Quicksort

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• Quicksort

QUICKSORT(A, p, r)

1 if p < r $q \leftarrow \text{PARTITION}(A, p, r)$ QUICKSORT(A, p, q - 1)QUICKSORT(A, q + 1, r)

PARTITION(A, p, r)

 $\begin{array}{lll} 1 & i \leftarrow p-1 \\ 2 & \textbf{for } j \leftarrow p \textbf{ to } r-1 \\ 3 & \textbf{if } A[j] \leq A[r] \\ 4 & i \leftarrow i+1 \\ 5 & \text{swap } A[i] \text{ and } A[j] \\ 6 & \text{swap } A[i+1] \text{ and } A[r] \\ 7 & \textbf{return } i+1 \end{array}$

Loop invariant: Elements in the subarray A[p...i] are all less than or equal to A[r] and elements in the subarray A[i + 1...j - 1] are all greater than A[r]

Proof by induction: Base case: i = p - 1, so A[p...i] is empty and j = p and i + 1 = p, so A[i + 1...j - 1] is also empty.

Inductive case: We'll assume that the invariant is true for iteration j and show that iteration j + 1 is also true. There are two cases based on line the if statement in line 4.

⁻ Is it correct?

1. If A[j] > A[r] the only thing that happenens is that j is incremented. This means that A[p...i] remains unchanged and will still contain elements that are less than or equal to A[r]. A[i+1...j] will consist of A[i+1...j-1], which contains elements greater than A[r] (by induction), and one additionally element A[j] which we know is greater than A[r], so we know the entire subarray A[i+1...j] contains elements that are greater than A[r].

2. If $A[j] \leq A[r]$ then two things happen. *i* is incremented and A[i] is swapped with A[j]. A[p...i] will then contain the elements A[p...i-1], which we already know are less than or equal to A[r], and element A[j], which is also less than or equal to A[r]. Sub-array A[i+1...j] will contain the same elements, except the last element, A[j], will be the old first element, A[i+1], and the other elements will be shifted down.

At termination, what does this tell us about the PARTITION procedure?

If PARITION is correct, is QUICKSORT correct?

- Running time?

What is the running time of PARTITION?

Iterates over each element of the array and does at most a constant amount of work for each iteration: $\Theta(n)$

Runing time of QUICKSORT

* Worst case: Array is sorted (or reverse sorted) and each call to partition subdivides the array into a subarray of length n-1 and a subarray of length 0.

Draw the tree

$$T(n) = T(n-1) + T(0) + \Theta(n)$$

= $T(n-1) + \Theta(n)$

which we've seen before: $\Theta(n^2)$

* Best case: The partition algorithm splits the array into two equal (or nearly) equal halves, e.g. 11 elements into two subarrays of length 5 or 10 elements into a subarray of length 4 and a subarray of length 5.

Draw the tree

 $T(n) \le 2T(n/2) + \Theta(n)$

which we have also seen before with MERGE-SORT: $\Theta(n \log n)$

* Average case: Intuition 1 How balanced do the splits have to be to maintain the $\Theta(n \log n)$ running time?

Say the PARTITION procedure always splits the array into constant ratio b-to-a, e.g. 9-to-1.

$$T(n) \le T(\frac{a}{a+b}n) + T(\frac{b}{a+b}n) + cn$$

Recursion tree: Level 0: cnLevel 1: $cn(\frac{a}{a+b}) + cn(\frac{b}{a+b}) = cn$ Level 2: $cn(\frac{a^2}{(a+b)^2}) + cn(\frac{ab}{(a+b)^2}) + cn(\frac{ba}{(a+b)^2}) + cn(\frac{b^2}{(a+b)^2}) = cn\frac{a^2+2ab+b^2}{(a+b)^2} = cn$ Level 3 $cn(\frac{(a+b)^2a+(a+b)^2b}{(a+b)^3}) = cn\frac{(a+b)(a+b)^2}{(a+b)^3} = cn$ Level d: $cn\frac{(a+b)^d}{(a+b)^d} \le cn$

What is the depth of the tree? What is the minimum depth of the tree?

Assume a < b.

$$(\frac{a}{a+b})^d n = 1$$
$$\log(\frac{a}{a+b})^d n) = \log 1$$
$$\log n + \log(\frac{a}{a+b})^d = 0$$
$$\log n + d\log(\frac{a}{a+b}) = 0$$

$$d\log(\frac{a}{a+b}) = -\log n$$
$$d = \frac{-\log n}{\log(\frac{a}{a+b})}$$
$$d = \frac{\log n}{\log(\frac{a+b}{a})}$$
$$d = \log_{\frac{a+b}{a}} n$$

What is the maximum depth of the tree?

 $d = \log_{\frac{a+b}{b}} n$

Runtime: Each level has a cost of at most cn with maximum depth $d = \log_{\frac{a+b}{b}} n$: $O(n \log_{\frac{a+b}{b}} n)$

Why not $\Theta(n \log_{\frac{a+b}{b}} n)$?

 $\ast\,$ Average case: Intuition 2

What would happen if half the time PARTITION produced a "bad" split of parts sized 0 and n-1 and the other half of the time it produced a "good" split of equal sized parts?

Draw the trees for these two cases.

Cost for the 50/50: Partition cost = $\Theta(n)$ Recursion = $T(\frac{n-1}{2}) + T(\frac{n-1}{2})$

$$T(n) = 2T(\frac{n-1}{2}) + \Theta(n)$$

Cost of "bad" followed by 50/50: Partition cost = $\Theta(n) + \Theta(n-1) = \Theta(n)$ Recursion = $T(0) + T(\frac{(n-1)}{2} - 1) + T(\frac{n-1}{2})$

$$T(n) = T(\frac{n-1}{2} - 1) + T(\frac{n-1}{2}) + \Theta(n)$$

The cost of the "bad" partition is absorbed. In general, any constant number of "bad" partitions intermixed with "good" partitions will still results in $O(n \log n)$ runtime.

* RANDOMIZED-QUICKSORT

How can we avoid the worst case situation for QUICKSORT?

RANDOMIZED-PARTITION(A, p, r)

1 $i \leftarrow \text{RANDOM}(p, r)$

- 2 swap A[r] and A[i]
- 3 return PARTITION(A, p, r)
- * Analysis of RANDOMIZED-QUICKSORT: Expected running time

How many calls to PARTITION are made for an input of size n?

n - Each time a pivot element is selected and that element is never selected again.

What is the cost of an individual call to PARTITION? Proportional to the number of iterations of the **for** loop. Therefore, if we count the number of comparisons made (**if** $A[j] \leq A[r]$) then this is a bound on the running time of QUICKSORT.

Counting the number of comparisons:

Don't try and analyze each call, but analyze the global number of comparisons.

Let z_i of $z_1, z_2, ..., z_n$ be the *i*th smallest element and Z_{ij} be the set of elements $Z_{ij} = z_i, z_{i+1}, ..., z_j$ between z_i and z_j .

For example, if A = [3, 9, 7, 2] then, $z_1 = 2$, $z_2 = 3$, $z_3 = 7$, $z_4 = 9$ and $Z_{24} = \{3, 7, 9\}$.

Let $X_{ij} = I\{z_i \text{ is compared to } z_j\} = \begin{cases} 1 & \text{if } z_i \text{ is compared to } z_j \\ 0 & \text{otherwise} \end{cases}$ (indicator random variable)

How many times can z_i and z_j be compared? - At most once, since for a comparison to happen, one of the two must be the pivot, after which it is not included in recursive calls.

$$X = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} X_{ij}$$

i.e., the total number of comparisons (and a bound on the overall runtime) - O(n + X), where n is for the calls to PARTITION and X for each iteration in PARTITION.

Remember, we want to know what the expected (on average) running time:

$$E[X] = E[\sum_{i=1}^{n-1} \sum_{j=i+1}^{n} X_{ij}]$$

=
$$\sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E[X_{ij}]$$

=
$$\sum_{i=1}^{n-1} \sum_{j=i+1}^{n} p\{z_i \text{ is compared to } z_j\}$$

The pivot element separates the set of numbers into two sets (those less than the pivot and those larger). Elements from one set will *never* be compared to elements of the other set.

If a pivot x is chosen $z_i < x < z_j$, then z_i and z_j will not be compared.

Similarly, from the set Z_{ij} , the only time z_i and z_j will be compared is if either z_i or z_j is chosen as a pivot. Why?

$$p\{z_i \text{ is compared to } z_j\} = p\{z_i \text{ or } z_j \text{ is first pivot chosen from } Z_{ij}\}$$
$$= p\{z_i \text{ is first pivot chosen from } Z_{ij}\}$$
$$+ p\{z_j \text{ is first pivot chosen from } Z_{ij}\}$$
$$= \frac{1}{j-i+1} + \frac{1}{j-i+1}$$
$$= \frac{2}{j-i+1}$$

Line 2: Independent events (p(a, b) = p(a) + p(b) if a and b are independent events) Line 3: Because the pivot is chosen randomly and there are j-i+1 elements in the set Z_{ij}

Let
$$k = j - i$$
:

$$E[X] = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \frac{2}{j-i+1}$$
$$= \sum_{i=1}^{n-1} \sum_{k=1}^{n-i} \frac{2}{k+1}$$
$$< \sum_{i=1}^{n-1} \sum_{k=1}^{n} \frac{2}{k}$$
$$= \sum_{i=1}^{n-1} O(\log n)$$
$$= O(n \log n)$$

where line 4 occurs because $\sum_{k=1}^{n} 2/k = \ln n + O(1) = O(\log n)$

Can a run of RANDOMIZE-QUICKSORT take time $\Theta(n^2)$?

- Memory usage?
- Ease of implementation?
- How does randomized quicksort compare to mergesort?
- Comparison based sorting

Asks the question is $i \leq j$.

We've seen MERGE-SORT and randomized QUICKSORT which both run on average in time $\Theta(n \log n)$. Can we do better?

Decision tree model

Picture

- A binary tree where each node represents comparison between two elements, i and j
- The branches are labeled with the decision outcome

- Each leaf contains a permutation of the original data representing the sorted order.
- To determine the correct output for a given input, follow the path based on the decisions from the root to a leaf node

How many leaf nodes are there for a decision tree representing the sorting of n elements? - n!, all possible permutation of the original n elements.

Why can't there be less?

What is the height of the tree?

Binary tree of height h contains 2^h leaves so,

$$2^{h} = n!$$

$$\log 2^{h} = \log n!$$

$$h = \Omega(n \log n)$$

using Stirling's approximation,

 $n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n \left(1 + \Theta(\frac{1}{n})\right)$

- Other uses/sources of randomness in algorithms
 - Contention resolution
 - Algorithm initialization (e.g. clustering)
 - Game playing, i.e. inherent randomness in the interacation
- Sorting in linear time

Counting sort

Radix sort

These notes are adapted from material found in chapters 7,8 of [1].

References

[1] Thomas H. Cormen, Charles E. Leiserson Ronald L. Rivest and Clifford Stein. 2007. Introduction to Algorithms, 2nd ed. MIT Press.