

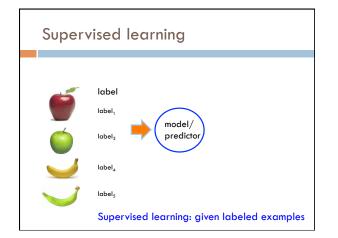
Administrative

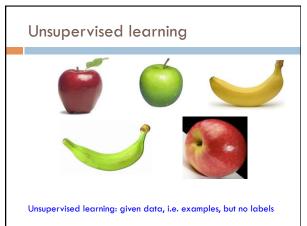
Final project

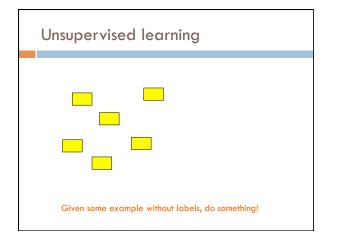
- Nice work forming groups ⁽²⁾
- Status report due tomorrow (Wednesday)
- In-class presentation next Tuesday

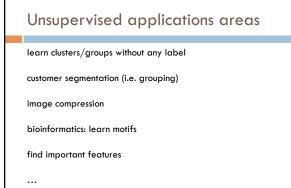
Midterm

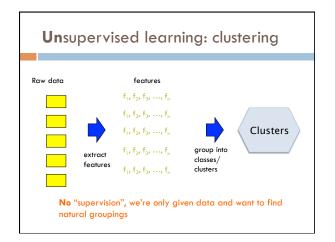
Grading

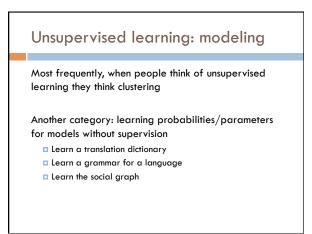






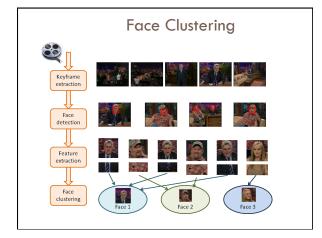


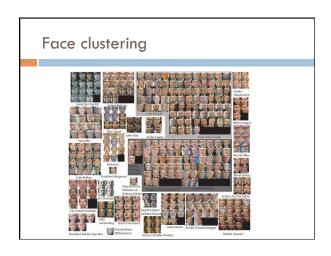




Clustering Clustering: the process of grouping a set of objects into classes of similar objects Applications?

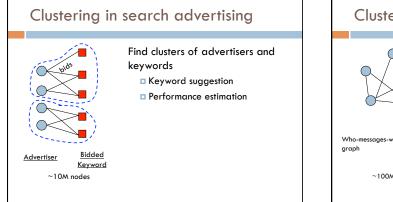


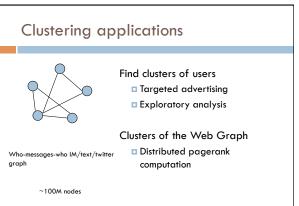


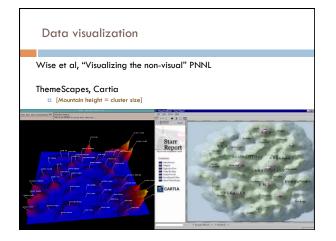


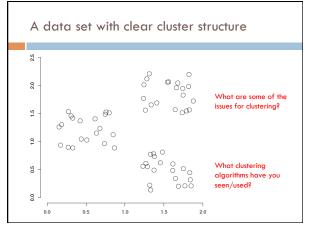
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Issues for clustering

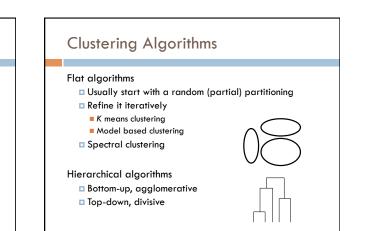
Representation for clustering

- How do we represent an example
 - features, etc.
- Similarity/distance between examples

Flat clustering or hierarchical

Number of clusters

- Fixed a priori
- Data driven?



Hard vs. soft clustering

Hard clustering: Each example belongs to exactly one cluster

Soft clustering: An example can belong to more than one cluster (probabilistic)

Makes more sense for applications like creating browsable hierarchies
 You may want to put a pair of sneakers in two clusters: (i) sports apparel and (ii) shoes

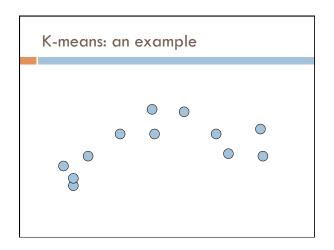
K-means

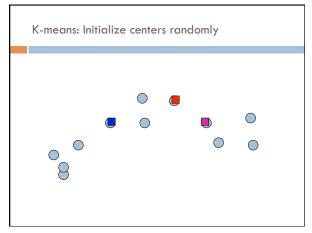
Most well-known and popular clustering algorithm:

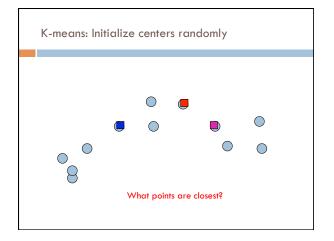
Start with some initial cluster centers

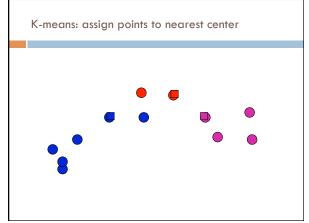
lterate:

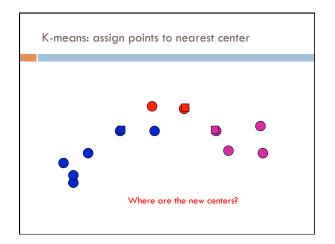
- Assign/cluster each example to closest center
- Recalculate centers as the mean of the points in a cluster

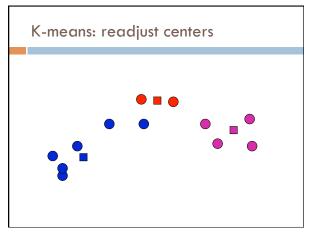




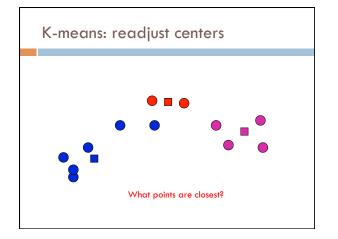


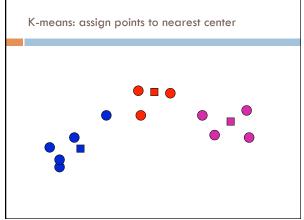


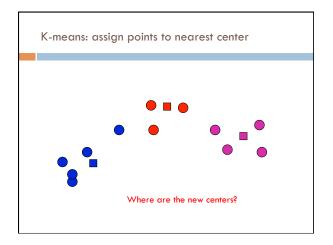


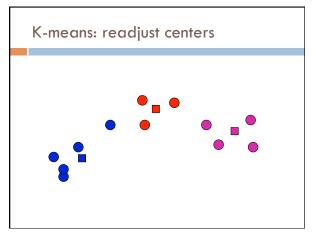


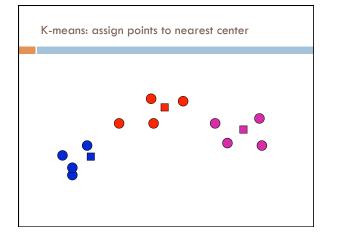
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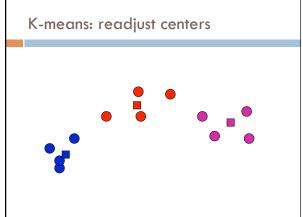


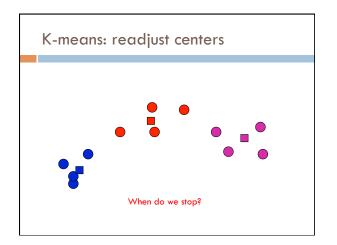


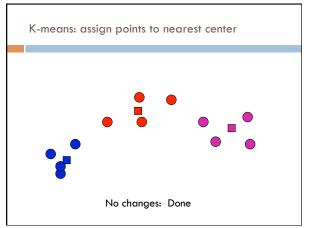


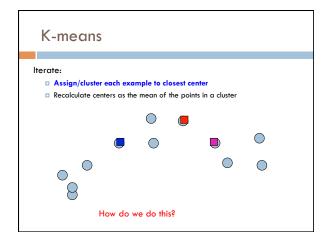


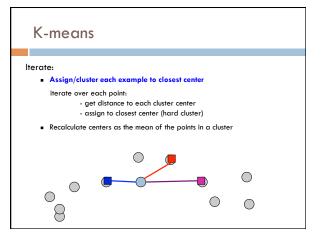


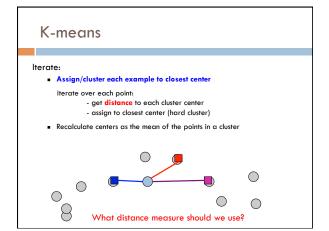


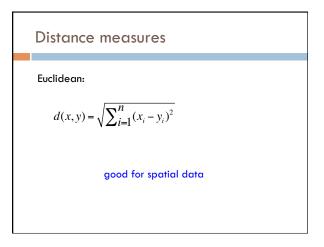


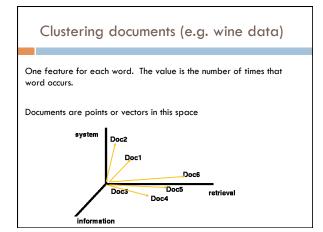


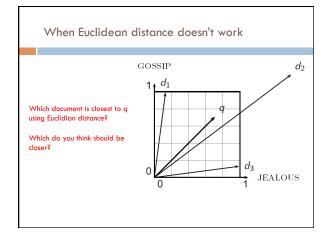


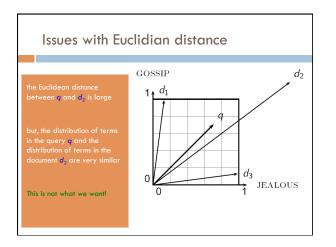


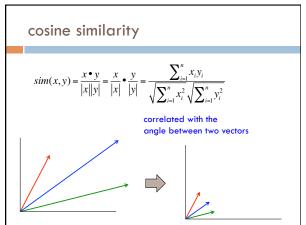


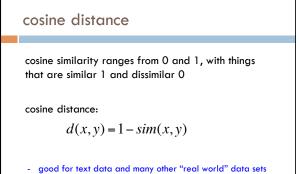




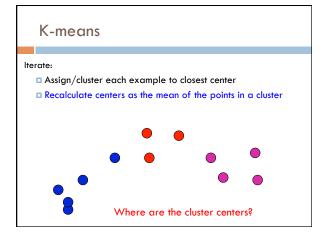


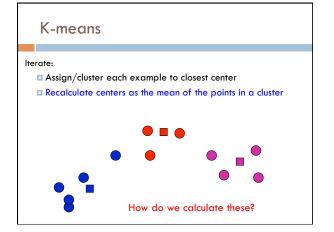


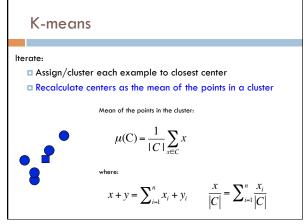




 good for her duit and many oner real world duit sets
 computationally friendly since we only need to consider features that have non-zero values for **both** examples







K-means loss function

K-means tries to minimize what is called the "k-means" loss function:

 $loss = \sum_{i=1}^{n} d(x_i, \mu_k)^2$ where μ_k is cluster center for x_i

the sum of the squared distances from each point to the associated cluster center

Minimizing k-means loss

lterate:

Assign/cluster each example to closest center
 Recalculate centers as the mean of the points in a cluster

$$loss = \sum_{i=1}^{n} d(x_i, \mu_k)^2$$
 where μ_k is cluster center for x_i

Does each step of k-means move towards reducing this loss function (or at least not increasing it)?

Minimizing k-means loss

lterate:

Assign/cluster each example to closest center
 Recalculate centers as the mean of the points in a cluster

 $loss = \sum_{i=1}^{n} d(x_i, \mu_k)^2$ where μ_k is cluster center for x_i

This isn't quite a complete proof/argument, but:

- 1. Any other assignment would end up in a larger loss
- 2. The mean of a set of values minimizes the squared error

Minimizing k-means loss

lterate:

Assign/cluster each example to closest center
 Recalculate centers as the mean of the points in a cluster

 $loss = \sum_{k=1}^{n} d(x_i, \mu_k)^2$ where μ_k is cluster center for x_i

Does this mean that k-means will always find the minimum loss/clustering?

Minimizing k-means loss

lterate:

Assign/cluster each example to closest center
 Recalculate centers as the mean of the points in a cluster

 $loss = \sum_{i=1}^{n} d(x_i, \mu_k)^2$ where μ_k is cluster center for x_i

NO! It will find a minimum.

Unfortunately, the k-means loss function is generally not convex and for most problems has many, many minima

We're only guaranteed to find one of them

K-means variations/parameters

Start with some initial cluster centers

Iterate:

- Assign/cluster each example to closest center
- Recalculate centers as the mean of the points in a cluster

What are some other variations/ parameters we haven't specified?

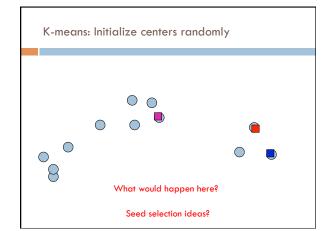
K-means variations/parameters

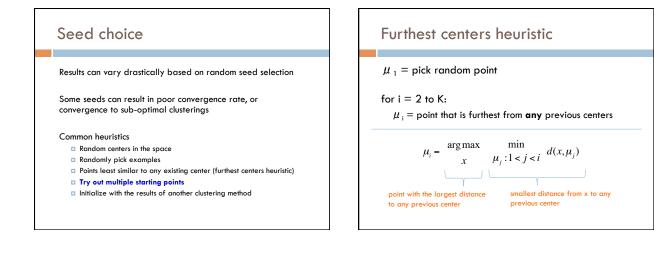
Initial (seed) cluster centers

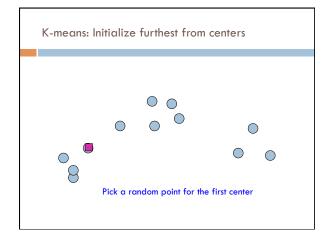
Convergence

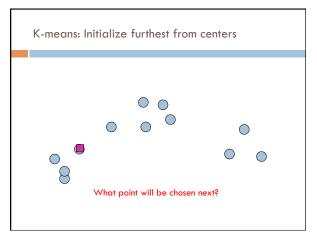
- A fixed number of iterations
- partitions unchanged
- Cluster centers don't change

K!

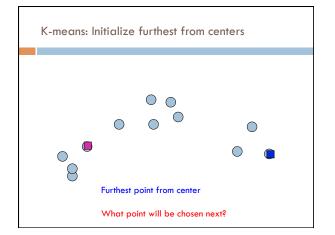


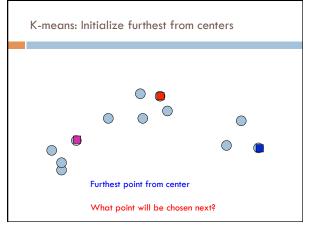


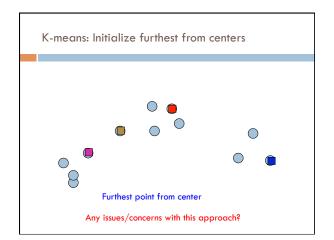


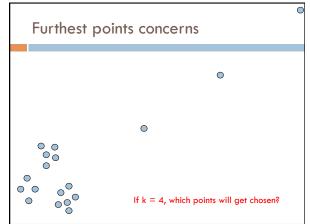


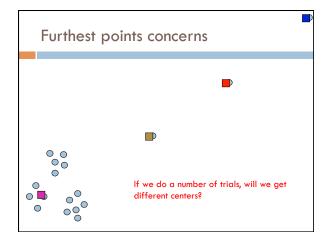
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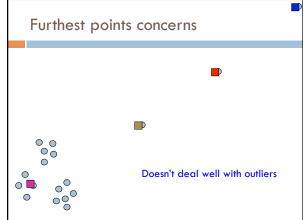












K-means++

 $\mu_1 = pick random point$

for k = 2 to K: for i = 1 to N: $s_i = \min d(x_{\mu} \mid \mu_{1...k\cdot 1}) \mid // \text{ smallest distance to any center}$

 $\mu_{\rm k}$ = randomly pick point **proportionate** to s

How does this help?



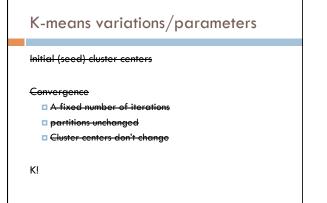
for k = 2 to **K**:

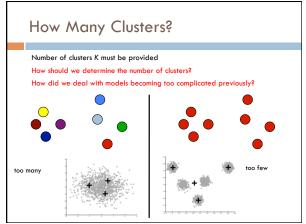
for i = 1 to N:

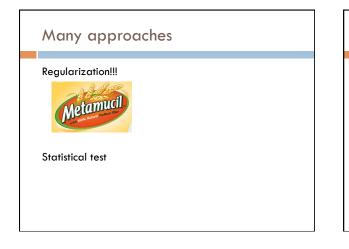
 ${\rm s_i} = \min \, {\rm d}({\rm x_{i'}} \, \, \mu_{1 \ldots k\text{-}1}) \; // \; {\rm smallest} \; {\rm distance} \; {\rm to} \; {\rm any} \; {\rm center}$

 $\mu_{\rm k}$ = randomly pick point **proportionate** to s

- Makes it possible to select other points
 if #points >> #outliers, we will pick good points
- Makes it non-deterministic, which will help with random runs
- Nice theoretical guarantees!





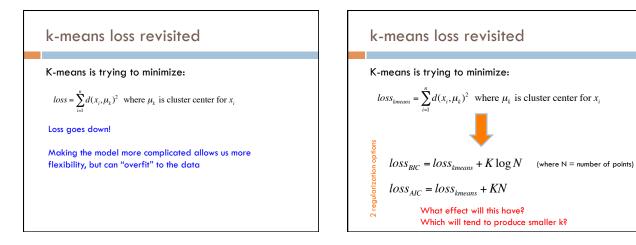


k-means loss revisited

K-means is trying to minimize:

 $loss = \sum_{i=1}^{n} d(x_i, \mu_k)^2$ where μ_k is cluster center for x_i

What happens when k increases?



k-means loss revisited

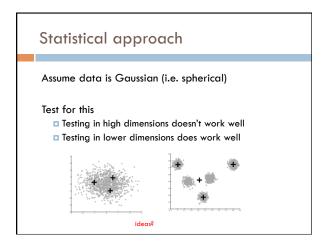
 $loss_{BIC} = loss_{kmeans} + K \log N$ (where N = number of points)

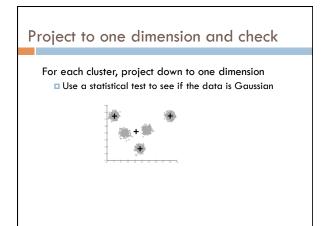
 $loss_{AIC} = loss_{kmeans} + KN$

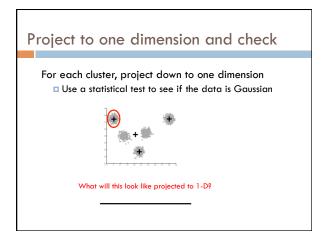
AIC penalizes increases in K more harshly

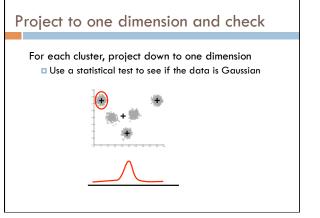
Both require a change to the K-means algorithm

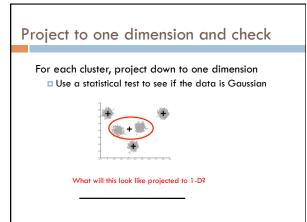
Tend to work reasonably well in practice if you don't know K

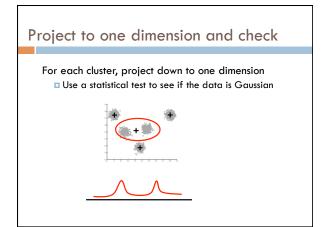


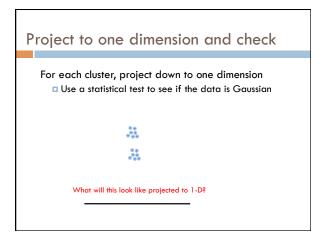


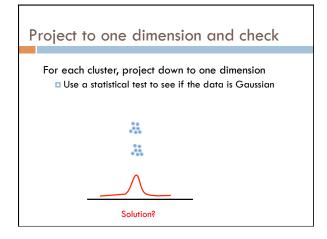


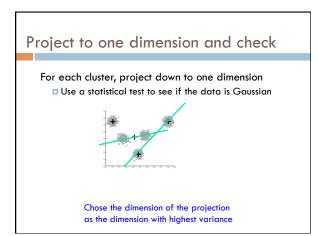


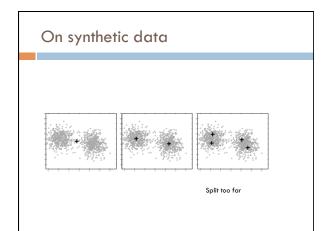


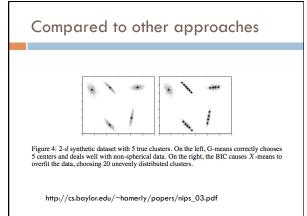












K-Means time complexity

Variables: K clusters, n data points, m features/dimensions, l iterations

What is the runtime complexity?

- Computing distance between two points (e.g. euclidean)
- Reassigning clusters
- Computing new centers
- Iterate...

K-Means time complexity

Variables: K clusters, n data points, m features/dimensions, l iterations

What is the runtime complexity?

- Computing distance between two points is O(m) where m is the
- dimensionality of the vectors/number of features.
- \blacksquare Reassigning clusters: O(Kn) distance computations, or O(Knm)
- Computing centroids: Each points gets added once to some centroid: O(nm)
- □ Assume these two steps are each done once for *l* iterations: O(*lknm*)

In practice, K-means converges quickly and is fairly fast