 - Different free lists for different size classes
- Method 4: Blocks sorted by size
 - Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

Challenges

- Goal: maximize throughput and peak memory utilization
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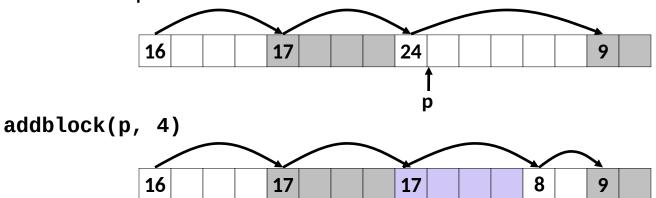
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 - Should often be faster than first fit: avoids re-scanning unhelpful blocks
 - Some research suggests that fragmentation is worse
- **Best fit.** Search the list, choose the best free block: fits, with fewest bytes left over:
 - Keeps fragments small—usually improves memory utilization
 - Will typically run slower than first fit

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Implicit List: Allocating in Free Block

- Allocating in a free block: splitting
 - Since allocated space might be smaller than free space, we might want to split the block



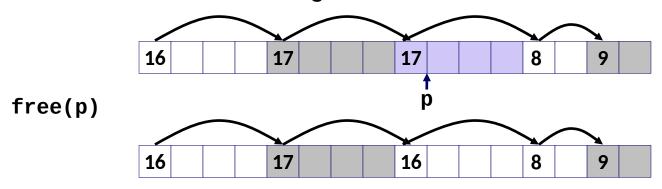
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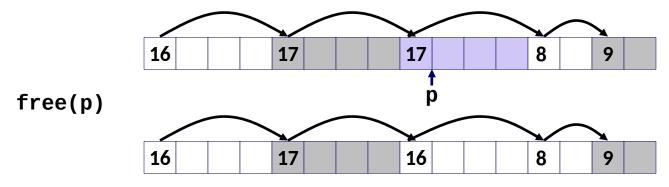
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 - Need only clear the "allocated" flag

```
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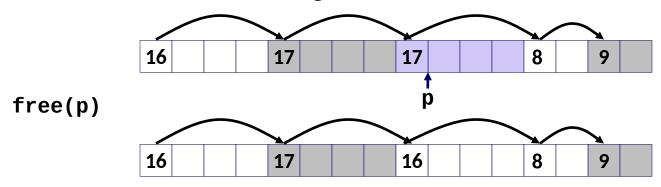


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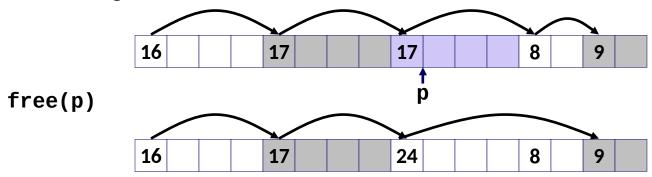


malloc(20) Oops!

There is enough free space, but the allocator won't be able to find it

Implicit List: Coalescing

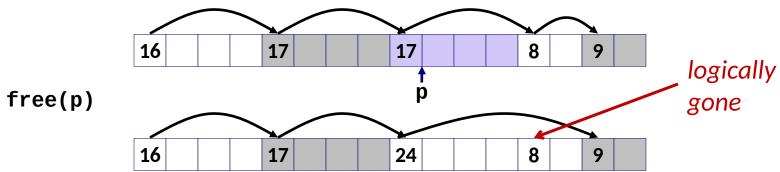
- Join *(coalesce)* with next/previous blocks, if they are free
 - Coalescing with next block



But how do we coalesce with previous block?

Implicit List: Coalescing

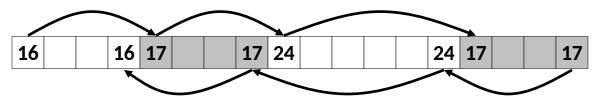
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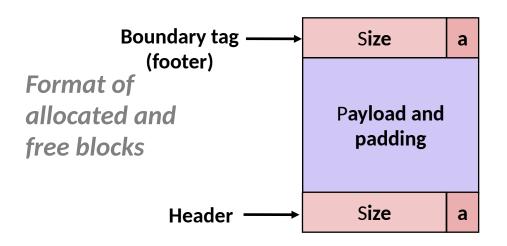


But how do we coalesce with previous block?

Implicit List: Bidirectional Coalescing

- Boundary tags [Knuth73]
 - Replicate size/allocated word at "bottom" (end) of free blocks
 - Allows us to traverse the "list" backwards, but requires extra space
 - Important and general technique!





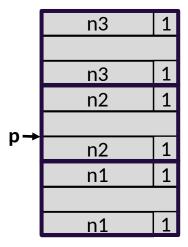
a = 1: Allocated block

a = 0: Free block

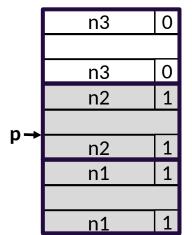
Size: Total block size

Payload: Application data (allocated blocks only)

Case 1: Prev and next block allocated



Case 2: Prev block allocated, next block free



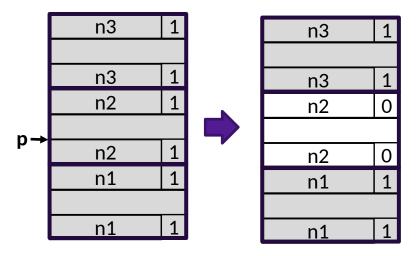
Case 2: Prev block free, next block allocated

	n3	1
	n3	1
	n2	1
p→	n2	1
	n1	0
	n1	0

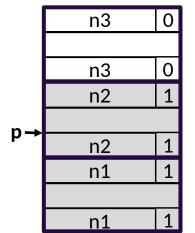
Case 4: Prev and next block free

n3	0
n3	0
n2	1
 n2	1
n1	0
n1	0

Case 1: Prev and next block allocated



Case 2: Prev block allocated, next block free



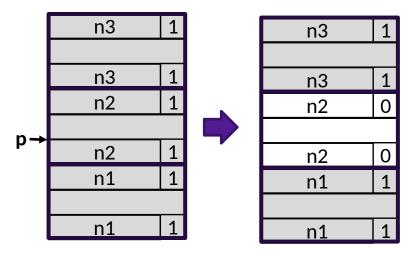
Case 2: Prev block free, next block allocated

	n3	1
	n3	1
	n2	1
<u>,</u> ,		
p→	n2	1
	n1	0
	n1	0
•	n1	0

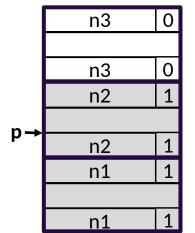
Case 4: Prev and next block free

n3	0
n3	0
n2	0
 n2	1
n1	0
n1	0

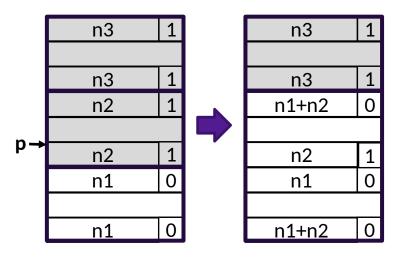
Case 1: Prev and next block allocated



Case 2: Prev block allocated, next block free



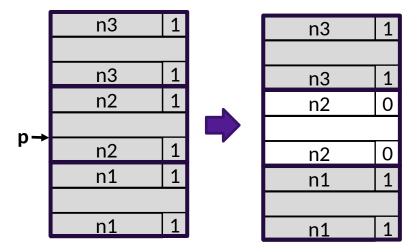
Case 2: Prev block free, next block allocated



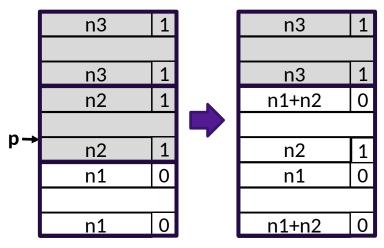
Case 4: Prev and next block free

	n3	0
	n3	0
	n2	1
.		
- v	n2	1
	n1	0
	n1	0

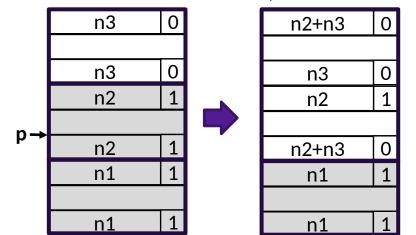
Case 1: Prev and next block allocated



Case 2: Prev block free, next block allocated



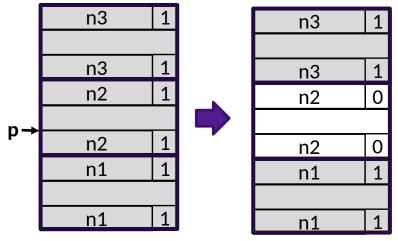
Case 2: Prev block allocated, next block free



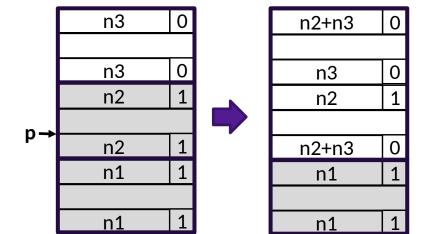
Case 4: Prev and next block free

	n3	0
	n3	0
	n2	0
<u>م</u> ـــ ۸		
y —	n2	1
	n1	0
	n1	0

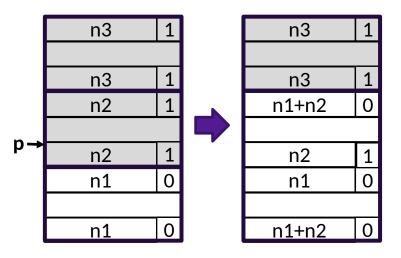
Case 1: Prev and next block allocated



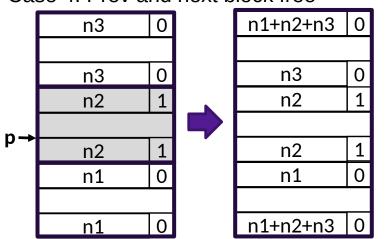
Case 2: Prev block allocated, next block free



Case 2: Prev block free, next block allocated



Case 4: Prev and next block free



Exercise: Coalescing

• Assume the current heap is shown below. What would be the state of the heap after the function free (0x118) is

executed?

0 100	0x000000c
0x128	0x0000047
0x124	0x0000000c
0x120	0x000000d
0x11c	0xc0ffee24
0x118	0x000000d
0x114	0x0000011
0x110	0x5ca1ab1e
0x10c	0x000000d
0x108	0x0000011
0x104	0x000000d
0x100'	

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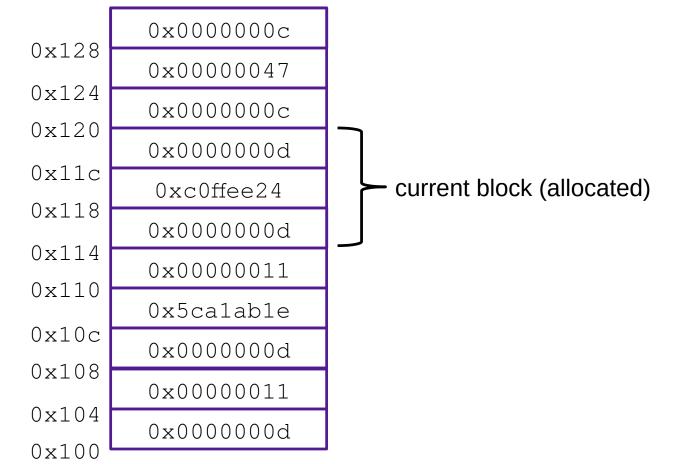
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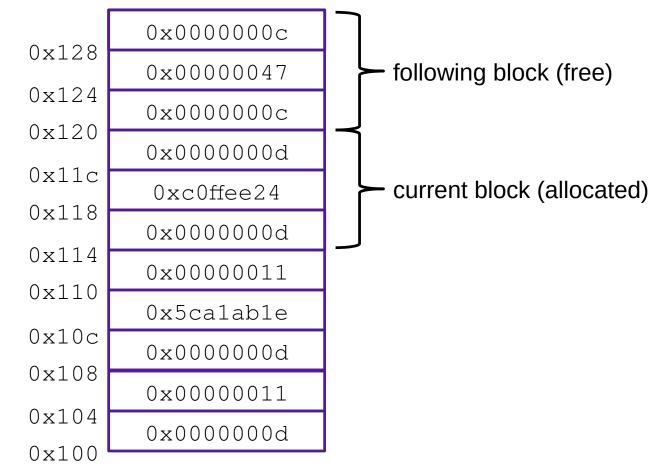
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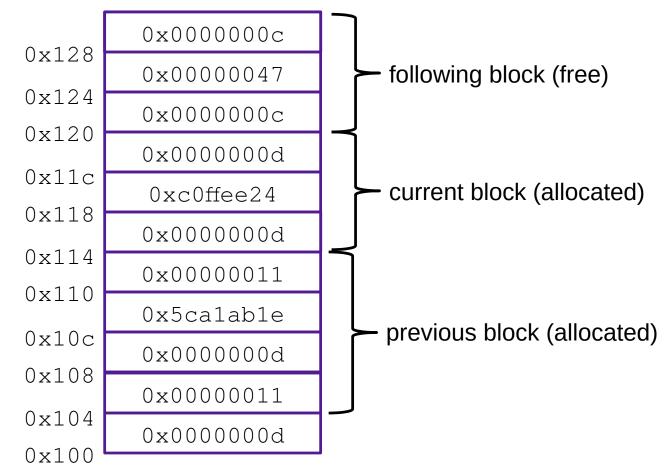
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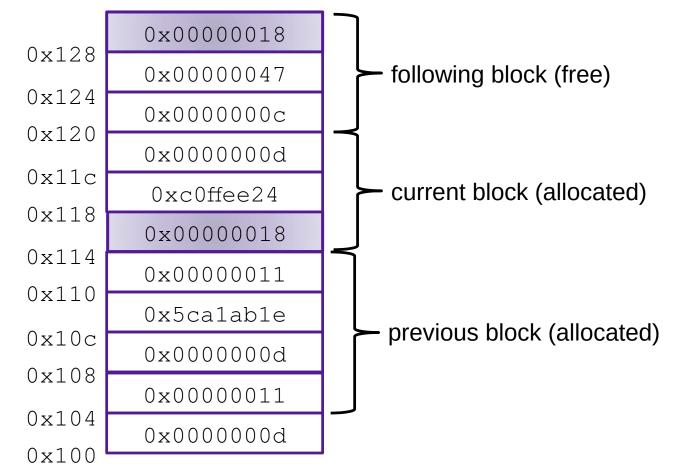
executed?



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- Free-block storage policy:
 - Implicit lists, with boundary tags (nice and simple)
 - Explicit lists, exclude free blocks (faster, but more overhead)
 - Segregated lists (different lists for different sized blocks)
 - Fancy data structures (red-black trees, for example)

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- Splitting policy:
 - When do we go ahead and split free blocks?
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- Coalescing policy:
 - No coalescing (bad choice)
 - Immediate coalescing: coalesce each time free is called
 - Deferred coalescing: coalesce on allocate or after fixed time

- Dereferencing bad pointers
- Reading uninitialized memory
- Overreading memory
- Overwriting memory
- Referencing freed blocks
- Freeing blocks multiple times
- Failing to free blocks

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